Warning
The servicing instructions are for use by qualified personnel only. To avoid personal injury, do not perform any servicing unless you are qualified to do so. Refer to the Safety Summary prior to performing service.
**Instrument Serial Numbers**

Each instrument manufactured by Tektronix has a serial number on a panel insert or tag, or stamped on the chassis. The first letter in the serial number designates the country of manufacture. The last five digits of the serial number are assigned sequentially and are unique to each instrument. Those manufactured in the United States have six unique digits. The country of manufacture is identified as follows:

- **B010000**  Tektronix, Inc., Beaverton, Oregon, USA
- **E200000**  Tektronix United Kingdom, Ltd., London
- **J300000**  Sony/Tektronix, Japan
- **H700000**  Tektronix Holland, NV, Heerlen, The Netherlands

Instruments manufactured for Tektronix by external vendors outside the United States are assigned a two digit alpha code to identify the country of manufacture (e.g., JP for Japan, HK for Hong Kong, IL for Israel, etc.).

Tektronix, Inc., P.O. Box 500, Beaverton, OR 97077

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Safety Summary

This general safety information is directed to operators and service personnel. Specific warnings and cautions will be found throughout the manual where they apply, but may not appear in this summary.

Symbols and Terms

Several safety-related symbols and terms appear in the manuals and on the equipment.

Terms in Manuals

CAUTION statements in manuals identify conditions or practices that could result in damage to the equipment or other property.

WARNING statements in manuals identify conditions or practices that could result in personal injury or loss of life.

Terms on Equipment

CAUTION on equipment means a personal injury hazard not immediately accessible as one reads the marking, or a hazard to property including the equipment itself.

DANGER on equipment means a personal injury hazard immediately accessible as one reads the marking.

Symbols in Manuals

Static Sensitive Devices

Symbols on Equipment

DANGER
High Voltage

Protective
ground (earth)
terminal

ATTENTION
Refer to
manual
Safety Summary

Specific Precautions

Observe the following precautions to ensure your personal safety and to prevent damage to your CSA 803A or equipment connected to it.

Power Source

This product is intended to operate from a power source that will not apply more than 250 \( V_{RMS} \) between the supply conductors or between either supply conductor and ground. A protective ground connection, by way of the grounding conductor in the power cord, is essential for safe operation.

Grounding the Product

This product is grounded through the grounding conductor of the instrument power cord. To avoid electric shock, plug the power cord into a properly wired receptacle before connecting to the product input or output terminal. A protective-ground connection, by way of the grounding conductor in the power cord, is essential for safe operation.

Danger Arising from Loss of Ground

Upon loss of the protective-ground connection, all accessible conductive parts (including knobs and controls that may appear to be insulating) can render an electrical shock.

Do Not Operate in Explosive Atmospheres

To avoid explosion, do not operate this product in an atmosphere of explosive gasses.

Do Not Service Alone

Do not perform internal service or adjustment of this product unless another person capable of rendering first aid and resuscitation is present.

Use Care When Servicing with Power On

Dangerous voltages exist at several points in this product. To avoid personal injury, do not touch exposed connections and components while the power is on.

Disconnect the power before removing protective panels, soldering, or replacing components.
CRT Handling

Use care when handling a CRT. Breakage of the CRT causes a high-velocity scattering of glass fragments (implosion). Protective clothing and safety glasses should be worn. Avoid striking the CRT on any object that might cause it to crack or implode. When storing a CRT, place it in a protective carton or set it face down in a protected location on a smooth surface with a soft mat under the faceplate.

Use the Proper Fuse

To avoid fire hazard, use only a fuse which is identical in type, voltage rating, and current rating to the fuse specified in the Parts List section.
Specifications

This section provides specifications for testing and adjusting your CSA 803A. Refer to the CSA 803A User Manual for a general description of the characteristic, environmental, and user specifications of the CSA 803A. Table 1-1 lists measurement and specification values. Refer to the Performance Verification section for Performance test procedures; refer to the Adjustments section for Adjustment procedures.

Table 1-1: Measurement Limits, Specifications, Adjustments, and Functional Tests

<table>
<thead>
<tr>
<th>Part and Description</th>
<th>Measurement Limits (Examine)</th>
<th>Specifications (Check)</th>
<th>Adjustments (Adjust)</th>
<th>Functional Tests</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power-On Diagnostics</td>
<td>none</td>
<td>none</td>
<td>none</td>
<td>yes</td>
</tr>
<tr>
<td>Sampling Head</td>
<td>none</td>
<td>none</td>
<td>none</td>
<td>yes</td>
</tr>
<tr>
<td>Extended Diagnostics</td>
<td>none</td>
<td>none</td>
<td>none</td>
<td>yes</td>
</tr>
<tr>
<td>Power Supply</td>
<td></td>
<td></td>
<td></td>
<td>no</td>
</tr>
<tr>
<td>Voltage Supply</td>
<td>+4.85 V to +5.25 V</td>
<td>none</td>
<td>none</td>
<td></td>
</tr>
<tr>
<td>Voltage Reference</td>
<td>+5.15 V to +5.25 V</td>
<td>none</td>
<td>R800 +5.2 V Ref for +5.20 V</td>
<td></td>
</tr>
<tr>
<td>Regulator Reference</td>
<td>+9.95 V to +10.05 V</td>
<td>none</td>
<td>R730 +10 V Ref for +10.00 V</td>
<td></td>
</tr>
<tr>
<td>Display</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Cutoff</td>
<td>visible</td>
<td>none</td>
<td>SCREEN, on transformer on A8 CRT Driver board, until display appears</td>
<td></td>
</tr>
<tr>
<td>Convergence</td>
<td>primary colors are not separated in the white grid</td>
<td>none</td>
<td>CONVERGENCE, R210, for optimum convergence of red, green, and blue</td>
<td></td>
</tr>
<tr>
<td>Focus</td>
<td>focused grid pattern</td>
<td>none</td>
<td>FOCUS, on transformer on A8 CRT Driver board, for optimum focus on white grid pattern</td>
<td></td>
</tr>
</tbody>
</table>

CSA 803A Service Manual 1-1
### Specifications

<table>
<thead>
<tr>
<th>Part and Description</th>
<th>Measurement Limits (Examine)</th>
<th>Specifications (Check)</th>
<th>Adjustments (Adjust)</th>
<th>Functional Tests</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Display (Cont.)</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Vertical Size and Position</td>
<td>align with tic marks</td>
<td>none</td>
<td>VERT SIZE, L321;</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>and VERT POS, R311;</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>for optimum</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>alignment</td>
<td></td>
</tr>
<tr>
<td>Horizontal Size, Linearity and Position</td>
<td>align with tic marks and for optimum appearance</td>
<td>none</td>
<td>H-SIZE, R501; H-LIN, R502; and H-POS, R500, for optimum alignment and linearity</td>
<td>no</td>
</tr>
<tr>
<td>Gray Scale</td>
<td>white at the top of the display and gray at the bottom, and the right side of the display is cut off</td>
<td>none</td>
<td>SCREEN, on transformer on A8 CRT Driver board; RED, R200; GREEN, R201; and BLUE, R203; for cutoff and color balance</td>
<td>no</td>
</tr>
<tr>
<td>Color Impurity</td>
<td>no severe color impurities in red, green, and blue display</td>
<td>none</td>
<td>cycle power on and off</td>
<td>no</td>
</tr>
<tr>
<td>Real Time Clock</td>
<td>1,000,000 µs ±5 µs</td>
<td>none</td>
<td>Real Time Clock for 1,000,000 µs</td>
<td>no</td>
</tr>
<tr>
<td>Vertical Reference Voltage</td>
<td>none</td>
<td>+5 V ±200 µV and -5 V ±200 µV</td>
<td>none</td>
<td>no</td>
</tr>
<tr>
<td>Horizontal Reference Clock</td>
<td>none</td>
<td>200,000 kHz ±5 kHz</td>
<td>none</td>
<td>no</td>
</tr>
<tr>
<td>Vertical Accuracy</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Vertical Gain</td>
<td>none</td>
<td>±1.0% full scale</td>
<td>none</td>
<td>yes</td>
</tr>
<tr>
<td>Offset Accuracy</td>
<td>none</td>
<td>±2 mV</td>
<td>none</td>
<td>yes</td>
</tr>
<tr>
<td>Vertical Linearity</td>
<td>none</td>
<td>±1%</td>
<td>none</td>
<td>no</td>
</tr>
<tr>
<td>System Vertical RMS Noise</td>
<td>200 µV at 2 mV/div 500 µV at 5 mV/div 1 mV at 10 mV/div 632 µV at 20 mV/div 1.58 mV at 500 mV/div 3.16 mV at 100 mV/div 6.32 mV at 200 mV/div</td>
<td>none</td>
<td>none</td>
<td>yes</td>
</tr>
</tbody>
</table>
Table 1-1: Measurement Limits, Specifications, Adjustments, and Functional Tests (Cont.)

<table>
<thead>
<tr>
<th>Part and Description</th>
<th>Measurement Limits (Examine)</th>
<th>Specifications (Check)</th>
<th>Adjustments (Adjust)</th>
<th>Functional Tests</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sweep Rate Accuracy</td>
<td>0.05% at 2 ns/div</td>
<td>none</td>
<td>none</td>
<td>yes</td>
</tr>
<tr>
<td></td>
<td>0.08% at 1 ns/div</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>0.8% at 100 ps/div</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>2.5% at 10 ps/div</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>10% at 1 ps/div</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Triggering, External Direct</td>
<td>yes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>300 MHz Sensitivity</td>
<td>100 mV_{R-P} at 300 MHz</td>
<td>100 mV stable display</td>
<td>none</td>
<td></td>
</tr>
<tr>
<td>1000 MHz Sensitivity</td>
<td>100 mV_{R-P} at 1000 MHz</td>
<td>100 mV stable display</td>
<td>none</td>
<td></td>
</tr>
<tr>
<td>3.0 GHz Sensitivity</td>
<td>100 mV_{R-P} at 3.0 GHz</td>
<td>100 mV stable display</td>
<td>none</td>
<td></td>
</tr>
<tr>
<td>Prescaler Triggering</td>
<td>600 mV_{R-P} at 2 GHz</td>
<td>600 mV stable display</td>
<td>none</td>
<td>yes</td>
</tr>
<tr>
<td></td>
<td>600 mV_{R-P} at 8 GHz</td>
<td>600 mV stable display</td>
<td>none</td>
<td></td>
</tr>
<tr>
<td></td>
<td>2 V_{R-P} at 10 GHz</td>
<td>2 V stable display</td>
<td>none</td>
<td></td>
</tr>
<tr>
<td>Internal Clock</td>
<td>yes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Rise Time</td>
<td>≤2.5 ns</td>
<td>≤2.5 ns</td>
<td>none</td>
<td></td>
</tr>
<tr>
<td>Frequency</td>
<td>100 kHz ±3%</td>
<td>100 kHz ±3%</td>
<td>none</td>
<td></td>
</tr>
<tr>
<td>Duty Cycle</td>
<td>50% ±3%</td>
<td>50% ±3%</td>
<td>none</td>
<td></td>
</tr>
<tr>
<td>Calibrator Output</td>
<td>yes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Rise Time</td>
<td>≤250 ps (20% – 80%)</td>
<td>≤250 ps (20% – 80%)</td>
<td>none</td>
<td></td>
</tr>
<tr>
<td>Peak-to-peak Amplitude</td>
<td>250 mV ±10%</td>
<td>250 mV ±10%</td>
<td>none</td>
<td></td>
</tr>
</tbody>
</table>
Operating Information

The CSA 803A Communications Signal Analyzer Service Manual is designed for use by qualified service personnel. It contains information necessary to check, troubleshoot, and maintain the CSA 803A Communications Signal Analyzer.

Troubleshooting is primarily based upon internal power-on diagnostics. These diagnostics isolate problems to the field replaceable unit (FRU) level. Defective FRUs not detected by diagnostics are isolated using other means. Once the faulty FRU is identified, use the instructions provided in this manual to remove and replace it. The removal and immediate replacement of the faulty FRU allows a minimum of downtime for the user. The Parts List section gives a complete list of the FRUs in this instrument.

First-time users are encouraged to read the CSA 803A Communications Signal Analyzer User Manual. This will help you learn the basic functions of the CSA 803A.

This section contains information about installing and removing a sampling head, applying power, proper environmental conditions, and shipping the instrument.
Sampling Head Installation and Removal

To avoid damage to the CSA 803A, set the ON/STANDBY switch to STANDBY before installing or removing sampling heads.

**CAUTION**

*Applying a voltage outside the range printed on the sampling head can result in damage. Static electricity is also a hazard.*

The input diodes used in the sampling heads are very susceptible to damage from overdrive signals or DC voltages and from electrostatic discharge. Never apply a voltage outside the range printed on the front of the sampling head. Operate the CSA 803A only in a static-controlled environment.

Connect the wrist strap provided with the CSA 803A to the **ANTISTATIC CONNECTION**, as shown in Figure 2-1. Refer to the CSA 803A Communications Signal Analyzer User Manual for more information.

The SD-Series sampling head slides into one of the front panel compartments of the CSA 803A Communications Signal Analyzer. Figure 2-1 shows the front panel of the CSA 803A Communications Signal Analyzer and the locations of the sampling head compartments.

![Figure 2-1: Sampling Head Compartments in the CSA 803A Communications Signal Analyzer](image)
With the ON/STANDBY switch set to STANDBY, place the sampling head in a compartment and slowly push it in with firm pressure. Once the sampling head is seated, turn the lock-down screw to tighten the sampling head in place.

**CAUTION**

*Never install or remove a sampling head when the ON/STANDBY switch is ON.*

To remove the sampling head, set the ON/STANDBY switch to STANDBY. Turn the lock-down screw to loosen the sampling head, and then slowly pull out the sampling head.
Power Information

The rear panel LINE VOLTAGE SELECTOR allows you to select either a 115 V or 230 V (48 Hz to 440 Hz) nominal supply source. The 6 A, 250 V line fuse is used for both 115 V and 230 V operation.

**WARNING**

**GROUNDING.** For electric shock protection, make the grounding connection before making any connection to the instrument’s input or output terminals. This instrument is safety Class 1 equipment (IEC designation). All accessible conductive parts are directly connected through the grounding conductor of the power cord to the grounded (earth) contact of the power plug.

Any interruption of the grounding connection can create an electrical shock hazard. The power input plug must be inserted only in a mating receptacle with a grounding contact where earth ground has been verified by a qualified service person. Do not defeat the grounding connection.

**WARNING**

**AC POWER SOURCE AND CONNECTION.** An improper voltage supply can damage the instrument. The instrument operates from a single-phase power source. It has a three-wire power cord and two-pole, three-terminal grounding type plug. The voltage to ground (earth) from either pole of the power source must not exceed the maximum rated operating voltage, 250 V.

Before making connection to the power source, check that the LINE VOLTAGE SELECTOR is set to match the voltage of the power source and has a suitable two-pole, three-terminal grounding-type plug.
Power Cord Information

A power cord with appropriate plug configuration is supplied with each instrument. Table 2-1, Power-Cord Conductor Identification, gives the color-coding of the conductors in the power cord. If you require a power cord other than the one supplied, refer to Figure 2-2, Power-Cord Plug Identification.

Table 2-1: Power-Cord Conductor Identification

<table>
<thead>
<tr>
<th>Conductor</th>
<th>Color</th>
<th>Alternate Color</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ungrounded (Line)</td>
<td>Brown</td>
<td>Black</td>
</tr>
<tr>
<td>Grounded (Neutral)</td>
<td>Light Blue</td>
<td>White</td>
</tr>
<tr>
<td>Grounded (Earth)</td>
<td>Green/Yellow</td>
<td>Green</td>
</tr>
</tbody>
</table>

![Image of power cords]

Standard* North American 115V
Option A1 Universal Euro 230V
Option A2 UK 230V
Option A3 Australian 230V
Option A4* North American 230V
Option A5 Switzerland 230V
Option 1A* North American 115V/High Power
Option 1B North American 3-Phase

* Canadian Standards Association certification includes these power plugs for use in the North American power network

Figure 2-2: Power-Cord Plug Identification
Memory Backup Power

There are four batteries within the instrument that allow the retention of volatile memory upon loss of the AC power source. These self-contained power sources provide memory backup power to retain the following:

- front-panel settings
- stored settings
- stored waveforms
- **Time & Date** parameters
- some of the Time Base Cal Constants (these are regenerated automatically if lost)
- the number of hours of instrument on-time, number of power-on sequences, and instrument serial number

The batteries have a nominal shelf life of approximately five years.

---

Operating Environment

The following environmental requirements are provided so that you can ensure proper functioning and extend the operation of the instrument.

**Operating Temperature**

The instrument can be operated where the ambient air temperature is between 0°C and +50°C and can be stored in ambient temperatures from −40°C to +75°C. After storage at temperatures outside the operating limits, allow the chassis to reach the safe operating temperature before applying power.

**Ventilation Requirements**

The fan draws air through the side panels of the instrument and blows air out through the rear to cool the instrument. To ensure that this cooling process occurs properly, allow at least two inches clearance on both sides and the rear of the instrument. The top and bottom of the instrument do not require ventilation clearance.

---

**CAUTION**

*If air flow is restricted, then the instrument’s power supply may temporarily shut down.*
Packaging for Shipment

If the instrument is to be shipped for long distances by commercial transportation, it should be packaged in the original manner. The carton and packaging material in which your instrument was shipped should be saved and used for this purpose.

Also, if the instrument is to be shipped to a Tektronix service center for service or repair, attach a tag to the instrument showing the following:

- owner of the instrument (with address)
- name of person to contact at your firm
- complete instrument type and serial number
- if possible, furnish complete system firmware versions as displayed in the Instrument Options pop-up menu selected from the UTILITY major menu
- a description of the service required

If the original packaging is unfit for use or not available, package the instrument as follows:

☐ Step 1: Obtain a corrugated cardboard shipping carton with a 375-pound test strength and having inside dimensions at least six inches greater than the instrument dimensions. This allows for cushioning.

☐ Step 2: Wrap the instrument with polyethylene sheeting or equivalent material to protect the finish.

☐ Step 3: Cushion the instrument on all sides by tightly packing dunnage or urethane foam between the carton and the instrument, allowing three inches on each side.

☐ Step 4: Seal the carton with shipping tape or with an industrial stapler.

☐ Step 5: Mark the address of your local Tektronix service center and your return address on the carton in one or more prominent locations.
Theory of Operation

The Tektronix CSA 803A is a high-resolution Communications Signal Analyzer accommodating up to four input channels through the dual-channel sampling heads. With the SD-24 TDR/Sampling Head, four channels of single-ended TDR or two channels of differential TDR are available as well. Features include:

- sweep rates ranging from 5 ms/division to 1 ps/div
- autoset to provide a suitably adjusted display for viewing and further manual adjustment
- windows for viewing expanded sections of a trace
- self-tests to assure continuous accuracy of waveform data and measurements
- digital waveform storage and display
- on-board measurement capabilities
- menu-driven touch-screen operation
- RS-232-C, GPIB, and PRINTER interfaces

This section has two main sub sections:

- **System Functional Overview** describes the major functional blocks of the CSA 803A and presents a typical waveform processing cycle

- **Block Diagram Descriptions** discusses the individual boards in the CSA 803A
Theory of Operation
System Functional Overview

This section describes the major functional blocks of the CSA 803A (see Figure 9-1).

---

**Acquisition System Block**

The CSA 803A contains an Acquisition system, which supports two dual-channel sampling heads and contains two data acquisition and measurement channels. Additionally, two power-only slots are provided.

Since the Acquisition system supports four input channels (two dual-channel heads) and contains only two measurement channels, the four input channels are multiplexed into the two measurement channels through an analog multiplexer. Either one of the sampling head input channels can be independently connected to either of these two measurement channels.

Several calibration signals are also supplied to each multiplexer, although these signals are used only for self-tests and diagnostics.

---

**Strobe Distribution Block**

The Strobe Distribution block acts as an interface between the Time Base/Controller and the Acquisition systems.

The Time Base/Controller generates a strobe pulse that is regenerated by the Strobe Distribution block to drive all the sampling heads in parallel.

---

**Time Base/Controller Block**

The Time Base/Controller block is comprised of the following circuits:

- a microprocessor with local RAM and ROM
- the time base and trigger circuits
- interfaces to the memory management unit (MMU) and Acquisition systems

---

**Trigger Select Block**

The Trigger Select block selects the desired trigger signal to be sent to the Time Base/Controller block.
Executive Processor Block

After the user requests an operation (with a front panel control for instance), the Executive Processor (EXP) directs the CSA 803A to perform this operation. Another primary function of the EXP is to execute diagnostic Self-Tests on the instrument when powering-on or at the user’s request. To control operations, the EXP controls and monitors the other circuit boards sharing the executive system bus. Through the executive bus boards, the EXP also indirectly controls all other instrument boards. The EXP generates commands and status signals to control on-board devices and I/O devices, such as GPIB and RS-232-C interfaces, that help process data and help control the rest of the instrument.

Memory Management Unit Block

The memory management unit (MMU) arbitrates requests for access to the Waveform Memory from the following three sources:

- the EXP
- the Time Base/Controller
- the display system

This arbitration allows all three systems transparent access to the Waveform Memory.

Waveform Memory Block

Waveform Memory is shared among the following processors:

- the EXP
- the Display
- the Time Base/Controller

While the main function of the Waveform Memory is the storage of waveform data and waveform related information, the shared memory is also used to pass messages between the Executive, Display, and Time Base/Controller processors. Eventually, all acquired waveforms are transferred from the Acquisition system memory to the Waveform Memory for display.
User control of the CSA 803A is primarily through the following three front panel controls:

- the front-panel major-menu buttons
- the touch panel
- the multifunction knobs

The major menu buttons are the top level menu selections for the instrument. Touching an icon, menu item, or waveform selects that particular icon, menu item, or waveform, respectively. The multifunction knobs control the function of the particular item that is selected.

The I/O block provides a GPIB port, RS-232-C port, and a PRINTER port for interfacing various I/O devices to the instrument.

The display subsystem provides all visual output to the user. This includes not only data output such as waveform traces, graticules, axes, and annotation, but displays supporting the human interface as well (which includes menus, labeling for touch panel input, and an interactive output to assist in operating the system; that is, the current mode-setting information).

The CSA 803A uses a custom vertical raster-scan display that provides excellent resolution for both waveform display and text. The display system produces the display by the following:

1. transferring waveform data from the Waveform Memory
2. compressing it into 512 horizontal pixels
3. converting it to a format compatible with the vertical raster-scan display

The Waveform Compressor takes waveforms with more than 512 data points and compresses these points into 512 groups. For example, for a 1024-point waveform, each group would contain two points; for 2048-point waveforms, each group would contain four points. The Waveform Compressor finds the largest and smallest vertical value in a group of points and then draws a vector between the maximum and minimum — even in “dots” mode. The only difference between dots and vectors is that in vector mode the vectors are extended vertically to meet the vector on the next scan line.
Power Supply

The CSA 803A operates from either a 115 V or 230 V nominal line voltage source at a line frequency between 48 Hz and 440 Hz. The LINE VOLTAGE SELECTOR switch allows selection of AC line inputs of 90 $V_{RMS}$ to 132 $V_{RMS}$ or 180 $V_{RMS}$ to 250 $V_{RMS}$.

Apply power to the instrument as follows:

1. Turn the rear panel PRINCIPAL POWER switch to ON
2. Turn the front panel ON/STANDBY switch to ON

A small green indicator lamp should light indicating the power is on.

Typical Waveform Processing Cycle

The following is a brief overview of how the CSA 803A acquires, processes, and displays a waveform from the input channels:

1. Analog input signals are connected to the sampling head inputs.
2. The Time Base/Controller block produces precisely timed strobe signals based on the trigger signal.
3. These strobe signals are distributed to the sampling head channels and instruct the sampling heads when to take samples of the input signal.
4. The Acquisition systems take the output of the sampling heads, amplify or attenuate the signals, and apply any offset based on the vertical size and position controls.
5. The output of the amplifiers are applied to analog-to-digital (A/D) converters, which convert the sampled voltages to digital codes and then store these codes in the acquisition system memory.
6. Once all the samples in a waveform have been acquired, the Time Base/Controller then transfers these samples from the Acquisition system memory to the Waveform Memory, through the waveform data direct memory access (DMA).
7. The EXP processes information from the human interfaces (that is, the menus, icons, buttons, and knobs that you interact with to control the oscilloscope).
8. The EXP sends commands to the display system so that the function that you selected is displayed.
9. When instructed by the EXP, the display system receives the waveform data from waveform memory and converts it to a unique vertical raster-scan format for a display based on your settings.
Block Diagram Descriptions

This section describes the CSA 803A detailed block diagram (see Figure 9-2) and the board-level block diagrams (see the Diagrams section).

A1 M/F Strobe Drive Board

The A1 M/F Strobe Drive board consists of the following circuits:

- Data buffers circuitry
- Address latch circuitry
- Function decoder circuitry
- Internal clock rate generator circuitry
- Control buffers circuitry

See Figure 9-3 for a block diagram of this board.

Data Buffers

This circuit buffers the A5 Time Base/Controller board’s address and data buses with bidirectional buffers, and the A5 Time Base/Controller board’s control lines with octal buffers.

Address Latch

This circuit buffers and latches the address for the A5 Time Base/Controller board to use.

Function Decoder

This circuit partially decodes this latched address and enables the data buffers if the address is on this board or the A27 & A28 Acquisition system boards (controlled through this board). The function decoder also selects the appropriate direction of the data buffers to perform a read or write operation.

Internal Clock Rate Generator

This circuit is a 16-bit programmable counter that is tied to the ÷ 2 flip-flop that produces the square wave output. The overall division ratio of this block can be programmed from $2^5$ to $2^{17}$. The internal clock rate generator is programmed at power-on to provide a 100 kHz output given a 4 MHz input on jumper J35.
**Control Buffer**

This circuit buffers the control signals sent to the A1 M/F Strobe Drive board from the A5 Time Base/Controller board.

---

**A3 M/F Power Connect Board**

The A3 M/F Power Connector board consists of built-in connectors that distribute the power supply voltages from the A4 Regulator board to the following boards:

- A1 M/F Strobe Drive board
- A5 Time Base/Controller board
- A26 M/F Acquisition Interconnect board

The A3 M/F Power Connect board also supplies ±15 V power to the A14 Input/Output (I/O) board through a 16-pin ribbon cable.

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**A4 Regulator Board**

The regulators convert semi-regulated voltages into stabilized low-ripple output voltages. The A4 Regulator board consists of the following regulators and the voltage-fault detect circuitry:

- +50 V
- −15 V
- +5 V
- +15 V
- −50 V

See Figure 9-4 for a block diagram of this board.

The operational amplifiers used for the +50 V, +15 V, +5 V, −50 V, −15 V and −5 V regulators require that the following special voltages be generated for their operation:

- Semi-regulated +54 V supply generates the +20 V supply
- Semi-regulated −54 V supply generates the −20 V supply
- Semi-regulated +54 V supply generates the +10 V supply
- Semi-regulated −54 V supply generates the −10 V supply
- +10.0 V REF is used as a reference voltage

**Voltage-Fault Detect**

This circuit consists of two window comparators and associated resistors. The circuitry detects if any regulated supply is over-voltage or under-voltage. The associated resistors set a hysteresis window that is 5% of the regulator sense line voltages.
A5 Time Base/Controller Board

The A5 Time Base Controller board consists of the following circuitry:

- Microprocessor (MPU)
- RAM/ROM
- Trigger circuitry
- Time Base circuitry
- Acquisition system interface
- Memory management unit (MMU) interface

See Figure 9-5 for the block diagram of this board.

Microprocessor

The microprocessor controls the time base and trigger circuitry in response to commands from the Executive Processor, performs local on-line calibration of the time base, schedules waveform acquisitions, and manages the Acquisition system and waveform data transfers.

RAM/ROM Memory

Both RAM and ROM memory reside within the microprocessor’s 1 Mbyte of address space. The upper 256 Kbytes is reserved as ROM, the lower 128 Kbytes of static RAM is provided for dynamic data storage and local non-volatile memory. There are 32 Kbytes of memory-provided communication and waveform storage for the CSA 803A’s 8 channels, and another 32 Kbytes for the Strobe Distribution block of the oscilloscope and multiplexers. There are 512 Kbytes of memory assigned as communication and primary waveform storage. Another 32 Kbytes are used to map the communication buffer of the parallel interface with the memory management unit, and the remaining 32 Kbytes are divided into I/O space and time base control.

Trigger

This circuitry is comprised of the trigger recognizer and gated voltage control oscillator. The trigger circuits accept trigger signals from either the Direct or Prescaler Inputs. The strobe sense signal and internal feedback signals are used in the Self-Tests diagnostic process but are not normally used for data acquisition.

The trigger recognizer sees a valid direct or prescale trigger signal and outputs this signal to the voltage controlled oscillator that sets the timing for the strobe signal.

The direct trigger input allows programmed slope and level selection, but the prescale trigger input is not adjustable.
If auto trigger mode is selected, the timebase will generate its own trigger signal after 20 ms. If normal trigger mode is selected, the CSA 803A will wait for trigger signals.

The High Frequency On/Off Control selects the state of the trigger hysteresis in the direct trigger path.

High Frequency On removes trigger hysteresis and improves sensitivity when the trigger signal edge slew rate is 1 V/ns or greater, typically a 320 mV_{pp}, 1 GHz sine wave. See Figure 3-1.

High Frequency Off retains trigger hysteresis while improving noise rejection at low frequencies, when the trigger edge slew rate is less than 1 V/ns. It can be used at any frequency if the trigger signal amplitude reliably triggers the CSA 803A. See Figure 3-1. This is the default setting after initialization.

![Figure 3-1: Trigger Edge Slew Rate for High Frequency Selection](image)

The Enhanced Triggering ON/Off Control selects the state of the metastable trigger rejection feature in the direct trigger path.

Enhanced Triggering On directs the timebase to detect metastable trigger events and reject the acquired data. The data is reacquired at the next trigger event.

Enhanced Triggering Off allows the timebase to acquire and display metastable trigger events.

The Trigger Holdoff Control in the trigger menu programs the trigger holdoff value.

Auto Holdoff is the default mode. This mode automatically programs Actual Holdoff to the minimum possible value. It depends only on the time base settings and is updated when the Main Size and Main Position values
change. Triggering is held off to beyond the rightmost point in the Main record. The minimum value is 5 µs. The Actual Holdoff (auto mode) calculation is:

$$\text{Actual Holdoff (auto mode)} = \max (5 \text{ } \mu\text{s}, 5 \text{ } \mu\text{s} + \text{Main Pos} + \text{Duration})$$

where \( \text{Duration} = \text{Main Size} \times 10 \text{ divisions} \).

Manual Holdoff extends the trigger holdoff to longer periods, up to 2.5 seconds. The Actual Holdoff value depends on the value of Requested Holdoff in addition to the time base settings. The Actual Holdoff (manual mode) calculation is:

$$\text{Actual Holdoff (manual mode)} = \max (5 \text{ } \mu\text{s}, 5 \text{ } \mu\text{s} + \text{Main Pos} + \text{Duration, Requested Holdoff})$$

**Time Base**

This circuit is a very precise slewing delay generator. It accepts triggers from the reference oscillator, generates a precise delay, and outputs a strobe-drive pulse.

The time base circuitry consists of a TECL integrated circuit (IC), which contains three six-bit high-speed counters, and a CMOS IC, which contains a 48-bit programmable strobe delay generator.

On the first sample of the waveform, the sample is taken immediately after a starting delay. Subsequent samples are delayed by a small additional amount, called the dot delay. The dot delay is programmed and stored into the strobe delay register. Each sample is delayed by one delay more than the previous sample. The dot delay can vary from 10 fs to 20 ns depending on the horizontal size and the number of points in the waveform record.

The sampling interval (incremental delay between samples) is the total acquisition time (time/division \( \times \) 10 divisions) divided by the number of points acquired.

**Acquisition System Interface**

This circuit contains 16 Kbytes of RAM (physically located on the A28 Acquisition MPU board) that is shared between the Acquisition system and the Time Base/Controller. This RAM is mapped into the microprocessor memory space so that it can be accessed as any other RAM — either by the microprocessor itself or the DMA controller.

This shared memory allows the microprocessor to transfer waveforms from the Acquisition system to the Waveform Memory using DMA. It also provides a mailbox structure for commands and data passed between the two systems.
Memory Management Unit (MMU) Interface

This circuit interfaces the Time Base/Controller to the EXP and the Waveform Memory. This interface allows the EXP to send commands to the microprocessor through the Time Base/Controller and provides the path for waveform transfers from the Acquisition system to the Waveform Memory.

A7 CRT Socket Board

The A7 CRT Socket board is an interface from the A15 MMU board to the CRT. The A7 CRT Socket board consists of the following circuits:

- Red, Green, and Blue video amplifiers
- RED, GREEN, and BLUE cutoff adjustments
- CONVERGENCE adjustment

See Figure 9-6 for a block diagram of this board.

Red, Green, and Blue Video Amplifiers

These three circuits are identical high speed video amplifiers that drive the three cathodes (R, G, and B; red, green, and blue, respectively) of the CRT. Each of the three colors can be programmed to display 64 different levels. This yields a possible 262,144 colors, of which eight can be displayed on the screen at any time.

Red, Green, and Blue Adjustments

These three potentiometers control the cutoff point; that is, the point at which a certain color becomes invisible.

Convergence Adjustment

This potentiometer controls the vertical convergence of the red, green, and blue deflection beams.
A8 CRT Driver Board

The A8 CRT Driver board consists of the following circuits:

- Horizontal sweep circuitry
- Vertical sweep circuitry
- High voltage and grid voltage generator circuitry
- Degauss circuit
- Beam current limit circuit
- Grid bias circuit

The A8 CRT Driver board circuitry drives the raster scan CRT. The VIDEO and SYNC signals from the A15 MMU board generate the Z-axis signal, sweep signals, and grid bias voltages for the CRT.

See Figure 9-7 for a block diagram of this board.

Horizontal Sweep

This circuit generates the sweep current for the horizontal deflection yoke. The horizontal driver includes an oscillator, a voltage ramp generator, a high-gain amplifier, and a flyback generator. These components provide sweep synchronization, horizontal deflection, and linearity.

The horizontal adjustments, H-SIZE, H-POS, and H-LIN, allow you to optimize the appearance of the display.

Vertical Sweep

This circuit produces a deflection current that sweeps the video beam from the bottom to the top of the CRT. This circuit also produces a flyback signal to the flyback transformer that is in parallel with the deflection yoke.

The vertical adjustments, VERT SIZE and VERT POS, set the vertical size and position of the display.

High Voltage and Grid Voltage Generator

This circuit includes the flyback transformer that generates the 16 kV CRT anode potential and other bias voltages. This transformer is coupled and synchronized with the vertical deflection system.

The SCREEN adjustment provides the cutoff point; that is, the point where no information is visible on the display screen. The FOCUS adjustment provides manual focusing of the display image.
Degauss

This circuit removes magnetic fields from the color steel aperture grille. These magnetic fields are induced at each power-on by magnetic sources.

The Degauss circuit produces an exponentially decaying sine wave with a frequency of approximately 3.7 kHz. This waveform is applied to the degauss coils that are located on both sides of the CRT. The decayed oscillation through the coils causes a magnetic field to be induced in the CRT steel aperture grille. This magnetic field saturates the steel and then forces the stored magnetic field down to zero as the steel is driven around its hysteresis curve.

Beam Current Limit

This circuit limits the average power to the CRT to less than 15 W. An amplifier circuit compares the sum of the anode current and the FOCUS adjustment current to a reference current of 0.72 mA. If the sum of the two currents exceeds the reference current, then the three video amplifiers on the A7 CRT Socket board are disabled.

Grid Bias

This circuit provides −40 V of grid bias to the A7 CRT Socket board. At power-off, the grid is supplied with −90 V until the focus circuit discharges a high voltage. This prevents a bright spot from appearing at the center of the screen at power-off.

A9, A10, and A11 Front Panel Boards

The A9, A10, and A11 Front-Panel Circuit boards specifically consist of the following boards:

- A9 Touch Panel assembly
- A10 Front Panel Control board
- A11 Front Panel Button board

Touch Panel, Major Menu Keys, and Menu Status LEDs

These three functions interface to the Executive processor through a general purpose programmable keyboard and display controller IC on the A10 Front Panel Controller board.

The keyboard function of the IC handles the touch matrix and hard keys. The display function drives the menu LED light bars.

A9 Touch Panel Assembly

This circuit is comprised of infrared LEDs that produce a matrix of light beams that are interrupted when the user touches a particular touch zone. The touch panel and hard key matrix are scanned continuously until a
shadow or keypress is detected. When a hit is detected, that scan is completed and the interrupt line is asserted by the display controller. During this time, the interrupt is active and no new data is written into the sensor RAM from the touch panel or hard keys, even though the hardware continues to scan; therefore, the data will not change in the sensor RAM while the microprocessor is reading it.

Only one infrared LED is turned on at a time and only the phototransistor directly opposite is selected to receive light. This prevents any crosstalk between emitter/detector pairs.

**A10 Front Panel Control Board**

This circuitry generates the 6-bit address bus that is used to select an infrared LED and its compliment phototransistor on the A9 Touch Panel board.

**A11 Front Panel Button Board**

This circuitry is comprised of the major menu LED light bars that are driven by the display refresh register output of the A7 Display Controller board. Internally, there is a matrix of display RAM organized in an 8-bit by 8-bit matrix. This display RAM is scanned column by column (automatically), lighting the appropriate LED bar(s) when a high bit is encountered. The coarse/fine LEDs are driven by a latch that is controlled by the EXP. The coarse/fine selections are sensed on the A9 Touch Panel board.
A12 Rear Panel Assembly

The A12 Rear Panel assembly links the oscilloscope to other devices. This assembly contains connectors for the following ports:

- One GPIB Port
- One RS-232-C Port
- One Printer Port (Centronics style)

The A12 Rear Panel assembly is controlled from the A14 Input/Output (I/O) board through a 40-wire cable. This cable contains the following signals:

- Eight-bit bidirectional data bus
- Four-bit address bus
- Four interrupt lines
- GPIB DMA request and grant lines
- Four device control lines
- Assorted power supply and ground lines

See Figure 9-8 for a block diagram of this assembly.

GPIB Data and Address Bus

This bus drives the GPIB controller directly. Control signals DBIN and WR are used by the GPIB controller to determine if the microprocessor is trying to read from it or write to it. The interrupt controllers in the A17 Executive Processor board monitor this interrupt line and will signal the microprocessor to service the GPIB controller. In order to communicate with the microprocessor, the GPIB controller requires that at least one of the following conditions occurs:

- the receiver section of the GPIB controller has a byte of data (Inbyte Register) from the GPIB bus that the microprocessor needs to read
- the transmitter section register (Outbyte Register) is empty and is ready to receive another byte of data
- the status of the GPIB bus or the GPIB controller has changed and the microprocessor has to be notified

On the opposite side of the GPIB controller is another bus system. This other bus system includes an 8-bit data bus which accesses a bidirectional GPIB data buffer and an eight-bit control bus which accesses a GPIB control driver. The GPIB bus is connected to the opposite side of the buffer and control driver. These two devices are specially designed to be TTL signal-level compatible on the bus side of the buffer driver.

The states of three control signals from the GPIB controller, SRQ, NRFD, and NDAC, are monitored and displayed on the rear panel of the CSA 803A. These LEDs show the state that the GPIB controller is in, not the state of the GPIB bus.
Two other signals of interest are GPIB RQ and GPIB GR. These signals are used by the DMA Controller on the A17 Executive Processor board to communicate with the GPIB controller. The DMA can be programmed by the microprocessor to service either the Inbyte register or the Outbyte register.

**Standard RS-232-C Controller**

This communications controller is connected to the same data bus and address bus as the GPIB controller. The RPD7-RPD0 address lines transfer data to and from the microprocessor. The RPA1-RPA4 address lines are used by the microprocessor to select individual registers in the GPIB controller. The STD RS SEL line goes low when the microprocessor wants to communicate with the RS-232-C controller. (This line also drives the Chip Enable.)

The RD and WR signals are driven by the microprocessor to signal if the GPIB controller is to be read from or written into. The controller sets the STD RS INTR (interrupt) line low to request service from the microprocessor. The microprocessor writes a byte into the controller's transmit buffer to transmit data on the RS-232-C bus. The microprocessor reads a byte from the receiver buffer to receive data from the RS-232-C bus. The microprocessor can also read the status of the controller. The RS-232-C controller translates the parallel data from the microprocessor to serial data from RXD on the RS-232-C bus to parallel data for the microprocessor.

There are transmit and receive buffers that are compatible with the RS-232-C bus. Clear To Send (CTS) and Data Set Ready (DSR) are RS-232-C control signals that can be controlled by the microprocessor. Request To Send (RTS) and Data Terminal Ready (DTR) are signals that can be read by the microprocessor. The received signal detect (RDS) control signal is always high when power is on. This RS-232-C port is a DCE type.

**Printer Port**

The Centronics-style printer port, J111, is controlled by a programmable peripheral interface IC. This IC has all the control lines necessary to connect to a microprocessor, plus two general purpose eight-bit ports and the control signals to use them. The A12 Rear Panel Assembly Data bus and Address bus connect to the IC and have the same function as described for the GPIB and RS-232-C controllers. The Printer Sel line is set low by the microprocessor when it is communicating with the interface. The RD and WR lines allow the microprocessor to either read or write to the registers in the programmable peripheral interface IC. This IC must be initialized by the microprocessor for Port A to be a strobed input port. Port C provides the control signals.
A13 Mother Board

The A13 Mother board provides the interconnection for the microprocessor signals and the +5 V power among the following boards:

- A14 I/O board
- A15 Memory Management Unit (MMU) board
- A17 Executive Processor board
- A18 Memory board

A14 Input/Output (I/O) Board

The A14 I/O board contains the following circuitry:

- Data buffers
- Timer configuration circuitry
- Real time clock
- Serial data interface (SDI)
- Temp/tone readback buffer
- Tone generator
- GPIB control circuitry

See Figure 9-9 for a block diagram of this board.

The A14 I/O board is an interface between the Executive Processor (EXP) and devices on the A9, A10, and A11 Front Panel boards, the A12 Rear Panel assembly, and on-board I/O devices. The EXP reads and writes to these I/O devices at specific I/O addresses. These I/O addresses are decoded to produce device select signals which enable the addressed device. Each I/O device is located on I/O address boundaries of at least 100\text{hex}.

The lower eight bits of the Executive data bus transmit data to and from the various I/O devices. Note that only one I/O device can be accessed at a time.

I/O Data Buffer

This circuit buffers the lower eight bits of the Executive data bus from P105. The output of the I/O data bus drives data to the following six on-board devices:

- I/O delayed data buffer
- Rear panel data buffer
- Front panel data buffer
- Tone generator
- Tone/temp readback buffer
- Timer configuration circuitry
I/O Delayed Data Buffer

This circuit is the interface between the I/O data bus and the Write Delayed data bus.

Timer Configuration

This circuitry is composed of a latch and three two-input data multiplexers built with discrete gates. When a byte of data on the I/O data bus is latched, some of the data bits individually configure counters 1 and 2, allowing the timer to accept different inputs for different system tasks. The operating system uses counter 0 as a real-time clock based on the 2 MHz CLK input from the clock generator that is always operating at 8 MHz.

Real Time Clock

This clock and its oscillator circuit maintain the current time of day. The EXP sets the real time clock and also interrupts the Executive processor (EXP) every one second to request the EXP to read the time.

Serial Data Interface (SDI)

This is a custom IC that interfaces the EXP to both front panel knobs. The EXP controls this IC, and this IC interrupts the EXP when a device requires service.

Tone Generator

This circuitry utilizes a DAC and a timer. The timer is equipped with a special current switch and capacitor to set the timer’s frequency. The timer outputs a square wave whose frequency is inversely proportional to the digital value written to the temp/tone DAC. Thus, if a zero value is input to the DAC, the tone generator produces the highest tone.

Temp/Tone Readback Buffer

This circuit is an eight-line buffer connected to the I/O data bus. The EXP uses this buffer to monitor the tone generator.
A15 Memory Management Unit (MMU) Board

The A15 MMU board consists of the following circuits:

- MMU IC
- Waveform RAM
- Display interface
- Time Base/Controller interface
- Executive processor (EXP) interface
- Display IC
- Microprocessor
- Bit map RAM
- Waveform display RAM circuitry
- Video DAC

The A15 MMU board coordinates communications among the following three CSA 803A subsystems:

- Display
- Time Base/Controller
- Executive

See Figure 9-10 for a block diagram of this board.

**MMU IC**

This circuit controls all data transfers to and from waveform RAM. The MMU gate array controls high-speed transfers of waveform data and communication messages between waveform RAM and the three subsystem interfaces: the Display, Time Base/Controller and Executive processors. A set of handshaking lines designed to the DMA facilities of each particular subsystem coordinates each subsystem interface.

**Waveform RAM**

This circuit consists of 512 Kbytes of RAM. The RAM holds waveform data and messages that are read and written by the Time Base/Controller, Display, and Executive subsystems.

**Display Interface**

Data is transferred to and from the Display subsystem and to and from the MMU IC through this interface. The data is buffered with the bidirectional display data buffers.
Time Base/Controller Interface
Data is transferred to and from the Time Base/Controller subsystem and to and from the MMU IC through this interface.

Executive Processor (EXP) Interface
This circuitry consists of bidirectional buffers, address mapping programmable array logic (PAL), and interface timing control PALs. This circuitry directs data flow to the EXP from the MMU IC and vice versa.

Display IC
This component consists of the following functional circuits:

- CRT controller
- Video output circuitry
- Compressor circuit

The basic function of the CRT Controller is to produce VIDEO and SYNC signals that indicate to the CRT where to position video information. The controller is virtually automatic in operation and invisible to the firmware programmer with the exception of several internal registers that must be initialized at power-on.

The video output circuitry is where the hardware recognizes and displays specific data structures; the raster-scan CRT displays the contents of the bit map.

During the refresh of the screen, the hardware acquires bit map data along with waveform display data to yield a final color index.

The compressor circuit receives a waveform composed of several possible number of data points and outputs 512 pairs (one minimum and one maximum) to the display.

Microprocessor
This component transforms the entire Display subsystem into an intelligent peripheral dedicated to operating the display. The firmware that controls the Display subsystem executes from ROM in the microprocessor’s address space. The clock for this microprocessor operates at a frequency of 8 MHz.

Bit Map RAM
This circuit consists of 256 Kbytes of RAM, divided into 4-bit planes of 65,536 bytes each. Three of the bit planes are for text and the remaining bit plane is for XY, variable persistence, and infinite persistence. Each bit in a plane represents a single pixel of the display. Setting the representative pixel bit in each of the planes controls the color or intensity.
**Block Diagram Descriptions**

**Waveform Display RAM**

This memory circuitry consists of 65,536 bytes. These bytes contain the minimum/maximum pairs of values, along with color index and overrange/underrange information.

**Video Digital-to-Analog Converter (DAC)**

This circuit converts the digital data from the Display IC into analog data for the A7 CRT Socket board.

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**A17 Executive Processor Board**

The A17 Executive Processor board consists of the:

- Executive processor (EXP)
- Numeric coprocessor circuitry
- Bus buffer circuitry
- Preset circuitry
- Wait state circuitry
- Interrupt controllers
- DMA Controller

See Figure 9-11 for a block diagram of this board.

**Executive Processor (EXP)**

This microprocessor executes firmware routines stored in EPROMS that are located on the A18 Memory board to control the operation of the CSA 803A. Along with the numeric coprocessor, the EXP does all data processing not directly related to generating the display or digitizing the waveform. When power is first applied to the CSA 803A, the EXP executes local and system diagnostic tests, which are located in the EPROMs on the A18 Memory board.

The EXP performs the following functions with three main circuits:

- the clock generator generates the timing signals and synchronized reset signals for the microprocessor
- the microprocessor reads and writes data, generates addresses for I/O and memory devices, and generates status signals for the bus controller
- the bus controller interprets the microprocessor’s status signals and generates the necessary bus control signals for the Executive bus

Address decoders, address latches, and data buffers are all support circuits for I/O operations.
Numeric Coprocessor

This coprocessor is a high-speed, floating-point processor that executes instructions in parallel with the EXP. The EXP programs and controls the numeric coprocessor as an I/O device at addresses $0F8_{\text{hex}}$ to $0FF_{\text{hex}}$.

Bus Controller

This circuit consists of a data buffer, an address buffer, and a control buffer that provide command and control signals from the microprocessor to the three Executive busses. The Executive busses consist of the following:

- **The system data bus** — is a bidirectional bus. It allows the microprocessor to fetch instructions from memory, and also to write data to memory and read data from memory. The memory that the microprocessor uses is located on the A18 Memory board.

- **The system address bus** — carries the address of a device when the microprocessor is requesting access to that device. Once the microprocessor has access, the addressed device can then respond to the microprocessor.

- **The system control bus** — carries control signals sent by the microprocessor. These control signals are sent to the devices that the microprocessor addresses, so that the devices can respond at the proper moment in the bus cycle.

Reset

This circuit generates synchronized ready and reset control signals.

Wait State

This circuit extends the bus cycle with wait states so that slower devices have sufficient time to read or write data.

Interrupt Controllers

These circuits constantly monitor the EXP’s interrupt lines to ensure that the highest priority interrupt gets serviced first. The Interrupt controllers provide the ability to assign priority levels to all the system’s interrupt lines and, conversely, to ignore (mask) any of the interrupt lines as well.

DMA Controller

This circuit shortens the GPIB transfer time as well as the transmission time of waveforms through the GPIB.
A18 Memory Board

The A18 Memory Board provides the Executive processor (EXP) with system RAM (SRAM), Non-volatile RAM (NVRAM), and EPROM for most operations. Support circuitry for the memories and diagnostic circuitry for troubleshooting are located on-board. All accesses to SRAM, NVRAM, or EPROMs are initiated by the A17 Executive Processor board (specifically by the EXP or the DMA controller). Refer to the discussion of the A17 Executive Processor board, earlier in this section, for bus cycle timing information.

The A18 Memory board consists of the following circuitry:

- Address latches
- Address decode and memory select circuitry
- EPROM and system RAM
- Memory data buffers
- Wait state generator
- Wait state diagnostics
- Memory configuration readback
- Non-volatile RAM and battery backup

See Figure 9-12 for a block diagram of this board.

Address Latches

This circuitry buffers and holds the address lines for the EPROMs, SRAMs, NVRAMs, and other on-board devices until the end of the bus cycle.

Address Decode and Memory Select

This circuit consists of a programmable array logic (PAL) device that decodes the address lines to produce five RAM select signals (DCS4-8) and four EPROM select signals (DCS0-3). DCS8 enables the SRAM while DCS4-7 enable the NVRAM. All EPROM and RAM select lines are latched, and the latch outputs are normally enabled. While the latch enable signal is high, the latch outputs are responsive to changes on the inputs; while the latch enable signal is low, the select lines are latched.

The EXP on the A17 Executive Processor board generates the address line inputs, A14-A19. Depending upon the position of a jumper on the A17 Executive Processor board, address lines A20-A23 can be memory bank-select lines or microprocessor address lines.

The memory select circuitry provides latched memory select lines and an enable signal for the memory data buffers.
**EPROMs, SRAM, and NVRAM**

The memory includes EPROMs, System RAM (SRAM), and Non-volatile RAM (NVRAM). The EPROMs contain all of the operating system code and diagnostics code for the EXP. All the memories share the latched address bus. The SRAM (System RAM) stores miscellaneous constants that the operating system code uses and produces. The NVRAM (non-volatile RAM) contains stored settings, stored traces, and other non-volatile parameters. The memories are organized into high and low-byte pairs. The address decode PAL generates latched chip-select signals. A separate latched chip-select signal selects each of these pair. The memory data buffers buffer the data lines to the Executive data bus.

**Memory Data Buffers**

This circuitry drives data between the memories and Executive data bus. Both 8-bit buffers are enabled when all of their inputs are high.

**Wait State Generator**

This circuit allows the EXP to access memory devices when the EXP is operating at faster clock frequencies. When the EXP is operating at frequencies greater than 8 MHz, the bus cycle time is too short to allow reads or writes to the present memory devices. The wait state generator sets the SRDY line (see Figure 9-11) on the Executive bus low to signal the EXP to lengthen the bus cycles.

The wait state generator also contains a circuit to generate control signals (similar to those on the Executive bus). These control signals are early address latch (ELATCH), early memory write control (EMWTC), and early memory read control (EMRDC).

**Wait State Diagnostics**

These diagnostics measure the time interval that the wait state generator generates when a one (1) is written to I/O address \(8020_{\text{hex}}\). This causes the wait state diagnostics to connect the SRDY signal to the DIAGNSIG line on the Executive bus. A timer on the A14 I/O board can then measure the length of the wait.

**Memory Configuration Readback**

This circuitry allows the diagnostics to read the position of the memory configuration straps and the bank address lines. One bit of the readback data byte also indicates if the battery is at 2.5 V (an early warning of a low battery). The EXP performs an I/O read at address \(8040_{\text{hex}}\) to read this information.
Battery Backup

This circuit provides standby power to the non-volatile RAM (NVRAM) during the powered-off periods of the CSA 803A.

A19 Strobe/TDR Buffer Board

The A19 Strobe/TDR buffer board is comprised of three main circuits:

- Strobe sense select circuitry
- Strobe deskew circuitry
- TDR buffer and level shift circuitry

See Figure 9-13 for a block diagram of this board.

Strobe Sense Select

This circuitry consists of three signal diodes (these diodes are normally off). The diodes carry the two sampling signals (J3A, J4A) from the two sampling heads and the reference strobe signal. When a particular diode is biased on, it allows the selected strobe sense signal to continue out of jumper J32.

Strobe Deskew

This circuit corrects the time delay between the sampling strobe signals which may occur from the mismatch in the external cabling or in the internal cables that distribute the strobe. The repositioning is done with the strobe deskew voltages, which are DC control voltages found on jumper J34. (Power is also supplied to this board through this jumper.) The strobe deskew voltages are generated on the A1 M/F Strobe Drive board and are controlled by the microprocessor on the A5 Time Base/Controller board. The sampling strobe alignment is checked by routing the strobe sense signals to the A5 Time Base/Controller board where the microprocessor measures and adjusts the time alignment of each sampling head.

TDR Buffer and Level Shift

This circuitry consists of an ECL buffer and four dual-transistors that level-shift the TDR signal for proper drive of the TDR step generators in the sampling heads.
A20/A21 Head Interconnect (Power Only) Boards

The A20/A21 Head Interconnect (Power Only) boards provide power only to the interface between the sampling head connectors (J11, J12) and ribbon cable W150. W150 connects to the A26 M/F Acquisition Interface board and carries the control status and power.

A22/A23 Head Interconnect Boards

The A22/A23 Head Interconnect boards provide the interface between the sampling head connectors (J13, J14) and ribbon cable W150 and coaxial cables W100 and W200. W150 connects to the A26 M/F Acquisition Interface board and carries the control status and power. W100 and W200 connect to the A27 Acquisition Analog board and carry the signal from the sampling heads.

A26 M/F Acquisition Interconnect Board

The A26 M/F Acquisition Interconnect board provides and distributes the power to the interconnections between the following boards:

- A27 Acquisition Analog board
- A28 Acquisition MPU board
- A22/A23 Head Interconnect boards

See Figure 9-14 for the block diagram of this board.

The A26 M/F Acquisition Interconnect board also has a precision voltage reference (V) to furnish the ±5 V reference required by the A27 Acquisition Analog board.
A27 & A28 Acquisition System Boards

The Acquisition system consists of two boards: the A27 Acquisition Analog board and the A28 Acquisition MPU board.

The A27 Acquisition Analog board consists of the following major blocks:

- Programmable gain amplifiers
- A/D converters
- Measurement hardware
- Timing and sampling head control

The A28 Acquisition Analog board consists of the following major blocks:

- Shared RAM
- Time base/controller interface
- Microprocessor
- Measurement hardware
- Timing and sampling head control

See Figures 9-15 and 9-16 for the block diagrams of these boards.

Programmable Gain Amplifiers

The four sampling head outputs are multiplexed to two amplifier channels through the input multiplexer. The microprocessor selects a sampling head channel to be acquired and connects it to one of the amplifier channels. The programmable gain amplifier then applies offset (Vert Pos) and amplifies or attenuates the signal (Vert Size). The output of the amplifier is applied to the analog to digital (A/D) converter for conversion to digitized data.

A/D Converters

The output of each programmable gain amplifier is applied to an 8-bit flash A/D converter. The converter compares its analog input to two reference voltages (+1 V REF and −1 V REF) and outputs an 8-bit binary number that indicates the value of the analog input signal in relation to the reference voltages. The digital output from the A/D converters is stored in the shared RAM and made available for transfer to the Waveform Memory through the Time Base/Controller.

Measurement Hardware

This circuitry has the selected sampling head output from the input multiplexer applied to a precision-strobed voltage comparator. This voltage comparator compares the sampling head output voltage to a reference voltage generated by a 14-bit digital-to-analog converter (DAC). The comparator output is then filtered by a filter and transition counter circuit on the A28 Acquisition MPU board to remove false transitions generated by noise and to count the transitions.
When the processor requests a hardware timing measurement such as a propagation delay measurement, the comparator is programmed for the appropriate measurement level and the transition counter is programmed to locate the selected transition number and slope. The hardware counts the strobe pulses that occur from the beginning of the acquisition to the point where the selected transition occurs. This operation is performed on two channels — one for each crossing point of the timing measurement. When the transition points are found, the Acquisition processor reads the sample number from the hardware and stores it in a specific location in the shared memory for the Time Base/Controller. The Time Base/Controller reads these points (from each channel involved in the measurement), subtracts these points, and then multiplies the result by the sampling interval. The result is a measurement of the time between the two threshold points.

**Timing and Sampling Head Control**

This hardware generates analog control voltages that control several sampling head operating and calibration parameters. For example, the loop gain calibration adjustment is controlled by an analog voltage generated in the CSA 803A for each sampling head channel. In addition, three digital control lines go to each sampling head — two to enable or disable TDR on each channel and one to enable smoothing for both channels in a head.

This circuit block also generates timing signals that control when waveform data is digitized and when the measurement hardware is clocked. The time base sends a strobe pulse to the acquisition system and to the sampling head to initiate a sample. Each acquisition processor can also generate strobe pulses locally for Self-Tests and diagnostic purposes.

**Shared RAM**

This memory for the A28 Acquisition MPU board contains 16 Kbytes of shared RAM. This memory is arbitrated on the A25/A28 Acquisition MPU boards between the Acquisition system processor, the Time Base/Controller processor, and the A/D converters on the A27 Acquisition Analog board. All waveform data acquired by the Acquisition system, as well as control and data messages passed between the Acquisition system and the Time Base/Controller, pass through this shared memory.

**Time Base/Controller Interface**

This circuitry handles requests from the Time Base/Controller to access the shared memory on the A28 Acquisition MPU boards. The shared memory is then arbitrated and buffered through the Time Base/Controller interface hardware. This hardware decodes and latches the Time Base/Controller address and generates a wait signal that holds the Time Base/Controller processor in a wait state until a bus cycle can be granted to allow the memory access to complete.

The arbitration logic coordinates requests for access to the shared memory from the A/D converters, the Acquisition system processor, and the time base/controller processor.
Microprocessor

A microprocessor controls the Acquisition system, which has 64 Kbytes of EPROM for code storage, 16 Kbytes of shared RAM, and 8 Kbytes of un-shared RAM. The microprocessor calibrates and manages the program-mable gain amplifiers and measurement hardware. The microprocessor also accepts and executes commands from the Time Base/Controller processor and manages the sampling head digital and analog controls, including scanning the front panel SELECT buttons on the sampling head and driving the front panel LEDs.
Performance Verification

This section contains procedures to check electrical specifications and examine measurement limits listed in Table 4-1. Use these procedures to check the CSA 803A following repair, or to verify that the CSA 803A meets specifications. To functionally test the CSA 803A, simply perform the procedures which have a “yes” indication in the Functional Tests column listed in Table 4-1. The Specifications or Measurement Limits are given at the beginning of each procedure. Adjustment procedures are included in the Adjustments section. Refer to the CSA 803A Communications Signal Analyzer User Manual for more information about specifications and CSA 803A operation. The Setup in each procedure provides information concerning test equipment setup or interconnection. Refer to Table 4-2 for more information concerning test equipment used in the setups.

Most Performance Verification and Adjustment procedures can be run in any order. However, the Sampling Head Calibration must always precede other procedures which use an operational sampling head (i.e., does not apply to procedures using the Calibration Head). Also, if different sampling heads are used, then sampling head calibration is required for each additional sampling head.

Table 4-1: Measurement Limits, Specifications, and Functional Tests

<table>
<thead>
<tr>
<th>Procedure Description</th>
<th>Measurement Limits (Examine)</th>
<th>Specifications (Check)</th>
<th>Functional Tests</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power-On Diagnostics</td>
<td>none</td>
<td>none</td>
<td>yes</td>
</tr>
<tr>
<td>Sampling Head</td>
<td>none</td>
<td>none</td>
<td>yes</td>
</tr>
<tr>
<td>Extended Diagnostics</td>
<td>none</td>
<td>none</td>
<td>yes</td>
</tr>
<tr>
<td>Vertical Reference Voltage</td>
<td>none</td>
<td>+5 V ±200 μV and -5 V ±200 μV</td>
<td>no</td>
</tr>
<tr>
<td>Horizontal Reference Clock</td>
<td>none</td>
<td>200,000 kHz ±5 kHz</td>
<td>no</td>
</tr>
<tr>
<td>Vertical Accuracy</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Vertical Gain</td>
<td>none</td>
<td>±1.0% full scale</td>
<td>yes</td>
</tr>
<tr>
<td>Offset Accuracy</td>
<td>none</td>
<td>±2 mV</td>
<td>yes</td>
</tr>
<tr>
<td>Vertical Linearity</td>
<td>none</td>
<td>±1%</td>
<td>no</td>
</tr>
<tr>
<td>System Vertical RMS Noise</td>
<td>200 μV at 2 mV/div</td>
<td>none</td>
<td>yes</td>
</tr>
<tr>
<td></td>
<td>500 μV at 5 mV/div</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>1 mV at 10 mV/div</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>632 μV at 20 mV/div</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>1.58 mV at 50 mV/div</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>3.16 mV at 100 mV/div</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>6.32 mV at 200 mV/div</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Table 4-1: Measurement Limits, Specifications, and Functional Tests (Cont.)

<table>
<thead>
<tr>
<th>Procedure Description</th>
<th>Measurement Limits (Examine)</th>
<th>Specifications (Check)</th>
<th>Functional Tests</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sweep Rate Accuracy</td>
<td>0.05% at 2 ns/div 0.08% at 1 ns/div 0.8% at 100 ps/div 2.5% at 10 ps/div 10% at 1 ps/div</td>
<td>none</td>
<td>yes</td>
</tr>
<tr>
<td>Triggering</td>
<td></td>
<td></td>
<td>yes</td>
</tr>
<tr>
<td>300 MHz Sensitivity</td>
<td>100 mV&lt;sub&gt;pp&lt;/sub&gt; at 300 MHz</td>
<td>100 mV stable display</td>
<td></td>
</tr>
<tr>
<td>1000 MHz Sensitivity</td>
<td>100 mV&lt;sub&gt;pp&lt;/sub&gt; at 1000 MHz</td>
<td>100 mV stable display</td>
<td></td>
</tr>
<tr>
<td>3.0 GHz Sensitivity</td>
<td>100 mV&lt;sub&gt;pp&lt;/sub&gt; at 3.0 GHz</td>
<td>100 mV stable display</td>
<td></td>
</tr>
<tr>
<td>Internal Clock</td>
<td></td>
<td></td>
<td>yes</td>
</tr>
<tr>
<td>Rise Time</td>
<td>≤ 2.5 ns</td>
<td>≤ 2.5 ns</td>
<td></td>
</tr>
<tr>
<td>Frequency</td>
<td>100 kHz ±3%</td>
<td>100 kHz ±3%</td>
<td></td>
</tr>
<tr>
<td>Duty Cycle</td>
<td>50% ±3%</td>
<td>50% ±3%</td>
<td></td>
</tr>
<tr>
<td>Prescaler</td>
<td>600 mV&lt;sub&gt;pp&lt;/sub&gt; at 2 GHz</td>
<td>600 mV stable display</td>
<td>yes</td>
</tr>
<tr>
<td></td>
<td>600 mV&lt;sub&gt;pp&lt;/sub&gt; at 8 GHz</td>
<td>600 mV stable display</td>
<td></td>
</tr>
<tr>
<td></td>
<td>2 V&lt;sub&gt;pp&lt;/sub&gt; at 10 GHz</td>
<td>2 V stable display</td>
<td></td>
</tr>
<tr>
<td>Calibrator Output</td>
<td></td>
<td></td>
<td>yes</td>
</tr>
<tr>
<td>Rise Time</td>
<td>≤ 250 ps (20% – 80%)</td>
<td>≤ 250 ps (20% – 80%)</td>
<td></td>
</tr>
<tr>
<td>Peak-to-peak Amplitude</td>
<td>250 mV ±10%</td>
<td>250 mV ±10%</td>
<td></td>
</tr>
</tbody>
</table>
## Test Equipment

Table 4-2 (Test Equipment), contains suggested test equipment for use in this manual. Procedure steps are based on the test equipment examples given, but you may substitute other equipment with similar specifications. The use of different equipment may alter test results, setup information, and related connectors and adapters.

### Table 4-2: Test Equipment

<table>
<thead>
<tr>
<th>Description</th>
<th>Minimum Specification</th>
<th>Examples of Applicable Test Equipment</th>
</tr>
</thead>
<tbody>
<tr>
<td>High Frequency Sine Wave Generator</td>
<td>10 MHz to 10 GHz</td>
<td>WILTRON 6759B Opt 2</td>
</tr>
<tr>
<td>Sampling Head</td>
<td>SD-Series</td>
<td>SD-24 and any other Tektronix SD-Series Sampling Head except SD-14</td>
</tr>
<tr>
<td>Digital Voltmeter (w/test leads)</td>
<td>≤0.005% Accuracy</td>
<td>FLUKE 8842A Digital Voltmeter</td>
</tr>
<tr>
<td>Frequency Counter</td>
<td>One Part in 1,000,000 Accuracy</td>
<td>Tektronix DC 5010 Universal Counter/Timer with a TM 5000-Series Power Module</td>
</tr>
<tr>
<td>Calibration Head</td>
<td></td>
<td>Tektronix Calibration Head 067-1413-00</td>
</tr>
<tr>
<td>Precision Voltage Source</td>
<td></td>
<td>DATA PRECISION 8200</td>
</tr>
<tr>
<td>Test Terminal</td>
<td>any GPIB (IEEE-1978) controller, or ASCII terminal equipped with an RS-232-C port. Requires compatible RS-232-C serial interface cable</td>
<td>IBM compatible PC with terminal emulation software</td>
</tr>
<tr>
<td>Coaxial Cable, 50 Ω (3 required)</td>
<td>50 Ω, 36-inch, male BNC connectors</td>
<td>Tektronix Part 012–0482–00</td>
</tr>
<tr>
<td>Coaxial Cable, RF</td>
<td>RF cable, 12 in., SMA connectors</td>
<td>Tektronix Part 174–1364–00</td>
</tr>
<tr>
<td></td>
<td>RF cable, 8.5 in., SMA connectors</td>
<td>Tektronix Part 174–1120–00</td>
</tr>
<tr>
<td>Description</td>
<td>Minimum Specification</td>
<td>Examples of Applicable Test Equipment</td>
</tr>
<tr>
<td>------------------------------</td>
<td>------------------------------------------------------------</td>
<td>----------------------------------------------------</td>
</tr>
<tr>
<td>Adapters</td>
<td>BNC female-to-male Dual Banana</td>
<td>Tektronix Part 103–0090–00</td>
</tr>
<tr>
<td></td>
<td>BNC male-to-female Dual Banana</td>
<td>Tektronix Part 103–0035–00</td>
</tr>
<tr>
<td></td>
<td>SMA male-to-BNC female (8 required)</td>
<td>Tektronix Part 015–1018–00</td>
</tr>
<tr>
<td></td>
<td>SMA female-to-BNC male</td>
<td>Tektronix Part 013–0126–00</td>
</tr>
<tr>
<td></td>
<td>SMA male-to-N male</td>
<td>Tektronix Part 015–0369–00</td>
</tr>
<tr>
<td>Power Divider, 50 Ω</td>
<td>6 dB load isolation, 50 Ω, SMA connectors</td>
<td>Tektronix Part 015–1014–00</td>
</tr>
<tr>
<td>Termination, 50 Ω</td>
<td>Impedance, 50 Ω; accuracy within 2%; SMA connectors</td>
<td>Tektronix Part 015–1022–00</td>
</tr>
<tr>
<td>Attenuator, 10X</td>
<td>20 dB attenuation, 50 Ω, one male and one female</td>
<td>Tektronix Part 011–0059–02</td>
</tr>
<tr>
<td>Attenuator, 2X</td>
<td>50 Ω, SMA, one male and one female</td>
<td>Tektronix Part 015–1001–00</td>
</tr>
<tr>
<td>Power Supplies Troubleshooting Fixture</td>
<td>Tektronix 067–1264–00 Extended Diagnostics 11000-Series Power Supplies troubleshooting fixture</td>
<td></td>
</tr>
<tr>
<td>Probe, 10X</td>
<td>Attenuation 10X</td>
<td>Tektronix P6106A</td>
</tr>
<tr>
<td>Pickoff, 10X</td>
<td>Picosecond Pulse Labs 5520A</td>
<td></td>
</tr>
<tr>
<td>Power Meter</td>
<td>HP 436A</td>
<td></td>
</tr>
<tr>
<td>Power Sensor</td>
<td>HP 8485A</td>
<td></td>
</tr>
<tr>
<td>Alignment Tool</td>
<td>Plastic hex</td>
<td>Tektronix Part 003–0301–00</td>
</tr>
<tr>
<td></td>
<td>Insulated slot</td>
<td>Tektronix Part 003–0675–01</td>
</tr>
<tr>
<td></td>
<td>Square Tip (ceramic)</td>
<td>Tektronix Part 003–1400–00</td>
</tr>
<tr>
<td>Magnetic Screwdriver</td>
<td>Holder for Torx head tips</td>
<td>Tektronix Part 003–0293–00</td>
</tr>
</tbody>
</table>
### Table 4-2: Test Equipment (Cont.)

<table>
<thead>
<tr>
<th>Description</th>
<th>Minimum Specification</th>
<th>Examples of Applicable Test Equipment</th>
</tr>
</thead>
<tbody>
<tr>
<td>Torx Head Screw-driver</td>
<td>#10 tip</td>
<td>Tektronix Part 003–0814–00</td>
</tr>
<tr>
<td></td>
<td>#15 tip</td>
<td>Tektronix Part 003–0966–00</td>
</tr>
<tr>
<td></td>
<td>#20 tip</td>
<td>Tektronix Part 003–0866–00</td>
</tr>
<tr>
<td>External Loopback Connector</td>
<td>RS-232-C connector</td>
<td>Tektronix Part 013–0198–00</td>
</tr>
<tr>
<td>Shorting Strap</td>
<td>Two alligator clips</td>
<td></td>
</tr>
<tr>
<td></td>
<td>on a short pigtail</td>
<td></td>
</tr>
<tr>
<td></td>
<td>conductor</td>
<td></td>
</tr>
<tr>
<td>Integrated Circuit</td>
<td>IC Insertion-Extraction Pliers, 28-pin</td>
<td>General Tool P/N U505BG or equivalent</td>
</tr>
<tr>
<td>Extracting Tool</td>
<td>type</td>
<td></td>
</tr>
<tr>
<td>Board Removal Tools</td>
<td>Straight-slot screw-</td>
<td></td>
</tr>
<tr>
<td></td>
<td>driver, large</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Torx-drive screw-</td>
<td></td>
</tr>
<tr>
<td></td>
<td>driver, T-7, T-8, T-10, T-15, T-20, T-25</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Allen (hex) Wrench,</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1/16-inch</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Nutdrivers, 3/16-inch, 1/4-inch, 7/16-inch</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Needle-nose pliers</td>
<td></td>
</tr>
<tr>
<td>Small Ruler</td>
<td>Half inch rulings</td>
<td></td>
</tr>
<tr>
<td>Antistatic wrist strap</td>
<td></td>
<td>Tektronix Part 006–3415–04</td>
</tr>
</tbody>
</table>
Test Record

Photocopy pages 4-7 through 4-10 and use them to record the performance test results for your instrument.
## CSA 803A Test Record

<table>
<thead>
<tr>
<th>Instrument Serial Number:</th>
<th>Certificate Number:</th>
</tr>
</thead>
<tbody>
<tr>
<td>Temperature:</td>
<td>RH %:</td>
</tr>
<tr>
<td>Date of Calibration:</td>
<td>Technician:</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Performance Test</th>
<th>Minimum</th>
<th>Incoming</th>
<th>Outgoing</th>
<th>Maximum</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Vertical Accuracy</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Vertical Gain, First Compartment

<table>
<thead>
<tr>
<th>Step 11.</th>
<th>5 mV/div</th>
<th>10 mV/div</th>
<th>20 mV/div</th>
<th>50 mV/div</th>
<th>100 mV/div</th>
<th>200 mV/div</th>
<th>5 mV/div</th>
<th>10 mV/div</th>
<th>20 mV/div</th>
<th>50 mV/div</th>
<th>100 mV/div</th>
<th>200 mV/div</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>−20.5 mV</td>
<td>−41.0 mV</td>
<td>−82 mV</td>
<td>−205 mV</td>
<td>−410 mV</td>
<td>−820 mV</td>
<td>19.5 mV</td>
<td>39.0 mV</td>
<td>78 mV</td>
<td>195 mV</td>
<td>390 mV</td>
<td>780 mV</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

±1.2% at Checkpoint

### Vertical Offset Accuracy, First Compartment

<table>
<thead>
<tr>
<th>Step 10.</th>
<th>400 mV</th>
<th>398 mV</th>
<th>402 mV</th>
</tr>
</thead>
<tbody>
<tr>
<td>Step 12.</td>
<td>1 V</td>
<td>0.998 V</td>
<td>1.002 V</td>
</tr>
<tr>
<td></td>
<td>2 V</td>
<td>1.998 V</td>
<td>2.002 V</td>
</tr>
<tr>
<td></td>
<td>−400 mV</td>
<td>−402 mV</td>
<td>−398 mV</td>
</tr>
<tr>
<td></td>
<td>−1 V</td>
<td>−1.002 V</td>
<td>−0.998 V</td>
</tr>
<tr>
<td></td>
<td>−2 V</td>
<td>−2.002 V</td>
<td>−1.998 V</td>
</tr>
</tbody>
</table>

± 2 mV
### CSA 803A Test Record (Cont.)

<table>
<thead>
<tr>
<th>Performance Test</th>
<th>Minimum</th>
<th>Incoming</th>
<th>Outgoing</th>
<th>Maximum</th>
</tr>
</thead>
<tbody>
<tr>
<td>Vertical Gain, Second Compartment</td>
<td></td>
<td></td>
<td></td>
<td>±1.2% at Checkpoint</td>
</tr>
<tr>
<td>Step 11. 5 mV/div</td>
<td>−20.5 mV</td>
<td></td>
<td></td>
<td>−19.5 mV</td>
</tr>
<tr>
<td>10 mV/div</td>
<td>−41.0 mV</td>
<td></td>
<td></td>
<td>−39.0 mV</td>
</tr>
<tr>
<td>20 mV/div</td>
<td>−82 mV</td>
<td></td>
<td></td>
<td>−78 mV</td>
</tr>
<tr>
<td>50 mV/div</td>
<td>−205 mV</td>
<td></td>
<td></td>
<td>−195 mV</td>
</tr>
<tr>
<td>100 mV/div</td>
<td>−410 mV</td>
<td></td>
<td></td>
<td>−390 mV</td>
</tr>
<tr>
<td>200 mV/div</td>
<td>−820 mV</td>
<td></td>
<td></td>
<td>−780 mV</td>
</tr>
<tr>
<td>5 mV/div</td>
<td>19.5 mV</td>
<td></td>
<td></td>
<td>20.5 mV</td>
</tr>
<tr>
<td>10 mV/div</td>
<td>39.0 mV</td>
<td></td>
<td></td>
<td>41.0 mV</td>
</tr>
<tr>
<td>20 mV/div</td>
<td>78 mV</td>
<td></td>
<td></td>
<td>82 mV</td>
</tr>
<tr>
<td>50 mV/div</td>
<td>195 mV</td>
<td></td>
<td></td>
<td>205 mV</td>
</tr>
<tr>
<td>100 mV/div</td>
<td>390 mV</td>
<td></td>
<td></td>
<td>410 mV</td>
</tr>
<tr>
<td>200 mV/div</td>
<td>780 mV</td>
<td></td>
<td></td>
<td>820 mV</td>
</tr>
<tr>
<td>Vertical Offset Accuracy, Second Compartment</td>
<td></td>
<td></td>
<td></td>
<td>±2 mV</td>
</tr>
<tr>
<td>Step 10. 400 mV</td>
<td>398 mV</td>
<td></td>
<td></td>
<td>402 mV</td>
</tr>
<tr>
<td>Step 12. 1 V</td>
<td>0.998 V</td>
<td></td>
<td></td>
<td>1.002 V</td>
</tr>
<tr>
<td>2 V</td>
<td>1.998 V</td>
<td></td>
<td></td>
<td>2.002 V</td>
</tr>
<tr>
<td>−400 mV</td>
<td>−402 mV</td>
<td></td>
<td></td>
<td>−398 mV</td>
</tr>
<tr>
<td>−1 V</td>
<td>−1.002 V</td>
<td></td>
<td></td>
<td>−0.998 V</td>
</tr>
<tr>
<td>−2 V</td>
<td>−2.002 V</td>
<td></td>
<td></td>
<td>−1.998 V</td>
</tr>
<tr>
<td>Vertical Gain, Third Compartment</td>
<td></td>
<td></td>
<td></td>
<td>±1.2% at Checkpoint</td>
</tr>
<tr>
<td>Step 11. 5 mV/div</td>
<td>−20.5 mV</td>
<td></td>
<td></td>
<td>−19.5 mV</td>
</tr>
<tr>
<td>10 mV/div</td>
<td>−41.0 mV</td>
<td></td>
<td></td>
<td>−39.0 mV</td>
</tr>
<tr>
<td>20 mV/div</td>
<td>−82 mV</td>
<td></td>
<td></td>
<td>−78 mV</td>
</tr>
<tr>
<td>50 mV/div</td>
<td>−205 mV</td>
<td></td>
<td></td>
<td>−195 mV</td>
</tr>
<tr>
<td>100 mV/div</td>
<td>−410 mV</td>
<td></td>
<td></td>
<td>−390 mV</td>
</tr>
<tr>
<td>200 mV/div</td>
<td>−820 mV</td>
<td></td>
<td></td>
<td>−780 mV</td>
</tr>
<tr>
<td>Performance Test</td>
<td>Minimum</td>
<td>Incoming</td>
<td>Outgoing</td>
<td>Maximum</td>
</tr>
<tr>
<td>------------------</td>
<td>---------</td>
<td>----------</td>
<td>----------</td>
<td>---------</td>
</tr>
<tr>
<td>5 mV/div</td>
<td>19.5 mV</td>
<td></td>
<td></td>
<td>20.5 mV</td>
</tr>
<tr>
<td>10 mV/div</td>
<td>39.0 mV</td>
<td></td>
<td></td>
<td>41.0 mV</td>
</tr>
<tr>
<td>20 mV/div</td>
<td>78 mV</td>
<td></td>
<td></td>
<td>82 mV</td>
</tr>
<tr>
<td>50 mV/div</td>
<td>195 mV</td>
<td></td>
<td></td>
<td>205 mV</td>
</tr>
<tr>
<td>100 mV/div</td>
<td>390 mV</td>
<td></td>
<td></td>
<td>410 mV</td>
</tr>
<tr>
<td>200 mV/div</td>
<td>780 mV</td>
<td></td>
<td></td>
<td>820 mV</td>
</tr>
</tbody>
</table>

**Vertical Offset Accuracy, Third Compartment**

<table>
<thead>
<tr>
<th>Step</th>
<th>Voltage</th>
<th>Minimum</th>
<th>Incoming</th>
<th>Outgoing</th>
<th>Maximum</th>
</tr>
</thead>
<tbody>
<tr>
<td>Step 10</td>
<td>400 mV</td>
<td>398 mV</td>
<td></td>
<td></td>
<td>402 mV</td>
</tr>
<tr>
<td>Step 12</td>
<td>1 V</td>
<td>0.998 V</td>
<td></td>
<td></td>
<td>1.002 V</td>
</tr>
<tr>
<td></td>
<td>2 V</td>
<td>1.998 V</td>
<td></td>
<td></td>
<td>2.002 V</td>
</tr>
<tr>
<td></td>
<td>–400 mV</td>
<td>–402 mV</td>
<td></td>
<td></td>
<td>–398 mV</td>
</tr>
<tr>
<td></td>
<td>–1 V</td>
<td>–1.002 V</td>
<td></td>
<td></td>
<td>–0.998 V</td>
</tr>
<tr>
<td></td>
<td>–2 V</td>
<td>–2.002 V</td>
<td></td>
<td></td>
<td>–1.998 V</td>
</tr>
</tbody>
</table>

**Vertical Gain, Fourth Compartment**

<table>
<thead>
<tr>
<th>Step</th>
<th>Voltage</th>
<th>Minimum</th>
<th>Incoming</th>
<th>Outgoing</th>
<th>Maximum</th>
</tr>
</thead>
<tbody>
<tr>
<td>Step 11</td>
<td>5 mV/div</td>
<td>–20.5 mV</td>
<td></td>
<td></td>
<td>–19.5 mV</td>
</tr>
<tr>
<td></td>
<td>10 mV/div</td>
<td>–41.0 mV</td>
<td></td>
<td></td>
<td>–39.0 mV</td>
</tr>
<tr>
<td></td>
<td>20 mV/div</td>
<td>–82 mV</td>
<td></td>
<td></td>
<td>–78 mV</td>
</tr>
<tr>
<td></td>
<td>50 mV/div</td>
<td>–205 mV</td>
<td></td>
<td></td>
<td>–195 mV</td>
</tr>
<tr>
<td></td>
<td>100 mV/div</td>
<td>–410 mV</td>
<td></td>
<td></td>
<td>–390 mV</td>
</tr>
<tr>
<td></td>
<td>200 mV/div</td>
<td>–820 mV</td>
<td></td>
<td></td>
<td>–780 mV</td>
</tr>
<tr>
<td></td>
<td>5 mV/div</td>
<td>19.5 mV</td>
<td></td>
<td></td>
<td>20.5 mV</td>
</tr>
<tr>
<td></td>
<td>10 mV/div</td>
<td>39.0 mV</td>
<td></td>
<td></td>
<td>41.0 mV</td>
</tr>
<tr>
<td></td>
<td>20 mV/div</td>
<td>78 mV</td>
<td></td>
<td></td>
<td>82 mV</td>
</tr>
<tr>
<td></td>
<td>50 mV/div</td>
<td>195 mV</td>
<td></td>
<td></td>
<td>205 mV</td>
</tr>
<tr>
<td></td>
<td>100 mV/div</td>
<td>390 mV</td>
<td></td>
<td></td>
<td>410 mV</td>
</tr>
<tr>
<td></td>
<td>200 mV/div</td>
<td>780 mV</td>
<td></td>
<td></td>
<td>820 mV</td>
</tr>
</tbody>
</table>
**CSA 803A Test Record (Cont.)**

<table>
<thead>
<tr>
<th>Performance Test</th>
<th>Minimum</th>
<th>Incoming</th>
<th>Outgoing</th>
<th>Maximum</th>
</tr>
</thead>
<tbody>
<tr>
<td>Vertical Offset Accuracy, Fourth Compartment</td>
<td>± 2 mV</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Step 10. 400 mV</td>
<td>398 mV</td>
<td></td>
<td></td>
<td>402 mV</td>
</tr>
<tr>
<td>Step 12. 1 V</td>
<td>0.998 V</td>
<td></td>
<td></td>
<td>1.002 V</td>
</tr>
<tr>
<td>2 V</td>
<td>1.998 V</td>
<td></td>
<td></td>
<td>2.002 V</td>
</tr>
<tr>
<td>–400 mV</td>
<td>–402 mV</td>
<td></td>
<td></td>
<td>–398 mV</td>
</tr>
<tr>
<td>–1 V</td>
<td>–1.002 V</td>
<td></td>
<td></td>
<td>–0.998 V</td>
</tr>
<tr>
<td>–2 V</td>
<td>–2.002 V</td>
<td></td>
<td></td>
<td>–1.998 V</td>
</tr>
</tbody>
</table>

**Sweep Rate Accuracy**

| ns Sweep Rate Accuracy                         |             |          |          |            |
| Step 10. 2 ns/div (± 0.05%)                    | 18.172 ns   |          |          | 18.192 ns  |
| Step 14. 1 ns/div (± 0.08%)                    | 9.083 ns    |          |          | 9.098 ns   |

| ps Sweep Rate Accuracy                         |             |          |          |            |
| Step 18. 100 ps/div (± 0.8%)                   | 902 ps      |          |          | 916 ps     |
| Step 28. 10 ps/div (± 2.5%)                    | 248.1 ps    |          |          | 260.5 ps   |
| Step 40. 1 ps/div (± 10%)                      | 23.1 ps     |          |          | 28.3 ps    |

**Internal Clock**

| Step 7. Rise Time                             |             |          |          | 2.5 ns     |
| Step 9. Frequency                             | 97 kHz      |          |          | 103 kHz    |
| Duty Cycle                                    | 47%         |          |          | 53%        |

**Calibrator Output**

| Step 7. Rise Time                             |             |          |          | 250 ps     |
| Amplitude                                     | 225 mV      |          |          | 275 mV     |
Using These Procedures

Some procedures begin with a setup illustration that shows what test equipment is needed and how to connect it. The other procedures require only a calibrated SD-Series Sampling Head. Refer to Table 4-2 (Test Equipment), on the preceding pages for an example of the test equipment for each procedure.

Conventions in this Manual

In these procedures, the following conventions are used:

- CAPITAL letters within the body of text identify front panel controls, indicators, and connectors on the CSA 803A (for example, MEASURE) and sampling head.

- Bold letters identify menu labels and display messages.

- Initial Capital letters identify connectors, controls, and indicators (for example, On) on associated test equipment.

- In some steps, the first word is italicized to identify a step that contains a performance verification and an adjustment instruction. For example, if Check is the first word in the title of a step, an electrical specification is checked. If Adjust appears in the title, the step involves an electrical adjustment. If Examine is the first word in the title, the step concerns measurement limits that indicate whether the CSA 803A is operating properly; these limits are not to be interpreted as electrical specifications.

Menu Selections and Measurement Techniques

Details on measurement techniques and instructions for making menu selections are generally not included in these procedures. Comprehensive descriptions of menus and CSA 803A features are located in the CSA 803A Communications Signal Analyzer User Manual.

User Manual

Reviewing the CSA 803A Communications Signal Analyzer User Manual is strongly recommended to familiarize the first-time user with CSA 803A controls and features.
Performance Tests

This section contains the procedures to check the electrical specifications and examine the measurement limits listed in Table 4-1. To functionally test the CSA 803A, simply perform the procedures which have a “yes” indication in the Functional Tests column. The Specifications or Measurement Limits are given at the beginning of each procedure. Adjustment procedures are included in the Adjustment section. Refer to the CSA 803A Communications Signal Analyzer User Manual for more information about CSA 803A operation. The Setup in each procedure provides information concerning test equipment setup or interconnection. Refer to Table 4-2 for more information concerning test equipment used in the setups.
Power-On Diagnostics

This procedure should be performed within the ambient temperature range of +18°C to +28°C (64°F to 82°F) when a performance check at peak operating conditions is required.

Setup to Invoke Power-On Diagnostics

![CSA 803A](image)

Procedure to Invoke Power-On Diagnostics

**CAUTION**

*Applying a voltage outside the range printed on the sampling head can result in damage. Static electricity is also a hazard.*

The input diodes used in the sampling heads are very susceptible to damage from overdrive signal or DC voltages and from electrostatic discharge. Never apply a voltage outside the range printed on the front of the sampling head. Operate the CSA 803A only in a static-controlled environment.

Connect the wrist strap provided with the CSA 803A to the **ANTISTATIC CONNECTION**, as shown in Figure 2-1. Refer to the **CSA 803A Communications Signal Analyzer User Manual** for more information.

- **Step 1**: Check that the sampling head is not yet installed and that the ON/STANDBY switch is in the STANDBY position.
- **Step 2**: Remove the top and bottom covers from the CSA 803A (unless you are only performing a functional test).
- **Step 3**: Install an SD Series sampling head in the left sampling head compartment marked CH 1/CH 2.
- **Step 4**: With the CSA 803A’s rear panel PRINCIPAL POWER SWITCH set to OFF, connect the CSA 803A to a suitable power source.
Step 5: Set the rear panel PRINCIPAL POWER SWITCH to ON and then set the CSA 803A’s front panel ON/STANDBY switch to ON.

When the CSA 803A is first installed, the rear panel PRINCIPAL POWER SWITCH should be set to and left in the ON position. From then on, use the front panel ON/STANDBY switch to perform all subsequent power switching.

Step 6: Monitor the following diagnostic run functions, and note the range of possible results.

Diagnostics

Each time the front panel ON/STANDBY switch is set to ON, the CSA 803A performs Kernel diagnostics on its microprocessor subsystems, followed by Self-Test diagnostics on most of its major circuits. Failures from either of these two sets of diagnostics may cause the CSA 803A to enter the Extended Diagnostics menu as described in this procedure.

When Kernel diagnostics begin, the Diagnostics in Progress and Comm Test in Progress messages are displayed on the screen. If the CSA 803A is being powered-on from a cold condition, then the diagnostics may be completed before the CRT is warmed up and able to display these messages. Diagnostic routines are then performed in parallel on each of the CSA 803A’s microprocessor subsystems (Display, Executive, Time Base, and Mainframe Acquisition). Following successful execution of their Kernel diagnostics, Acquisition microprocessors attempt to communicate with the Time Base microprocessor and the Time Base and Display microprocessors attempt to communicate with the Executive microprocessor.

Successful completion of Kernel diagnostics is indicated by the start of Self-Test diagnostics. A failure of Kernel diagnostics will be indicated by the message, Dsy Kernel Failure, or Comm Test in Progress displaying on the screen (for Display kernel failures) and/or by a single high-low beep and illuminated menu button indicators (for Executive kernel failures).

Self-Test Diagnostics

These begin by displaying Self-Test in Progress (when the Display microprocessor has successfully communicated with the Executive microprocessor). Pattern changes on the display and the flashing of the display indicate a test in progress. The Self-Test diagnostics are successfully completed when the CSA 803A returns to normal operation. Any failures cause the CSA 803A to produce a double high-low beep, and then to display the Extended Diagnostics menu on the screen. Faulty field replaceable units (FRUs) may then be identified by touching the (?)Help label. If any errors occur, record the error codes for the failed circuit block(s), and then refer the CSA 803A to a qualified service person.

Front panel controls are active during the Self-Test diagnostic sequence; however, any disturbance of these controls causes a test failure. If such a failure occurs, the CSA 803A automatically enters the Extended Diagnostics
mode and displays the **Extended Diagnostics** menu. Touch the **Exit** label twice to remove this menu. Note that if the diagnostics detect a fatal fault, it may not be possible to exit the menu.

**Power-On Diagnostics Complete**

This state is signified when the CSA 803A returns to normal operation. If the CSA 803A passes Power-On Diagnostics, the front-panel settings that were in effect at the last power-off are restored.
**Sampling Heads**

This procedure shows the setup and lists the test steps for calibrating Loop Gain and Offset Null. Note that this is an optional enhanced accuracy procedure and it fine tunes internal channel processing circuitry in conjunction with any operational sampling head type being used (the 067–1413–00 calibration head is a service device and does not require system calibration). This procedure also initiates a built-in CSA 803A program which causes the mainframe to remember which sampling head type was used in the calibration. In this way, pre-calibrated heads can be interchanged without requiring recalibration.

**Setup to Calibrate a Sampling Head**

**Procedure to Calibrate a Sampling Head**

- **Step 1**: Power-up and Initialize as follows:
  - Set the ON/STANDBY switch to ON ................. rocker / press
  - UTILITY button ......................................................... press
  - **Initialize** (in major menu) ............................... touch
  - **Initialize** (verify) ........................................... touch

- **Step 2**: Set up first Automatic Calibration as follows:
  - Press the UTILITY button ................................. press
  - **Page to Enhanced Accuracy** ............................... press
  - **Gain** (in major menu) ................................. touch
  - Identify Channel (2) ........................................ touch
  - **Automatic Calibrate** (in pop-up menu) ............... touch
Performance Tests

☐ **Step 3:** Perform the Loop Gain calibration as follows:

- Connect the CALIBRATOR output to the sampling head input to be calibrated (2).
- Select **Proceed** (in the Loop Gain pop-up menu) touch
- **Store Constants** (in pop-up menu) touch

☐ **Step 4:** Set up second Automatic Calibration as follows:

- Disconnect the calibration cable from the sampling head input.
- **Offset** (in major menu) touch
- **Automatic Calibrate** (in pop-up menu) touch

☐ **Step 5:** Perform the Offset Null calibration as follows:

- Connect a 50 Ω termination to the sampling head input.
- Select **Proceed** (in pop-up menu) touch
- **Store Constants** (in pop-up menu) touch
- **Exit** (in pop-up menu) touch

☐ **Step 6:** Repeat Steps 1 through 5 for all sampling head compartments and channels being tested.
Extended Diagnostics

The Extended Diagnostics perform more extensive testing than the Self-Test diagnostics. They can be used to assist troubleshooting, particularly in service environments.

Setup to Invoke Extended Diagnostics

If the CSA 803A entered the normal operating mode without any diagnostic failures, perform the following steps to enter the Extended Diagnostics mode. Do not attach inputs or I/O cables to the CSA 803A for these tests.

Procedure to Invoke Extended Diagnostics

☐ **Step 1:** With the sampling head installed as illustrated, check initial conditions as follows:

- Set the CSA 803A ON/STANDBY switch to ON ................. press
- Check sampling head Select button is OFF . . visually check indicator

**CAUTION**

You may lose stored settings, stored traces, or other data stored in NVRAM by turning the power off (that is, setting the ON/STANDBY switch to STANDBY or the PRINCIPAL POWER SWITCH to OFF) during the execution of the Extended Diagnostic tests that deal with the Executive processor’s NVRAM tests. However, this does not seriously affect oscilloscope operation.

- Select the UTILITY button ......................... press
- **Page to Enhanced Accuracy** (in major menu) ............. touch
- **Page to Utility2** (in major menu) ....................... touch
- **Extended Diagnostic** (in major menu) ................. touch
- **Extended Diagnostic** (in pop-up menu) ................ touch
- Select All, and then Run to start the tests ................. touch
Performance Tests

☐ **Step 2:** _Check_ that all tests have executed and have a Pass status. Then make the following selections in the order shown:

- **Executive** (if not already highlighted) ................. touch
- **Block** (in major menu) .................................. touch
- **External I/O** (in pop-up menu) ......................... touch
- **Area** (in major menu) .................................. touch
- **GPIB** (in major menu) .................................. touch
- **Routine** (in major menu) ................................. touch

☐ **Step 3:** Select and run the following tests:

Select **Run** to start the **Intrpt Reset** test .................. touch
Select **Reset Status**, and then **Run** to start the test .......... touch
Select **Data Lines**, and then **Run** to start the test .......... touch
Select **Interrupt**, and then **Run** to start the test .......... touch

☐ **Step 4:** _Check_ that all four of the previous tests have executed and passed. Then exit as follows:

Select **Exit** twice to exit **Extended Diagnostics** .............. touch
Vertical Reference Voltage

This procedure checks that the vertical reference voltages are at +5 V and −5 V at J63C on the A26 M/F Acquisition Interconnect board (see Figure 4-1).

This procedure should only be performed if maintenance is required.
This procedure is not necessary for verifying instrument specifications.

Specifications

The measured voltage must be within the limits of 5 V ±200 μV and −5 V ±200 μV.

Setup to Check Vertical Reference Voltage

![Diagram of setup to check vertical reference voltage]

Procedure to Check Vertical Reference Voltage

☐ **Step 1:** Initialize the CSA 803A settings as follows:

- **UTILITY button** .......................................................... press
- **Initialize** (in major menu) .......................................... touch
- **Initialize** (in verification pop-up menu) ....................... touch

☐ **Step 2:** Connect the Digital Voltmeter to the +5 V reference point and GND on the A26 Mainframe (M/F) Acquisition Interconnect board. See Figure 4-1.

☐ **Step 3:** Set the Voltmeter for DC Voltage, and check for a reading of +5 V, ±200 μV.

☐ **Step 4:** Connect the Digital Voltmeter to the −5 V reference point and GND on the A26 M/F Acquisition Interconnect board.
Step 5: Set the Voltmeter for DC Voltage, and check for a reading of 
−5 V, ±200 μV.

If the readings noted in Steps 3 or 5 are outside the stated limits, 
then servicing of the CSA 803A is required before continuing to the 
Horizontal Reference Clock procedure.

Figure 4-1: A26 M/F Acquisition Interconnect Board Test Point Locations
Horizontal Reference Clock

This procedure verifies the correct operation and accuracy of the CSA 803A’s horizontal reference clock (see Figure 4-2).

This procedure should only be performed if maintenance is required. This procedure is not necessary for verifying instrument specifications.

Specifications

The operational frequency specification for the horizontal reference clock is 200,000 kHz ±5 kHz.

Setup to Check Horizontal Reference Clock

![Diagram of CSA 803A](image)

Procedure to Check Horizontal Reference Clock

☐ **Step 1:** Initialize the CSA 803A settings as follows:

- UTILITY button ......................................................... press
- **Initialize** (in major menu) ................................. touch
- **Initialize** (in verification pop-up menu) ................. touch

☐ **Step 2:** Perform the following operations on the CSA 803A in the order listed:

- Set the front panel ON/STANDBY switch to STANDBY.
- Set the CSA 803A on its right side (as viewed from facing the front of the CSA 803A).
- Set the CSA 803A front panel ON/STANDBY switch to ON.
Performance Tests

☐ **Step 3:** Set the Frequency Counter controls/output as follows:

Frequency counter

- Mode ........................................... Frequency A
- Trigger ............................................. AC
- Slope ........................................... + (positive)
- Attenuation ...................................... 1X
- Termination ...................................... 1 MΩ

☐ **Step 4:** At U191 on the A5 Time Base/Controller board, touch the 10X Probe to pin 9 and the ground probe to pin 1.

☐ **Step 5:** Check that the frequency counter reads within the limits of 199.995 kHz and 200.005 kHz.

![Figure 4-2: A5 Time Base/Controller Board Test Point Locations](image)
Vertical Accuracy

This procedure shows the setups and lists the steps to check the vertical accuracy of the CSA 803A.

Setup to Check Vertical Gain

![Diagram of Calibration Head and Prec. Voltage Source]

Procedure to Check Vertical Gain

☐ Step 1: Install a Calibration Head (067 – 1413 – 00) into the position shown in the setup diagram (CH 1/CH 2 slot). If the unit is in Standby mode, set the power switch to ON. Set the Precision Voltage Source to 0 V and connect it to Channel 2 of the Calibration Head.

NOTE

If powering up from a cold start, the diagnostics will report an error using the Calibration Head. The report will indicate a Time Base error. To clear this, exit the diagnostics. Then, ignore the subsequent time base calibration failure notice and continue with the following steps.

☐ Step 2: Initialize the mainframe as follows:

- Utility button ................................................................. press
- Initialize (in major menu) ............................................. touch
- Initialize (in verification pop-up menu) ......................... touch

☐ Step 3: Trigger the CSA 803A as follows:

- Trigger button ............................................................... press
- Source (in major menu) .............................................. touch
- Internal Clock (in pop-up menu) .................................. touch
Step 4: Identify the trace as follows:

Def Tra icon ................................................. touch
Identify Channel (2) ................................. touch
Select Enter Desc .......................... touch

Step 5: Set the mainframe Vert Offset as follows:

Vert size icon ............................................. touch
Set Vert Size:M2 to 2 mV/div ................. adjust upper knob

Step 6: Set Averaging as follows:

Acquire Desc (in major menu) .................. touch
Average N (in pop-up menu) ................... touch

Step 7: Select the Mean Measurement as follows:

MEASURE button ................................. press
Measurements (in major menu) ................. touch
Mean (in the Measurements pop-up menu) .... touch
Compare & References (in major menu) ....... touch
Save Current Meas Values as References (in pop-up menu) . touch
Compare off (to on in pop-up menu) ........... touch

Step 8: Set the Voltage source to 8 mV.

Select Remove/Cr Trace (in major menu) ....... touch
Select Clear Trace (in pop-up menu) .......... touch

Step 9: Wait for averaging to complete. Then, check that the ΔMean value is to be within 7.8 mV (lower spec) and 8.2 mV (upper spec).

**NOTE**

Averaging will complete faster if you exit the measurement menu and then return when averaging is complete. Alternatively, use the dial to move the Main Size setting two notches higher than the default setting.

Step 10: Change the polarity of the voltage differential coming from the precision voltage Source. Check that the ΔMean value is between −7.8 mV and −8.2 mV.
**Step 11:** Refer to Table 4-3 and **check** actual results against the table specifications for the setting levels indicated.

**NOTE**

*Specifications are one percent of full scale at each volts/div setting. Example: at 5 mV/div full scale for 10 div is 50 mV, which gives an upper and lower spec tolerance of +0.5 mV and –0.5 mV.*

<table>
<thead>
<tr>
<th>Sens.</th>
<th>Source V</th>
<th>Lower Spec</th>
<th>Upper Spec</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 mV/div</td>
<td>–20 mV</td>
<td>–20.5 mV</td>
<td>–19.5 mV</td>
</tr>
<tr>
<td>10 mV/div</td>
<td>–40 mV</td>
<td>–41.0 mV</td>
<td>–39.0 mV</td>
</tr>
<tr>
<td>20 mV/div</td>
<td>–80 mV</td>
<td>–82 mV</td>
<td>–78 mV</td>
</tr>
<tr>
<td>50 mV/div</td>
<td>–200 mV</td>
<td>–205 mV</td>
<td>–195 mV</td>
</tr>
<tr>
<td>100 mV/div</td>
<td>–400 mV</td>
<td>–410 mV</td>
<td>–390 mV</td>
</tr>
<tr>
<td>200 mV/div</td>
<td>–800 mV</td>
<td>–820 mV</td>
<td>–780 mV</td>
</tr>
<tr>
<td>5 mV/div</td>
<td>20 mV</td>
<td>19.5 mV</td>
<td>20.5 mV</td>
</tr>
<tr>
<td>10 mV/div</td>
<td>40 mV</td>
<td>39.0 mV</td>
<td>41.0 mV</td>
</tr>
<tr>
<td>20 mV/div</td>
<td>80 mV</td>
<td>78 mV</td>
<td>82 mV</td>
</tr>
<tr>
<td>50 mV/div</td>
<td>200 mV</td>
<td>195 mV</td>
<td>205 mV</td>
</tr>
<tr>
<td>100 mV/div</td>
<td>400 mV</td>
<td>390 mV</td>
<td>410 mV</td>
</tr>
<tr>
<td>200 mV/div</td>
<td>800 mV</td>
<td>780 mV</td>
<td>820 mV</td>
</tr>
</tbody>
</table>

**NOTE**

*Up to now, you have been working with trace 1 (Channel 2) and internal mainframe acquisition measurement channel 1. Use the following steps to verify the vertical accuracy through internal acquisition measurement channel 2, using trace 2. (Don’t remove Voltage Source from Calibration Head Channel 2).*

**Step 12:** Initialize the mainframe as follows:

- **UTILITY** button ......................... press
- **Initialize** (in major menu) ................ touch
- **Initialize** (in verification pop-up menu) .......... touch

**Step 13:** Trigger the CSA 803A as follows:

- **TRIGGER** button ......................... press
- **Source** (in major menu) ................... touch
- **Internal Clock** (in pop-up menu) ............. touch
Performance Tests

☐ **Step 14:** Define the first trace as follows:

- **Def Tra** icon ................................. touch
- Identify Channel (1) ......................... touch
- Select **Enter Desc** ........................... touch

Note that **Trace 1** has been selected at the base of the screen (just above **M1 Main**).

☐ **Step 15:** Define the second trace as follows:

- **Def Tra** icon ................................. touch
- Identify Channel (2) ......................... touch
- Select **Enter Desc** ........................... touch

Note that **Trace 2** has now been selected at the base of the screen (just above **M2 Main**).

☐ **Step 16:** Repeat steps 5 through 12.

☐ **Step 17:** Power down the CSA 803A. Move the Calibration Head to the second slot (CH 3/CH 4) and repeat Steps 1 through 16.

---

**Setup to Check Offset Accuracy**

![Diagram of CSA 803A with Calibration Head, DIRECT Input, and Prec. Voltage Source with 50 Ω Coaxial Cable]

**Procedure to Check Offset Accuracy**

☐ **Step 1:** This second vertical accuracy test uses the same setup preliminaries as the previous test. The Calibration Head/Time Base error will only re-appear if you have activated power-up diagnostics. If so, exit diagnostics and, in either case, continue from here.

☐ **Step 2:** Initialize the mainframe as follows:

- **UTILITY** button ................................. press
- **Initialize** (in major menu) ......................... touch
- **Initialize** (in verification pop-up menu) .................. touch
Step 3: Trigger the CSA 803A as follows:

- **TRIGGER button**: press
- **Source**: (in major menu) touch
- **Internal Clock**: (in pop-up menu) touch

Step 4: Define the trace as follows:

- **Def Tra icon**: touch
- **Identify Channel (2)**: touch
- **Select Enter Desc**: touch

Step 5: Set Averaging as follows:

- **Acquire Desc**: (in major menu) touch
- **Average N**: (in pop-up menu) touch
- **Select Exit**: touch

Step 6: Select the Mean Measurement as follows:

- **MEASURE Button**: press
- **Measurements**: (in major menu) touch
- **Mean**: (in pop-up menu) touch
- **Compare & Reference**: (in major menu) touch
- **Save Current Meas Values as References**: (in pop-up menu) touch
- **Compare off**: (changes to on in pop-up menu) touch
- **Select Exit**: touch

Step 7: Set the Vertical Size and Offset as follows:

- **Vertical size icon**: touch
- **Adjust the Vert Size**: M2 to 10 mV/div adjust upper knob
- **Vert Offset**: M2 (in major menu) touch
- **Key in 400 mV**: (400m) on the pop-up display touch
- **Select Enter**: touch

Check that 400 mV has now entered into the display below **Vert Offset**: M2.

Step 8: Connect the Voltage Source to the DIRECT input of the Calibration Head.

Step 9: **Adjust** the Voltage Source to 400 mV.

Step 10: Wait for averaging to complete. Then, check that ΔMean value is between −2 mV and +2 mV.

Step 11: Repeat Steps 2 through 10 for the offset values shown in Table 4-4.

Step 12: Power-off the CSA 803A. Move the Calibration Head to the second slot (CH 3/CH 4) and repeat Steps 1 through 11.
### Table 4-4: Vertical Offset Test Values

<table>
<thead>
<tr>
<th>Sens.</th>
<th>Source V/Vert Offset</th>
<th>Lower Spec</th>
<th>Upper Spec</th>
</tr>
</thead>
<tbody>
<tr>
<td>10 mV/div</td>
<td>1 V</td>
<td>0.998 V</td>
<td>1.002 V</td>
</tr>
<tr>
<td>10 mV/div</td>
<td>2 V</td>
<td>1.998 V</td>
<td>2.002 V</td>
</tr>
<tr>
<td>10 mV/div</td>
<td>−400 mV</td>
<td>−402 mV</td>
<td>−398 mV</td>
</tr>
<tr>
<td>10 mV/div</td>
<td>−1 V</td>
<td>−1.002 V</td>
<td>−0.998 V</td>
</tr>
<tr>
<td>10 mV/div</td>
<td>−2 V</td>
<td>−2.002 V</td>
<td>−1.998 V</td>
</tr>
</tbody>
</table>
System Vertical RMS Noise

This procedure uses the RMS measurement function to measure the noise on the trace from a sampling head compartment.

Setup to Examine Vertical RMS Noise

Procedure to Examine Vertical RMS Noise

☐ Step 1: Install the Calibration Head (067–1413–00) into the position shown in the setup diagram. If the unit was in standby mode, set the ON/STANDBY switch to ON.

**NOTE**

*If powering up from a cold start, the diagnostics will report an error using the Calibration Head. The report will indicate a Time Base error. To clear this, exit the diagnostics. Then, ignore the subsequent time base calibration failure notice and continue with the following steps.*

☐ Step 2: Initialize the mainframe as follows:

- UTILITY button ................................................. press
- **Initialize** (in major menu) .............................. touch
- **Initialize** (in verification pop-up menu) ............... touch

☐ Step 3: Trigger the CSA 803A as follows:

- TRIGGER button ............................................. press
- **Source** (in major menu) ................................. touch
- **Internal Clock** (in pop-up menu) ..................... touch

☐ Step 4: Identify the trace as follows:

- **Def Tra** icon ................................................. touch
- Identify Channel (1) ........................................ touch
- Select **Enter Desc** ....................................... touch
**Step 5:** Set the mainframe Vert Size as follows:

Vert Size icon ................................. touch
Set Vert Size:M1 to 2 mV/div .......... adjust upper knob

**Step 6:** Set the record length as follows:

**Horizontal Desc** (in major menu) ................................. touch
**Main Record Length** (in pop-up menu) ................................. touch
Set Main Record Len to 5120 points .......... adjust upper knob

**Step 7:** Store the trace as follows:

STORE/RECALL button ................................. press
**Store Trace** (in major menu) ...................... touch
**Trace 1** (in pop-up menu) ...................... touch

Note that you must touch Trace 1 even though it is highlighted in the menu.

**Recall Trace** (in major menu) ...................... touch
**STO 1** (in pop-up menu) ...................... touch

**Step 8:** Measure the Mean value as follows:

MEASURE button ................................. press
**Measurements** (in major menu) ...................... touch
**Mean** (in pop-up menu) ...................... touch
**Exit Menu** (in pop-up menu) ...................... touch

**NOTE**

Record (write down) the mean value for use in the next step.

**Step 9:** Define the trace to be stored as follows:

**Def Tra** icon ................................. touch
**Stored Traces** (in pop-up menu) ...................... touch
**Stored 1** (in pop-up menu) ...................... touch
Enter STO1 – (mean value) ...................... touch

Use the pop-up key pad to enter the STO1 – (mean value) recorded in Step 8.

**NOTE**

*For example, if mean value is 50.2 µV, you would key in “–(50.2 EEX – 6)”. STO1 already appears on upper left of display. Exponents are entered by pressing the EEX key, followed by the sign of the exponent (if negative), followed by the exponent value.*
Enter Desc (in pop-up menu) ............................ touch

☐ Step 10: Measure the RMS value as follows:

- MEASURE button ................................. press
- Measurements (in major menu) ................. touch
- RMS (in pop-up menu) ............................ touch

Check that RMS is \( \leq 200 \, \mu V \).
- Exit Menu (to exit) ................................. touch

☐ Step 11: Erase the test traces as follows:

- STORE/RECALL button .......................... press
- Delete Trace (in major menu) ..................... touch
- All Traces (in pop-up menu) ...................... touch
- Delete Selected Traces (in pop-up menu) ....... touch

☐ Step 12: Repeat Steps 4 through 11 at the sensitivities listed in Table 4-5 and check the resulting RMS against the matching specification value in the table.

<table>
<thead>
<tr>
<th>Sensitivity</th>
<th>Upper Limit</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 mV/div</td>
<td>500 ( \mu V )</td>
</tr>
<tr>
<td>10 mV/div</td>
<td>1 mV</td>
</tr>
<tr>
<td>20 mV/div</td>
<td>632 ( \mu V )</td>
</tr>
<tr>
<td>50 mV/div</td>
<td>1.58 mV</td>
</tr>
<tr>
<td>100 mV/div</td>
<td>3.16 mV</td>
</tr>
<tr>
<td>200 mV/div</td>
<td>6.32 mV</td>
</tr>
</tbody>
</table>

☐ Step 13: Power-off the CSA 803A. Move the calibration head to the second slot (CH3/CH4) and repeat steps 1-12.
Sweep Rate Accuracy

This procedure shows the setups and lists the steps to check the Sweep Rate Accuracy.

Setup to Examine Sweep Rate Accuracy

![Diagram of setup for Sweep Rate Accuracy](image)

Procedure to Examine Sweep Rate Accuracy

- **Step 1**: Install the SD-24 Sampling Head into the compartment shown in the setup diagram (CH 1/CH 2 slot). If the unit was in standby mode set the ON/STANDBY switch to ON.

- **Step 2**: Initialize the mainframe as follows:
  
  -Press Utility button .............................................
  -Touch Initialize (in major menu) .........................
  -Touch Initialize (in verification pop-up menu)

- **Step 3**: Set the horizontal record length as follows:
  
  -Touch Horizontal Desc (in major menu) ...........
  -Touch Main Record Length (in pop-up menu) ...........
  -Set Main Record Len to 1024 points ............... adjust upper knob

- **Step 4**: Identify the trace as follows:
  
  -Touch Def Tra icon ...........................................
  -Touch Identify Channel (1) ............................
  -Touch Select Enter Desc .................................
Step 5: Engage high precision calibration mode as follows:

- **UTILITY button** .......................................................... press
- **Page to Enhanced Accuracy** ........................................... touch
- **Time Base Cal Mode** (in major menu) ......................... touch
- **High Prec** (in pop-up menu) ........................................ touch
- **Exit** (in pop-up menu) ................................................ touch

**Sweep Rate Accuracy 2 ns/div**

Step 6: Adjust the Sweep Rate to 2 ns/div.

- **Horizontal** icon .......................................................... touch
- **Set Main Size** to 2 ns/div .......................................... adjust upper knob

Step 7: Adjust the Signal Generator to the following settings:

- **Frequency** .............................................................. 55 MHz
- **Amplitude** ............................................................. $1.0 \text{V}_{\text{RMS}}$

*NOTE*

*Check that selected Sampling Head channel (1) indicator is flashing. If not, select channel (1) by pressing select button.*

Step 8: Turn mainframe averaging on.

- **WAVEFORM button** .................................................... press
- **Acquire Desc** (in major menu) .................................... touch
- **Average N On** (in pop-up menu) ................................. touch
- **Select Exit** (in the pop-up menu) ............................... touch

*NOTE*

*Position the display so the sine wave is centered on the screen. To ensure accurate period measurement, the display must be a full cycle.*

Step 9: Obtain Period as follows:

- **MEASURE button** ..................................................... press
- **Measurement** (in major menu) ................................. touch
- **Period** (in pop-up menu) ......................................... touch
- **Exit Menu** (in pop-up menu) ................................. touch

Step 10: Examine that the period is between 18.172 ns and 18.192 ns, showing that the sweep rate accuracy is within 0.05%.
Sweep Rate Accuracy 1 ns/div

☐ **Step 11:** *Adjust* the Sweep Rate to 1 ns/div.

Horizontal (↔) icon ........................................ touch
Set **Main Size** to 1 ns/div .......................... adjust upper knob

☐ **Step 12:** *Adjust* the Signal Generator to the following settings:

Frequency ....................................................... 110 MHz
Amplitude ..................................................... 1.0 V<sub>RMS</sub>

☐ **Step 13:** Press the UTILITY button and *adjust* the lower knob for a display showing a full waveform.

☐ **Step 14:** Press the MEASURE button and *check* for a period interval between 9.083 ns and 9.098 ns, showing that the sweep rate accuracy is within 0.08%.

Sweep Rate Accuracy 100 ps/div

☐ **Step 15:** Use the upper control knob to adjust the **Main Size** to 100 ps/div.

☐ **Step 16:** *Adjust* the Signal Generator to the following settings:

Frequency ....................................................... 1.1 GHz
Amplitude ..................................................... 2.0 V<sub>P-P</sub> (1.4 V<sub>RMS</sub>)
(Set for 1.000 ±0.004 V<sub>P-P</sub> on screen.)

☐ **Step 17:** Press the UTILITY button and *adjust* the lower knob for a display showing a full waveform.

☐ **Step 18:** Press the MEASURE button and *check* for a period interval between 902 ps and 916 ps, showing that the sweep rate accuracy is within 0.8%.

Sweep Rate Accuracy 10 ps/div

☐ **Step 19:** *Adjust* the Signal Generator to the following settings:

Frequency ....................................................... 800 MHz
Amplitude ..................................................... 2.0 V<sub>P-P</sub> (1.4 V<sub>RMS</sub>)
(Set for 1.000 ±0.004 V<sub>P-P</sub> on screen.)

☐ **Step 20:** Invoke smoothing as follows:

WAVEFORM button ........................................ press
Sampling Head Fnc’s (in major menu) .................. touch
Smoothing On (in pop-up menu) ......................... touch
Exit (in pop-up menu) ..................................... touch

☐ **Step 21:** *Adjust* the **Main Size** to 1130 ps/div.
Step 22: Adjust the Main Pos to 55 ns.

Step 23: Set the Main Pos control (lower knob) so that the zero crossing of the waveform occurs on the center graticle.

Step 24: Set the horizontal reference point to Center as follows, so that the waveform will be expanded about the horizontal center:

WAVEFORM button ................................................. press
Horizontal Desc (in major menu) ...................... touch
Center (in pop-up menu) ................................. touch

Step 25: Adjust the Vertical Size as follows:

Vertical icon ..................................................... touch
Set Vert Size to 50 mV ................. adjust upper knob

Step 26: Adjust the Main Size as follows:

Horizontal icon ................................................. touch
Set the Main Size to 10 ps/div. .......... adjust upper knob

Step 27: Activate the cursors as follows:

Cursors icon ..................................................... touch

Step 28: Read the Δv located in the major menu. Δv should be within −260.5 mV and −248.1 mV or +248.1 mV and +260.5 mV, showing that the sweep rate accuracy is within 2.5%.

Step 29: Touch Exit (in the major menu).

Sweep Rate Accuracy 1 ps/div

Step 30: Adjust the Signal Generator to the following settings:

Frequency ...................................................... 800 MHz
Amplitude ..................................................... 2.0 Vp-p (1.4 VRMS)
(Set for 1.000 ±0.004 Vp-p on screen.)

Step 31: Invoke smoothing as follows:

WAVEFORM button ................................................. press
Sampling Head Fnc’s (in major menu) ............ touch
Smoothing On (in pop-up menu) ..................... touch
Exit (in pop-up menu) ................................. touch

Step 32: Adjust the Main Size to 130 ps/div.

Step 33: Adjust the Main Pos to 55 ns.

Step 34: Set the Main Pos control (lower knob) so that the zero crossing of the waveform occurs on the center graticle.
Step 35: Set the horizontal reference point to Center as follows, so that the waveform will be expanded around the horizontal center:

WAVEFORM button ................................. press
Horizontal Desc (in major menu) ........................ touch
Center (in pop-up menu) .............................. touch

Step 36: Adjust the Vertical Size as follows:

Vertical icon ................................. touch
Set Vert Size to 5 mV .................. adjust upper knob

Step 37: Set the Main Size as follows:

Horizontal icon ................................. touch
Set Main Size to 1 ps/div .................. adjust upper knob

Step 38: Turn the mainframe Average on.

WAVEFORM button ................................. press
Acquire Desc (in major menu) ........................ touch
Average N (in pop-up menu) .................... touch
Select Exit (in pop-up menu) .................... touch

Step 39: Activate the cursors as follows:

Cursors icon ................................. touch

Step 40: Read the Δv located in the major menu. Δv should be within –28.3 mV and –23.1 mV, or within +23.1 mV and +28.3 mV, showing that the sweep rate accuracy is within 10%.

Step 41: Touch Exit (in the major menu).
**Triggering, External Direct**

This procedure verifies the correct operation and accuracy of the CSA 803A’s trigger system.

**Specifications**

The specifications for triggering using the external trigger are as follows:

- 100 mV_{pp} at 300 MHz
- 100 mV_{pp} at 1000 MHz
- 100 mV_{pp} at 3.0 GHz

**Setup to Check Triggering**

![Schematic diagram of trigger setup]

**Procedure to Check Triggering**

- **Step 1**: Install the SD-24 Sampling Head into the position shown in the setup diagram (CH 1/CH 2 slot). If the unit was in standby mode, set the ON/STANDBY switch to ON.

- **Step 2**: Initialize the mainframe as follows:
  
  - Press the UTILITY button.
  - Touch Initialize (in major menu).
  - Touch Initialize (in verification pop-up menu).

- **Step 3**: Adjust the high frequency generator to 400 mV_{pp} at 300 MHz.

- **Step 4**: On the Sampling Head, press the Channel 1 select button.
Step 5: Make the following selections:

- AUTOSET button ........................................... press
- Slightly adjust the Trigger Level (in Trigger major menu), if necessary
- MEASURE button ........................................... press
  - Measurement (in major menu) ......................... touch
  - Peak-Peak (in pop-up menu) ......................... touch
- WAVEFORM button .......................................... press
  - Sampling Head Fnc’s (in major menu) ........... touch
  - Smoothing On (in pop-up menu) ................. touch
  - Exit (in pop-up menu) ............................. touch

Step 6: Check waveform for stable triggering. Using AUTOSET, repeat this procedure for the following frequency generator settings:

- 400 mV_p-p at 1000 MHz
- 400 mV_p-p at 3.0 GHz
**Prescaler Triggering**  
This procedure verifies the correct operation and accuracy of the CSA 803A’s Prescaler trigger system.

**Specifications**  
The specifications for Prescaler triggering are as follows:
- 600 mV<sub>p-p</sub> at 2 GHz
- 600 mV<sub>p-p</sub> at 8 GHz
- 2 V<sub>p-p</sub> at 10 GHz

**Setup to Check Prescaler Triggering**

![Diagram of setup](image)

**Procedure to Check Prescaler Triggering**

- **Step 1**: Install the SD-24 Sampling Head into the CH 1/CH 2 slot of the mainframe. Set the ON/STANDBY switch to ON and let the instrument warm up for approximately 15 minutes. Initialize the mainframe settings, then perform the following settings and steps.

- **Step 2**: Connect the High Frequency Generator to the Picosecond Pulse Labs (PSPL) 10X Pick-off IN. Connect the PSPL ÷ 10 output to Channel 1 of the Sampling Head.
Step 3: Connect the PSPL X1 output to the power meter/sensor (meter/sensor must be calibrated). Set the Generator frequency to 2 GHz.

Adjust the Generator output until the power meter reads:

\[-0.458 \text{ dBm (600 mV}_{p-p}\). Use correction factors for the sensor.\]

Step 4: Connect the PSPL X1 output to the CSA 803A Prescaler Trigger input.

Step 5: CSA 803A mainframe settings:

- **DefTra** .................................................. touch
- Select Channel 1, M1 .................................. touch
- TRIGGER button .......................................... press
- **Source** .................................................. touch
- **External Prescaler** .................................... touch
- Exit .............................................................. touch
- Horizontal (\(\Rightarrow\)) icon ................................ touch
- Adjust **Main Size** to 200 ps/div .................... adjust upper knob
- Vertical (\(\uparrow\)) icon .................................. touch
- Adjust **Main Size** to 10 mV/div .................... adjust upper knob

Step 6: Turn AVG ON. Check display for stable triggering. Then turn the AVG OFF.

Step 7: Repeat steps 3, 4, 5 and 6 for the following settings:

<table>
<thead>
<tr>
<th>Table 4-6: Prescaler Test Settings</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Generator Freq</strong></td>
</tr>
<tr>
<td>---------------------</td>
</tr>
<tr>
<td>8 GHz</td>
</tr>
<tr>
<td>10 GHz</td>
</tr>
</tbody>
</table>
Internal Clock

This procedure verifies the correct operation and accuracy of the CSA 803A’s Internal Clock signal.

Measurement Limits

The measurement limits of the internal clock pulse are as follows:

- rise time $\leq 2.5$ ns
- frequency of 100 kHz $\pm 3\%$ accuracy
- duty cycle $50\% \pm 3\%$

Setup to Examine Internal Clock

![Diagram of CSA 803A]

Procedure to Examine Internal Clock

☐ **Step 1:** Install the SD-24 Sampling Head into the position shown in the setup diagram (CH 1/CH 2 slot). If the unit was in standby mode, set the ON/STANDBY switch to ON.

☐ **Step 2:** Initialize the mainframe as follows:

- UTILITY button .................................................. press
- Initialize (in major menu) ................................. touch
- Initialize (in verification pop-up menu) .......... touch

☐ **Step 3:** Trigger the CSA 803A as follows:

- TRIGGER Button .............................................. press
- Source (in pop-up menu) .................. Internal Clock

☐ **Step 4:** On the Sampling Head, press the Channel 1 select button.
Performing Tests

- **Step 5**: Set up the CSA 803A as follows:
  - **UTILITY** button ........................................ press
  - **Instrument Options** (in major menu) ............... touch
  - **Edge Mode** (in pop-up menu) ...................... touch

- **Step 6**: On the CSA 803A, press the AUTOSET button.

- **Step 7**: Check the rise time as follows:
  - **MEASURE** button ................................. press
  - **Measurements** (in the major menu) .......... touch
  - **Rise** (in the pop-up menu) .................. touch
  - Check that **Rise** is ≤ 2.5 ns.
  - **Exit Menu** (in pop-up menu) .............. touch

- **Step 8**: Change the sweep rate as follows:
  - Horizontal (↔) icon ................................ touch
  - Adjust **Main Size** to 5 μs/div. .............. adjust upper knob

- **Step 9**: Check the frequency as follows:
  - **MEASURE** button ............................... press
  - **Measurements** (in major menu) .......... touch
  - **Frequency** (in pop-up menu) .............. touch
  - **Duty Cycle** (in pop-up menu) .......... touch
  - Check that the frequency is between 97 kHz and 103 kHz (100 kHz ±3%).
  - Check that the Duty Cycle is between 47% and 53% (50% ±3%).
  - **Exit Menu** (in pop-up menu) .......... touch
Calibrator Output

This procedure verifies the correct operation and accuracy of the 
CSA 803A’s Calibrator.

Measurement Limits

The measurement limits of the calibrator are as follows:

- rise time ≤ 250 ps
- 250 mV ±15%

Setup to Examine Calibrator

![Calibrator Output](image)

Procedure to Examine Calibrator

- **Step 1:** Install the SD-24 Sampling Head into the position shown in the 
  setup diagram (CH 1/CH 2 slot). If the unit was in standby mode, set the 
  ON/STANDBY switch to ON.

- **Step 2:** Initialize the mainframe as follows:
  
  UTILITY button .................................................. press
  
  **Initialize** (in major menu) ................................. touch
  
  **Initialize** (in verification pop-up menu) ............... touch

- **Step 3:** Trigger the CSA 803A as follows:

  TRIGGER Button ................................................ press
  
  **Source** (in pop-up menu) ............................... Touch
  
  **Internal Clock** ............................................. Touch

- **Step 4:** On the Sampling Head, press the Channel 1 select button.

- **Step 5:** Set up the CSA 803A as follows:

  UTILITY Button .................................................. press
  
  **Instrument Options** (in major menu) ................... Touch
  
  **Edge Mode** (in pop-up menu) ....................... Touch
Performance Tests

- **Step 6**: On the CSA 803A, press the AUTOSET button.

- **Step 7**: Check the rise time and peak-to-peak amplitude as follows:

  MEASURE button ................................. press
  Measurements (in the major menu) ............ touch
  Peak-Peak (in the pop-up menu) ............... touch
  Rise (in the pop-up menu) ....................... touch
  Rise (in the major menu) ....................... touch
  Proximal (in the pop-up menu) ............... touch

  Adjust Proximal to 20% and Distal to 80%.
  Check that Rise is ≤250 ps.
  Check that peak-to-peak amplitude is within 225 mV and 275 mV
  (250 mV ± 10%).
Adjustments

This section contains procedures to check electrical specifications, to examine measurement limits, and to manually set all internal adjustments listed in Table 5-1. Use these procedures to return the CSA 803A to specified operation following repair or as part of a comprehensive performance test procedure to verify that the CSA 803A meets specifications. To adjust the CSA 803A, simply perform the procedures listed in this section. The Measurement Limits are given at the beginning of each procedure. Functional tests are included in the Performance Verification section. Refer to the CSA 803A Communications Signal Analyzer User Manual for more information about specifications and CSA 803A operation. The Setup in each procedure provides information concerning test equipment setup or interconnection. Refer to Table 5-2 for more information concerning test equipment used in the setups.

Most Adjustment and Performance Verification procedures can be run in any order. However, the Sampling Head Calibration must always precede other procedures which use an operational sampling head. Also, if different sampling heads are used, then sampling head calibration is required for each additional sampling head.
## Table 5-1: Measurement Limits and Adjustments

<table>
<thead>
<tr>
<th>Procedure Description</th>
<th>Measurement Limits <em>(Examine)</em></th>
<th>Adjustments <em>(Adjust)</em></th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Power Supply</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Voltage Supply</td>
<td>+4.85 V to +5.25 V</td>
<td>none</td>
</tr>
<tr>
<td>Voltage Reference</td>
<td>+5.15 V to +5.25 V</td>
<td>R800 +5.2 V Ref for +5.20 V</td>
</tr>
<tr>
<td>Regulator Reference</td>
<td>+9.95 V to +10.05 V</td>
<td>R730 +10 V Ref for +10.00 V</td>
</tr>
<tr>
<td><strong>Display</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Cutoff</td>
<td>visible</td>
<td>SCREEN, on transformer on A8 CRT Driver board, until display appears</td>
</tr>
<tr>
<td>Convergence</td>
<td>primary colors are not separated in the white grid</td>
<td>CONVERGENCE, R210, for optimum convergence of red, green, and blue.</td>
</tr>
<tr>
<td>Focus</td>
<td>focused grid pattern</td>
<td>FOCUS, on transformer on A8 CRT Driver board, for optimum focus on white grid pattern.</td>
</tr>
<tr>
<td>Vertical Size and Position</td>
<td>align with tic marks</td>
<td>VERT SIZE, L321; and VERT POS, R311; for optimum alignment</td>
</tr>
<tr>
<td>Horizontal Size, Linearity and Position</td>
<td>align with tic marks and for optimum appearance</td>
<td>H-SIZE, R501; H-LIN, R502; and H-POS, R500; for optimum alignment and linearity</td>
</tr>
<tr>
<td>Gray Scale</td>
<td>white at the top of the display, gray at the bottom, and the right side of the display is cut off</td>
<td>SCREEN, on transformer on A8 CRT Driver board; RED, R200; GREEN, R201; and BLUE, R203, for cutoff and color balance</td>
</tr>
<tr>
<td>Color Impurity</td>
<td>no severe color impurities in red, green, and blue display</td>
<td>cycle power on and off</td>
</tr>
<tr>
<td><strong>Real Time Clock</strong></td>
<td>1,000,000 μs ±5 μs</td>
<td>Real Time Clock for 1,000,000 μs</td>
</tr>
</tbody>
</table>
# Test Equipment

Table 5-2 (Test Equipment), contains suggested test equipment for use in this section. Procedure steps are based on the test equipment examples given, but you may substitute other equipment with similar specifications. The use of different equipment may alter test results, setup information, and related connectors and adapters.

<table>
<thead>
<tr>
<th>Description</th>
<th>Minimum Specification</th>
<th>Examples of Applicable Test Equipment</th>
</tr>
</thead>
<tbody>
<tr>
<td>Digital Voltmeter (w/test leads)</td>
<td>$\leq 0.005%$ Accuracy</td>
<td>FLUKE 8842A Digital Voltmeter</td>
</tr>
<tr>
<td>Frequency Counter</td>
<td>One Part in 1,000,000 Accuracy</td>
<td>Tektronix DC 5010 Universal Counter/Timer with a TM 5000-Series Power Module</td>
</tr>
<tr>
<td>Test Terminal</td>
<td>any GPIB (IEEE-1978) controller, or ASCII terminal equipped with an RS-232-C port. Requires compatible RS-232-C serial interface cable</td>
<td>IBM compatible PC with terminal emulation software</td>
</tr>
<tr>
<td>Coaxial Cable, 50 Ω (3 required)</td>
<td>50 Ω, 36-inch, male BNC connectors</td>
<td>Tektronix Part 012–0482–00</td>
</tr>
<tr>
<td>Coaxial Cable, RF</td>
<td>RF cable, 12 in., SMA connectors</td>
<td>Tektronix Part 174–1364–00</td>
</tr>
<tr>
<td></td>
<td>RF cable, 8.5 in., SMA connectors</td>
<td>Tektronix Part 174–1120–00</td>
</tr>
<tr>
<td>Adapters</td>
<td>BNC female-to-male Dual Banana</td>
<td>Tektronix Part 103–0090–00</td>
</tr>
<tr>
<td></td>
<td>BNC male-to-female Dual Banana</td>
<td>Tektronix Part 103–0035–00</td>
</tr>
<tr>
<td></td>
<td>SMA male-to-BNC female (8 required)</td>
<td>Tektronix Part 015–1018–00</td>
</tr>
<tr>
<td></td>
<td>SMA female-to-BNC male</td>
<td>Tektronix Part 013–0126–00</td>
</tr>
<tr>
<td></td>
<td>SMA male-to-N male</td>
<td>Tektronix Part 015–0369–00</td>
</tr>
<tr>
<td>Attenuator, 10X</td>
<td>20 dB attenuation, 50 Ω, one male and one female</td>
<td>Tektronix Part 011–0059–02</td>
</tr>
</tbody>
</table>
Table 5-2: Test Equipment (Cont.)

<table>
<thead>
<tr>
<th>Description</th>
<th>Minimum Specification</th>
<th>Examples of Applicable Test Equipment</th>
</tr>
</thead>
<tbody>
<tr>
<td>Attenuator, 2X</td>
<td>50 Ω, SMA, one male and one female</td>
<td>Tektronix Part 015–1001–00</td>
</tr>
<tr>
<td>Power Supplies Troubleshooting Fixture</td>
<td></td>
<td>Tektronix 067–1264–00 Extended Diagnostics</td>
</tr>
<tr>
<td></td>
<td></td>
<td>11000-Series Power Supplies troubleshooting fixture</td>
</tr>
<tr>
<td>Probe, 10X</td>
<td>Attenuation 10X</td>
<td>Tektronix P6106A</td>
</tr>
<tr>
<td>Pickoff, 10X</td>
<td></td>
<td>Picosecond Pulse Labs 5520A</td>
</tr>
<tr>
<td>Power Meter</td>
<td></td>
<td>HP 436A</td>
</tr>
<tr>
<td>Power Sensor</td>
<td></td>
<td>HP 8485A</td>
</tr>
<tr>
<td>Alignment Tool</td>
<td>Plastic hex</td>
<td>Tektronix Part 003–0301–00</td>
</tr>
<tr>
<td></td>
<td>Insulated slot</td>
<td>Tektronix Part 003–0675–01</td>
</tr>
<tr>
<td></td>
<td>Square Tip (ceramic)</td>
<td>Tektronix Part 003–1400–00</td>
</tr>
<tr>
<td>Magnetic Screwdriver</td>
<td>Holder for Torx head tips</td>
<td>Tektronix Part 003–0293–00</td>
</tr>
<tr>
<td>Torx Head Screwdriver</td>
<td>#10 tip</td>
<td>Tektronix Part 003–0814–00</td>
</tr>
<tr>
<td></td>
<td>#15 tip</td>
<td>Tektronix Part 003–0966–00</td>
</tr>
<tr>
<td></td>
<td>#20 tip</td>
<td>Tektronix Part 003–0866–00</td>
</tr>
<tr>
<td>External Loopback Connector</td>
<td>RS-232-C connector</td>
<td>Tektronix Part 013–0198–00</td>
</tr>
<tr>
<td>Shorting Strap</td>
<td>two alligator clips on a short pigtail conductor</td>
<td></td>
</tr>
<tr>
<td>Integrated Circuit Extracting Tool</td>
<td>IC Insertion-Extraction Pliers, 28-pin type</td>
<td>General Tool P/N U505BG or equivalent</td>
</tr>
<tr>
<td>Description</td>
<td>Minimum Specification</td>
<td>Examples of Applicable Test Equipment</td>
</tr>
<tr>
<td>----------------------</td>
<td>--------------------------------------------</td>
<td>---------------------------------------</td>
</tr>
<tr>
<td>Board Removal Tools</td>
<td>Straight-slot screw-driver, large</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Torx-drive screw-driver, T-7, T-8, T-10, T-15, T-20, T-25</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Allen (hex) Wrench, 1/16-inch</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Nutdrivers, 3/16-inch, 1/4-inch, 7/16-inch</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Needle-nose pliers</td>
<td></td>
</tr>
<tr>
<td>Small Ruler</td>
<td>half inch rulings</td>
<td></td>
</tr>
<tr>
<td>Antistatic wrist strap</td>
<td>Tektronix Part 006–3415–04</td>
<td></td>
</tr>
</tbody>
</table>
Using These Procedures

Some procedures begin with a setup illustration that shows what test equipment is needed and how to connect it. The other procedures require only a calibrated SD-Series Sampling Head. Refer to Table 5-2 (Test Equipment) on the preceding pages for an example of the test equipment for each procedure.

Conventions in this Manual

In these procedures, the following conventions are used:

- **CAPITAL** letters within the body of text identify front panel controls, indicators, and connectors on the CSA 803A (for example, MEASURE) and sampling head.
- **Bold** letters identify menu labels and display messages.
- Initial **Capital** letters identify connectors, controls, and indicators (for example, On) on associated test equipment.
- In some steps, the first word is italicized to identify a step that contains a performance verification and an adjustment instruction. For example, if Check is the first word in the title of a step, an electrical specification is checked. If Adjust appears in the title, the step involves an electrical adjustment. If Examine is the first word in the title, the step concerns measurement limits that indicate whether the CSA 803A is operating properly; these limits are not to be interpreted as electrical specifications.

Menu Selections and Measurement Techniques

Details on measurement techniques and instructions for making menu selections are generally not included in these procedures. Comprehensive descriptions of menus and CSA 803A features are located in the CSA 803A Communications Signal Analyzer User Manual.

User Manual

Reviewing the CSA 803A Communications Signal Analyzer User Manual is strongly recommended to familiarize the first-time user with CSA 803A controls and features.
Power Supply

This procedure shows the setup and lists the steps to examine the Measured Voltage Supply and to check and adjust the Voltage Reference and the Regulator Reference (see Figures 5-1, 5-2, and 5-3).

This procedure should only be performed if the instrument is out of measurement limits and maintenance is required. If the CSA 803A is already within limits, proceed to the Display adjustment procedure.

Measurement Limits

The measurement limits for this procedure are as follows:

- Measured Voltage Supply limits must be within +4.85 V and +5.25 V
- Voltage Reference must be within +5.15 V and +5.25 V
- Regulator Reference must be within +9.95 V and +10.05 V

Setup to Examine Voltage Supply

![CSA 803A Diagram]

Procedure to Examine Voltage Supply

☐ **Step 1**: Set the CSA 803A ON/STANDBY switch to ON, and initialize as follows:

- Utility button ................................................................. press
- Initialize (in major menu) ................................................. touch
- Initialize (in verification pop-up menu) ........................... touch

☐ **Step 2**: With the CSA 803A top and bottom covers removed, refer to Section 3 and locate the A18 Memory circuit board.

☐ **Step 3**: Connect the digital multimeter to TP200 and TP300 as indicated in the setup illustration (see also Figure 5-1).
Step 4: Check that the Digital Voltmeter reads within the limits of +4.85 V and +5.25 V.

Figure 5-1: A18 Memory Board Test Point Locations
Setup to Examine/Adjust Voltage Reference

This procedure should only be performed if maintenance is required. This is not necessary for verifying instrument specifications.

Procedure to Examine/Adjust Voltage Reference

☐ **Step 1:** Perform the following settings in the order listed:

a. Set the front panel ON/STANDBY switch to STANDBY and the rear panel PRINCIPAL POWER SWITCH to OFF. Disconnect the CSA 803A from the power source.

b. Remove the Power Supply module following the procedure listed under Power Supply Module Removal/Replacement in the Maintenance Section.

c. Create a short between test points TP830 and TP831 on the A2A2 Control Rectifier board using a shorting strap. See Figure 5-2.

d. Connect the CSA 803A Power Supply module to a suitable line power source.

e. Set the rear panel PRINCIPAL POWER SWITCH to ON.

☐ **Step 2:** With the Digital Voltmeter set to DC Voltage and connected as indicated in the setup diagram, check that the multimeter reads within the limits of +5.15 V and +5.25 V.

DO NOT attempt to change the following adjustment setting if the reading is within the stated limits. Instead, proceed to Step 4.

---

**WARNING**

To prevent electric shock, use extreme caution when making the following adjustment.
Adjustments

- **Step 3**: Adjust the +5.2 V Ref, R800, on the A2A2 Control Rectifier board to +5.20 V.
- **Step 4**: Remove the Digital Voltmeter leads from the test points.
- **Step 5**: Set the rear panel PRINCIPAL POWER SWITCH to OFF.
- **Step 6**: Disconnect the CSA 803A from the power source.
- **Step 7**: Remove all test leads and the TP830/831 shorting strap.
- **Step 8**: Replace the Power Supply module using the instructions in the Maintenance Section.
- **Step 9**: Set the rear panel PRINCIPAL POWER SWITCH to ON, and the front panel ON/STANDBY switch to ON.

![Diagram of A2A2 Control Rectifier Board Test Point and Adjustment Locations](image)

*Figure 5-2: A2A2 Control Rectifier Board Test Point and Adjustment Locations*
Setup to Examine/Adjust Regulator Reference

**Procedure to Examine/Adjust Regulator Reference**

- **Step 1:** Make the connections shown in the setup and Figure 5-3 diagrams. Check that the CSA 803A power is ON.

- **Step 2:** With the Digital Voltmeter in DC Voltage mode, check the Voltmeter for a reading within the limits of +9.95 V and +10.05 V.

  DO NOT attempt to make the following adjustment to R730 if the reading is within the stated limits. Instead, proceed to Step 4.

  **WARNING**

  To prevent electric shock, use extreme caution when making the following adjustment. Access the test points from the right side of the oscilloscope.

- **Step 3:** Adjust the +10 V Ref, R730, on the A4 Regulator board to +10.00 V.

- **Step 4:** Remove the test leads.

- **Step 5:** Initiate Power-On Diagnostics (see Performance Verification section).
Figure 5-3: A4 Regulator Board Test Point and Adjustment Locations
Display

This procedure shows the setup and lists the steps to examine and adjust the A7 CRT Socket board and the A8 CRT Driver board (see Figures 5-4 and 5-5).

The adjustments in this procedure only affect the visual aspects of the CRT display and you should only perform these adjustments when the CRT, A7 CRT Socket board, or A8 CRT Driver board components are replaced. These adjustments do not affect CSA 803A accuracy since all measurements are made on the acquired data, not the displayed data. Unless alignment or brightness difficulties are apparent, proceed to the Real Time Clock adjustment procedure.

For all Examine steps in this procedure, if the display parameter examined is within the stated limits, then do not perform the Adjust step following that Examine step. Instead, proceed to the step following the Adjust step.

Measurement Limits

The measurement limits are set on the CRT as follows:

- The display must be visible (not cut off).
- The red, green, and blue traces must not be separated.
- Focus is adjusted for minimum line width.
- Vertical size is adjusted to align the corners of the grid pattern with the tic marks on the edges of the front panel bezel.
- Horizontal size is adjusted to align the corners of the grid pattern with the tic marks on the top and bottom edges of the front panel bezel, and the horizontal linearity is adjusted for uniform grid box length.
- Horizontal linearity is adjusted for optimum appearance using an internally generated grid pattern.
- Red, green, and blue colors must have optimum white to gray scale linearity.
- **Red Display, Green Display,** and **Blue Display** in Extended Diagnostics must not contain severe color impurities.
Setup to Examine/Adjust the Display

 CSA 803A

Procedure to Examine/Adjust the Display

 WARNING

To prevent electric shock, use extreme caution when performing the following adjustment.

☐ Step 1: Perform the following settings in the order listed:

 CSA 803A
 ON/STANDBY ............................. STANDBY

☐ Step 2: Remove the top and bottom cabinet panel covers.

☐ Step 3: Remove the three screws that secure the CRT cover, and then remove the cover.

☐ Step 4: Remove the two screws that secure the cover that shields the A7 CRT Socket board (CRT Socket board cover).

☐ Step 5: Set the ON/STANDBY switch to ON.

☐ Step 6: Examine that the display is visible.

☐ Step 7: Adjust SCREEN, located on the transformer mounted to the A8 CRT Driver board, clockwise until the display appears.

☐ Step 8: Press the UTILITY button.

☐ Step 9: Touch Extended Diagnostic, then touch Extended Diagnostic in the Verify Diagnostics pop-up menu.

☐ Step 10: Touch Block and then Front Panel.

☐ Step 11: Touch Area and then Test Pattern.

☐ Step 12: Touch Routine and then White Grid.
Step 13: Touch Run in the major menu.

Step 14: Examine that the primary colors (red, green, and blue) are not separated in the white grid pattern.

WARNING

To prevent electric shock, do not touch the back side of the A7 CRT Socket board. Use extreme caution when performing the following adjustment.

Step 15: Adjust CONVERGENCE, R210, on the A7 CRT Socket board for the optimum vertical convergence of the red, green, and blue colors.

Step 16: Examine that the grid pattern is focused.

Step 17: Adjust FOCUS, located on the transformer mounted on the A8 CRT Driver board, for the optimum focus of the white grid pattern.

Step 18: Examine that the grid is aligned with the top and bottom tic marks along the inside vertical edge of the front panel bezel. To eliminate any parallax error, look directly ahead at the CRT, and then align the top of the grid with the top vertical tic mark and the bottom of the grid with the bottom tic mark.

Step 19: Adjust VERT SIZE, L321, and VERT POS, R311, on the A8 CRT Driver board to align the grid with the tic marks along the inside vertical edge of the front panel bezel.

Step 20: Examine that the grid is aligned with the horizontal tic marks at the top and bottom of the front panel bezel and that the grid boxes are of uniform length throughout the grid pattern.

Step 21: Adjust H SIZE, R501; H LIN, R502; and H POS, R500; on the A8 CRT Driver board for the best overall linearity and position. Use the horizontal tic marks at the top and bottom of the front panel bezel to align the grid.

Step 22: H-SIZE, H-LIN, and H-POS potentiometers interact, so you may need to repeat Steps 20 and 21 until they are all correctly adjusted.

Step 23: Touch Exit to return to the Routine menu of the Extended Diagnostic menu structure.

Step 24: Touch Gray Scale in the Routine menu.

Step 25: Touch Run in the major menu.
Step 26: Examine that the color scale is white at the top, gray at the bottom, and the background on the right side of the display is cut off (that is, the vertical raster lines are not visible on the right side of the display).

If the gray scale meets the previous conditions, do not perform the adjustments in Steps 27, 28, and 30. Proceed to Step 31.

Step 27: Adjust RED, R200; GREEN, R201; and BLUE, R203; on the A7 CRT Socket board fully counterclockwise.

Step 28: Adjust SCREEN, located on the transformer that is mounted on the A8 CRT Driver board, so that the bottom block of the gray scale is visible but the background on the right side of the display is still cut off.

Step 29: Note which color (red, green, or blue) appears most prominently in the display. DO NOT adjust this color in the following step.

Step 30: Adjust RED, R200; GREEN, R201; or BLUE, R203; on the A7 CRT Socket board for a pure white to gray scale display. Only adjust the colors that do not appear to be prominent. For example, if the display appears to be more red, then adjust the GREEN and BLUE potentiometers.

NOTE

SCREEN may have to be adjusted slightly if any of the colors are adjusted. If the vertical raster lines are visible in the background, then adjust SCREEN so that the background is just cut off, but the bottom gray box is still visible.

Step 31: Touch Exit to return to the Extended Diagnostic menu structure.

Step 32: Touch Red Display, and then touch Run.

Step 33: Examine the red display for any severe color impurities.

Step 34: Touch Exit to return to the Extended Diagnostics menu structure.

Step 35: Touch Green Display and then touch Run.

Step 36: Examine the green display for any severe color impurities.

Step 37: Touch Exit to return to the Extended Diagnostic menu structure.

Step 38: Touch Blue Display and then touch Run.

Step 39: Examine the blue display for any severe color impurities.
Step 40: If any of the color displays (that is, the Red Display, Green Display, or Blue Display) showed severe color impurities, then perform the following to restore the color purity:

- Ensure that the CSA 803A environment is free of all external magnetic fields. For example, a magnetic screwdriver near the CSA 803A could cause color impurities on the screen.
- Set the ON/STANDBY switch to STANDBY.
- Wait 10 seconds, then set the ON/STANDBY switch to ON.
- Examine the color displays again, and verify that the color impurities are removed.

NOTE

*When the CSA 803A is moved in the earth’s magnetic field, color impurities will appear on the display. This is normal. To remove the impurity, repeat Step 40.*

Step 41: Set the ON/STANDBY switch to STANDBY.

Step 42: Replace the CRT Socket board cover and the CRT cover.
Adjustments

Figure 5-4: A8 CRT Driver Board Adjustment Locations
Figure 5-5: A7 CRT Socket Board Adjustment Locations
Real Time Clock

This procedure verifies the correct operation and accuracy of the CSA 803A’s input/output systems (see Figure 5-6).

This procedure should be performed only if maintenance is required. Its use is not necessary for verifying instrument specifications.

Measurement Limits

The measurement limit for the real time clock is 1,000,000 μs ±5 μs.

Setup to Examine/Adjust Real Time Clock

![Diagram of CSA 803A setup](image)

Procedure to Examine/Adjust Real Time Clock

- **Step 1:** Initialize the CSA 803A settings as follows:

  - UTILITY button .......................................................... press
  - Initialize (in major menu) ................................. touch
  - Initialize (in verification pop-up menu) ................. touch
Step 2: Perform the following operations in the order given:

- Set the front panel ON/STANDBY switch to STANDBY.
- Remove the L bracket on the front of the card cage.
- Remove both plastic retaining strips from the top of card cage.
- Remove the A17 Main Processor board, and then install it in the fourth slot from the outer edge.
- Remove the A29 Memory Expansion board, and then install it in the third slot.
- Remove the A14 Input/Output (I/O) board, and then install it in the second slot.
- Move the A18 Memory board from the first slot to the fifth slot.
- Reconnect all the cables to the A14 I/O board.
- Set the CSA 803A front panel ON/STANDBY switch to ON.

Step 3: Connect the Frequency Counter as indicated in the setup diagram (see also Figure 5-6), and set the controls as follows:

Frequency counter

- Mode .................................................. Period
- Trigger .................................................. DC
- Slope .................................................. – (negative)
- Time Base ........................................... 1 MHz

Step 4: Make the following CSA 803A selections:

UTILITY button ........................................ press

- Page to Enhanced Accuracy (in major menu) ........... touch
- Page to Utility2 (in major menu) ......................... touch
- Extended Diagnostics (in major menu) ................. touch
- Extended Diagnostics (in pop-up menu) ............... touch
- Block (in major menu) ................................ touch
- Input/Output (in pop-up menu) ......................... touch
- Area (in major menu) ................................ touch
- Real Time Clk (in pop-up menu) ...................... touch
- Routine (in major menu) ............................... touch
- Calibrate (in pop-up menu) ............................. touch
- Run (in major menu) .................................. touch

Step 5: Examine that the frequency counter reads within the limits of 999,995 µs and 1,000,005 µs.

DO NOT attempt to optimize the adjustment setting if the period is within the stated limits. Proceed to Step 7.

Step 6: Adjust Real Time Clock, C510, for 1,000,000 µs.
Adjustments

- **Step 7**: Remove the frequency counter from the power module.
- **Step 8**: Set the CSA 803A ON/STANDBY switch to STANDBY.
- **Step 9**: Replace the circuit boards (rearranged in Step 2) in their original positions.

---

**Figure 5-6**: A14 I/O Board Test Point and Adjustment Locations
Preventive Maintenance

Regular maintenance can prevent instrument breakdown and may improve the reliability of the instrument. The environment in which the instrument operates will determine the frequency of maintenance. A convenient time for doing preventive maintenance is prior to performing an electrical adjustment.

Removing the Cabinet Panel

**WARNING**

Dangerous potentials exist at several points throughout this instrument. When the instrument is operated with the covers removed, to avoid electric shock, do not touch exposed connections or components.

Some transistors have voltages present on their cases. Therefore, to avoid electric shock, disconnect the power before cleaning the instrument or replacing any parts.

The top and bottom cabinet panels (or covers) protect you from operating potentials present within the instrument. In addition, the panels reduce radiation of electromagnetic interference from the instrument. To remove the panels, loosen the fasteners and lift the panels off. Operate the instrument with the panels in place to protect the interior from dust.
Cleaning the Instrument

The instrument should be cleaned as often as operating conditions require. Dirt in the instrument can cause overheating and component breakdown. Dirt on components acts as an insulating blanket and prevents efficient heat dissipation. Dirt also provides an electrical conduction path which may cause the instrument to fail. The side panels reduce the amount of dust that reaches the interior of the instrument. Keep the side panels in place for safety and cooling.

**CAUTION**

*Avoid the use of chemical cleaning agents which might damage the plastics used in this instrument. Use a nonresidue type of cleaner, preferably isopropyl alcohol or totally denatured ethyl alcohol. Before using any other type of cleaner, consult your local Tektronix service center or representative.*

Exterior

Dust on the instrument can be removed with a soft cloth or small brush. The brush is also useful for dislodging dirt on and around the front panel controls. Dirt that remains can be removed with a soft cloth dampened in a mild detergent and water solution. Do not use abrasive cleaners.

CRT

Faceplates are cleaned with a soft, lint-free cloth dampened with denatured alcohol.
Interior

Cleaning should seldom be necessary. To clean the interior, blow off the dust with dry, low-velocity air (approximately 5 lb/in²). Remove any dirt that remains with a soft brush or a cloth dampened with a mild detergent and water solution. A cotton-tipped applicator is useful for cleaning in narrow spaces, or for cleaning more delicate circuit components. After cleaning, use a washcloth dampened with water to remove any residue.

**CAUTION**

*Circuit boards and components must be dry before applying power to prevent damage from electrical arcing.*

*The high-voltage circuits should receive special attention. Excessive dirt in these circuits may cause high-voltage arcing and result in improper instrument operation.*

Visual Inspection

The instrument should be inspected occasionally for defects such as broken connections, improperly seated semiconductors, damaged or improperly installed circuit boards, and heat-damaged parts. The corrective procedure for most visible defects is obvious; however, particular care must be taken if heat-damaged parts are found. Since overheating usually indicates other trouble in the instrument, correcting the cause of overheating is important to prevent the damage from reoccurring.

Periodic Electrical Adjustment

To ensure accurate measurements, check the electrical adjustment of this instrument after each 2,000 hours of operation, or every 24 months if used infrequently.
Preventive Maintenance
Corrective Maintenance

Corrective maintenance consists of module and board replacement procedure for repairing the instrument.

---

### Power Supply Voltage Hazard

Use caution if working near any metal-faced part in the Power Supply module.

**WARNING**

All metal components, including any metal-faced ones, in the Power Supply module should be considered hazardous because these components may be at the AC line voltage potential.

Always remove the line power cord before attempting any disassembly procedures.

An electric-shock hazard exists when the instrument is not grounded. Do not remove the ground wire (green-yellow) that connects the Power Supply module chassis to the instrument.

---

### Ordering Parts

When ordering replacement parts from Tektronix, Inc., include the following information:

- instrument type
- instrument serial number
- a description of the part
- Tektronix part number
Static-Sensitive Device Classification

CAUTION

Static discharge can damage any semiconductor component in this instrument. Follow the precautions in this section to prevent damage.

This instrument contains electrical components that are susceptible to damage from static discharge. See Table 6-1 for the relative susceptibility of various classes of semiconductors. Static voltages of 1 kV to 30 kV are common in unprotected environments.

Table 6-1: Relative Susceptibility to Damage from Static Discharge

<table>
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<th>Semiconductor Classes</th>
<th>Relative Susceptibility Levels¹</th>
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<tr>
<td>MOS or CMOS microcircuits, and discrete or linear microcircuits with MOS inputs (most sensitive)</td>
<td>100 V to 500 V</td>
</tr>
<tr>
<td>ECL</td>
<td>200 V to 500 V</td>
</tr>
<tr>
<td>Schottky signal diodes</td>
<td>250 V</td>
</tr>
<tr>
<td>Schottky TTL</td>
<td>500 V</td>
</tr>
<tr>
<td>High-frequency bipolar transistors</td>
<td>400 V to 600 V</td>
</tr>
<tr>
<td>JFETs</td>
<td>600 V to 800 V</td>
</tr>
<tr>
<td>Linear microcircuits</td>
<td>400 V to 1000 V (est.)</td>
</tr>
<tr>
<td>Low-power Schottky TTL</td>
<td>900 V</td>
</tr>
<tr>
<td>TTL (least sensitive)</td>
<td>1200 V</td>
</tr>
</tbody>
</table>

¹Voltage discharged from a 100 pF capacitor through a resistance of 100 Ω.
Observe the following precautions to avoid damage:

- Minimize handling of static-sensitive components.
- Transport and store static-sensitive components or assemblies in their original containers, anti-static tube rail, or conductive foam. Label any package that contains static-sensitive assemblies or components.
- Discharge the static voltage from your body by wearing a wrist strap while handling these components. Servicing static-sensitive assemblies or components should be performed only at a static-free work station by qualified service personnel. We recommend using the static control mat. Refer to Table 4-2 for the part numbers of these test equipment.
- Keep the work station surface free of anything that can generate or hold a static charge.
- Keep the component leads shorted together whenever possible by storing them in conductive foam or rails.
- Pick up components by the body, never by the leads.
- Do not slide the components over any surface.
- Avoid handling components in areas that have a floor or work-surface covering that can generate a static charge.
## Removing and Replacing FRUs

Use Table 6-2 as a convenient reference for finding connector and screw locations when removing and replacing field replaceable units (FRUs). The first column in the table lists the FRU to be removed or replaced, and the second column lists the figures that you should reference for the location of connector and screw locations discussed in the procedure to remove/replace this FRU.

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<td>Figure 6-12: Removing/Replacing the A8 CRT Driver Board</td>
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**NOTE**

*In addition to the figures listed in Table 6-2, the exploded-view drawings in the Parts List section may be helpful in removing or disassembling individual FRUs or subassemblies. Also, Figures 6-1 and 6-30 are useful for determining the location of FRUs and FRU ICs.*
Corrective Maintenance

The top and/or bottom covers will need to be removed for most repairs. To loosen the cover fasteners, use a coin or a straight-slot screwdriver with a large-sized tip and rotate the cover fasteners a quarter turn counter-clockwise.

Whenever a specific area is mentioned (such as the right side), it will usually be in reference to the front of the instrument. If another reference is intended, it will be indicated (for example, viewing from the left side or viewing from the rear of the instrument).

All connector names are labeled on the circuit board and/or on the connectors themselves.

**WARNING**

To avoid electric-shock hazard and instrument damage, always disconnect the CSA 803A from its power source before removing or replacing FRUs. For sampling head removal or replacement, switch the front panel ON/STANDBY switch to STANDBY.
Electrical Lock-On of the Front Panel ON/STANDBY Power Switch

Some applications of the CSA 803A may require that the power remain on. To electrically lock the power on, use the following procedure:

☐ Step 1: Switch the rear panel PRINCIPAL POWER SWITCH to OFF.

☐ Step 2: Remove the AC power cable.

☐ Step 3: Position the instrument on its left (handle) side, as viewed from the front.

☐ Step 4: Remove the bottom cover.

☐ Step 5: Locate the A4 Regulator board.

☐ Step 6: Locate the J820 jumper on the A4 Regulator board.

☐ Step 7: Reposition the J820 jumper from its two outer (right side) pins to its two inner (left side) pins, without dropping the jumper.

☐ Step 8: Replace the bottom cover. Turn the instrument in the upright position.

☐ Step 9: Reconnect the AC power cable and switch the PRINCIPAL POWER SWITCH to ON.

The power will now remain on regardless of the setting of the ON/STANDBY power switch.

CAUTION

To prevent damage to the instrument and/or sampling head, do not install or remove a sampling head while the power is on.

☐ Step 10: To turn the power off while the ON/STANDBY power switch is disabled, use the rear panel PRINCIPAL POWER SWITCH.

To return to normal operation of the ON/STANDBY Power Switch, follow the preceding steps in reverse order.
Figure 6-1: Field Replaceable Units (FRU) Locator
Figure 6-1: Field Replaceable Unit (FRU) Locator (Cont.)
Power Supply Module Removal/Replacement

The Power Supply module slides out of the rear of the CSA 803A for maintenance and troubleshooting. It may also be removed to gain better access to the A3 M/F Power Connect board or the A4 Regulator board.

See Figure 6-2 and Figure 6-3 for connector and screw locations.

Figure 6-2: Removing the Power Supply Module, Fan Housing, and Rear Panel Connector Plate
Figure 6-3: A2A2 Control Rectifier Board Connector Locations

To remove the Power Supply module from the CSA 803A, proceed as follows:

☐ **Step 1:** Turn the instrument on its left side (as viewed facing the rear panel). The Power Supply module will now be at the bottom of the instrument.

☐ **Step 2:** Remove the eight Torx head screws that secure the power supply module.

☐ **Step 3:** Carefully pull the Power Supply module partially out of the instrument. Stop short of stretching taut or binding the wires from the A2A2 Control Rectifier board connectors.

![CAUTION](image)

*To prevent damage to the connector pins, pull the Power Supply module only partially out of the instrument.*
Corrective Maintenance

☐ **Step 4:** Remove the wire connectors from the pins on the A2A2 Control Rectifier board.

☐ **Step 5:** Remove the chassis ground (green-yellow) wire that is connected to the Power Supply module from the chassis of the instrument.

☐ **Step 6:** Remove the Power Supply module.

To replace the Power Supply module, perform the previous steps in reverse order.

**NOTE**

*Align the metal guides on the top of the Power Supply module with the grooves inside the upper part of the opening in the instrument.*

*Be careful not to pinch any wires or interconnecting cables while installing the Power Supply module.*
Fan Motor Removal/Replacement

See Figure 6-2 for connector and screw locations.

Remove and replace the fan motor as follows:

- **Step 1:** Using a pencil or tape, mark the top of the fan motor housing for later use in determining the positioning of the motor. Remove the four screws securing the housing to the rear of the instrument mainframe. Hold the housing as you remove the last screws.

- **Step 2:** Separate the grill and the housing from the motor.

- **Step 3:** Remove the two wires at their motor connections. Note that the red wire is (+) and the brown wire is (−).

- **Step 4:** Remove the fan motor.

**NOTE**

*Observe the position in which the motor was mounted. Ensure that the motor is remounted in its original positioning, or the fan wires may not reach.*

To replace the fan motor, perform the previous steps in reverse order and note the following additional points while replacing the motor:

- use the mark from Step 1 to determine the original positioning of the motor
- tighten the screws securely
- remove the mark from the top of the housing
- check that no wires contact the fan blades

**CAUTION**

*To prevent damage to the fan connection, be careful not to pinch the wires under the fan housing.*
Cathode Ray Tube (CRT) Removal/Replacement

**WARNING**

The cathode ray tube (CRT) may retain a dangerous electrical (16 kV) charge. To prevent electric shock, fully discharge the anode before removing the CRT. Short the anode lead from the CRT to the chassis. Wait approximately ten minutes and again firmly short the anode lead to the chassis. Then, remove the CRT.

If the CRT breaks, the glass fragments scatter at a high velocity (implosion). Use extreme care when handling the CRT. Protective clothing and safety glasses should be worn. Avoid striking the CRT on any object which might cause it to crack or implode. When storing a CRT, place it in a protective carton or set the CRT face down in a protected location with a smooth surface and with the CRT faceplate on a soft mat.

See Figures 6-1, 6-4, 6-5, 6-6, 6-7, 6-13, and 6-32 for module, connector, screw, and index locations.

Remove the CRT as follows:

- **Step 1**: Remove the three Torx head screws that secure the CRT cover, and then the CRT cover.

- **Step 2**: Set the instrument in the inverted position.

- **Step 3**: Use a 1/16-inch Allen wrench to loosen the two small screws that secure the two control knobs. Carefully remove the control knobs so that you do not lose the small Allen screws inside the knobs.

**CAUTION**

When replacing the two control knobs, do not overtighten the two Allen screws.

- **Step 4**: Remove the two Torx head screws on the bottom of the A9 Touch Panel Assembly.

- **Step 5**: Lift up on the bottom of the A9 Touch Panel Assembly and swing the assembly outward. The top of the A9 Touch Panel Assembly is held in place with two tabs that hook under the top of the chassis. Pull the assembly out until you can access the black ground wire that connects the A9 Touch Panel Assembly to the instrument chassis.

- **Step 6**: Remove the quick-disconnect ground connector that connects the black ground wire to the instrument chassis.
Step 7: Set the A9 Touch Panel Assembly aside. To avoid stressing the ribbon cable that is still connected to the A9 Touch Panel Assembly, and to keep the assembly from cluttering your work space, place the A9 Touch Panel Assembly on top of the sampling head compartments. Do not damage the A9 Touch Panel Assembly when placing it on top of the sampling head plug-in compartments.

Step 8: Carefully set the instrument on its left side.

Step 9: Remove the two plastic circuit board guides from the top of the card cage.

Step 10: Remove the two Torx head screws that secure the A7 CRT Socket board cover. Use a short Torx head screwdriver to remove the rear-most Torx head screw.

Step 11: Remove the A7 CRT Socket board cover.

Step 12: Slowly pull the A7 CRT Socket board toward the rear of the instrument to remove the A7 CRT Socket board from the CRT.

NOTE

When reattaching the A7 CRT Socket board to the CRT, align the pins of the CRT to the receptacles on the A7 CRT Socket board. Then, slowly push the pins into the receptacles.

Do not force the connector into place; doing so can bend or break some of the pins. If the pins do not slide easily into the receptacles, then pull the A7 CRT Socket board away from the CRT, and realign the A7 CRT Socket board to the CRT.

WARNING

The CRT anode voltage is 16 kV. To avoid electric shock, ground the anode lead from the CRT to the chassis to remove any stored charge remaining in the CRT. Wait approximately ten minutes. Then, ground the anode lead to the chassis again.

Step 13: Remove connector J54 from the A8 CRT Driver board. Note the position of the multi-pin connector’s index triangle to ensure that you can correctly replace the connector.

Step 14: Remove the four Torx head screws that secure the CRT to the top of the instrument chassis. Two of the screws are removed from the front of the front panel chassis, and two of the screws are removed from behind the front panel casting.
Corrective Maintenance

- **Step 15:** Remove the top CRT support bar from the instrument. The CRT support bar is unattached once the four Torx head screws securing the top of the CRT are removed.

- **Step 16:** Remove the four Torx head screws that secure the CRT to the bottom of the instrument chassis. Two of the screws are removed from the front of the front panel chassis, and two of the screws are removed from behind the front panel casting.

- **Step 17:** Remove the bottom CRT support bar from the instrument.

**CAUTION**

*Once the four Torx head screws are removed from the bottom of the CRT, the CRT is not attached to the instrument. Use care to not damage the CRT while it is loose in the instrument.*

- **Step 18:** Slowly pull the CRT out of the front panel chassis.

To replace the CRT, perform the previous steps in reverse order.

**NOTE**

*Replacing the CRT will require that the instrument be readjusted.*
Figure 6-4: Removing/Replacing the CRT Cover
Figure 6-5: Removing/Replacing the Cathode Ray Tube
Figure 6-6: Removing/Replacing the CRT Torx Head Screws
Acquisition Unit Removal/Replacement

See Figures 6-23, 6-26, and 6-32 for connector, screw, and index locations.

Remove and replace the Acquisition unit as follows (the Acquisition unit can be removed with the instrument in the normal upright position for all steps):

**CAUTION**

Lifting the trim covers to remove them will break the trim covers. There is a clip on the inside of the trim cover that slides over the end of the side frame section. To remove the trim covers, move each cover toward the end of the instrument where it is located. (The front cover moves forward and the rear cover moves backward.) Moving the clip about 1/8-inch will release the cover. Then, the cover can be removed from the instrument.

- **Step 1**: Remove the bolt from the top of the chassis, just behind the front casting.
- **Step 2**: Remove the trim covers from the right side (as viewed from the front of the instrument).
- **Step 3**: Remove the two Torx head screws holding the frame section and remove the frame section.
- **Step 4**: Remove connectors J10 on the A26 M/F Acquisition Interconnect board and J34 on the A19 Strobe/TDR Buffer board. Note the position of the connectors’ index triangles to ensure that the multi-pin connectors can be correctly replaced.
- **Step 5**: Remove connectors J29A, J30A, J32, J33A, and J33B on the A19 Strobe/TDR Buffer board.
- **Step 6**: Grab between the two sampling head slots and gently pull out the Acquisition unit a few inches.
- **Step 7**: Remove the gray ground wire from the rear of the Acquisition unit.
- **Step 8**: Remove the Acquisition unit.

**CAUTION**

To prevent damage to interconnecting wires, be careful not to pinch any interconnecting wires when replacing this unit.

To replace the Acquisition unit, perform the previous steps in reverse order.
Battery Disposal and First Aid

The instrument contains the following number of batteries on the following boards:

- two batteries (in the U500 and U511 RAM sockets) on the A5 Time Base/Controller board
- one battery (BT130) on the A14 I/O board
- one battery (BT150) on the A18 Memory board

See Figures 6-10, 6-19, and 6-22, respectively, for the location of these batteries.

**WARNING**

To avoid personal injury, observe proper procedures for the handling of lithium batteries. Improper handling may cause fire, explosion, or severe burns. Do not recharge, crush, disassemble, heat the battery above 100°C (212°F), incinerate, or expose the contents to water.

Battery Disposal

Dispose of the batteries in accordance with local, state, and federal regulations.

**NOTE**

Typically, small quantities (less than 20) can be safely disposed of with ordinary garbage in a sanitary landfill.

Larger quantities must be sent by surface transport to a hazardous waste disposal facility. The batteries should be individually packaged to prevent shorting. Then, pack them into a sturdy container that is clearly labeled, Lithium Batteries — DO NOT OPEN.
Emergency and First Aid Information

In case of accidental contact with the lithium batteries, give your emergency care provider the following information:

- **Manufacturer:** Panasonic
- **Battery Type:** Lithium Poly-Carbon monofluoride, BR 2/3 A
- **Solvent** (electrolyte): Gama Butyrlactone is of low toxicity. It can cause some eye and respiratory irritation. According to the manufacturer, the solvent may be released during venting. (Venting is an out gassing of battery material.) This is usually caused by short circuiting (for more than a few seconds) or by overheating.
- **Solute:** LiBF4

Table 6-3 lists the emergency procedures to follow should you come in contact with battery solvent.

**Table 6-3: Emergency Procedures for Contact with Battery Solvent**

<table>
<thead>
<tr>
<th>Contact</th>
<th>Do This:</th>
</tr>
</thead>
<tbody>
<tr>
<td>Skin</td>
<td>Wash promptly with plenty of water.</td>
</tr>
<tr>
<td>Eyes</td>
<td>Flush immediately with plenty of water and use an emergency eye wash, if available. Report to a medical professional for treatment.</td>
</tr>
<tr>
<td>Inhalation</td>
<td>Leave the area and get fresh air. Report to a medical professional for treatment.</td>
</tr>
<tr>
<td>Ingestion</td>
<td>Non-toxic according to laboratory testing. However, report to a medical professional for advice.</td>
</tr>
</tbody>
</table>

In case of venting, clear the immediate area. Venting will usually last only a few seconds.
FRU Board and Assembly Removal

Pin connectors are for electrical interconnection with chassis-mounted components and other boards. Most boards/assemblies in the instrument are mounted on the chassis. The following four boards plug onto the top of the A13 Mother board (see Figure 6-7 for the location of these boards in the card cage):

- A14 Input/Output (I/O)
- A15 Memory Management Unit (MMU)
- A17 Executive Processor (EXP)
- A18 Memory

The following two boards plug onto the A26 M/F Acquisition Interconnect board (See Figure 6-1 for the locations of these boards in the Acquisition unit):

- A27 Acquisition Analog
- A28 Acquisition MPU

Feed-through connectors join the plug-on boards to the A13 Mother board and the A26 M/F Acquisition Interconnect board.

CAUTION

To minimize the chance of static charge damage to the integrated circuits and/or related circuitry, after removing a board from the instrument, place it on a grounded, antistatic surface.

Some components that are mounted on a board must be retained for use with the new assembly. These components would include interconnecting plugs, support posts, and some wiring.
Corrective Maintenance

Figure 6-7: Top View of the Card Cage
A1 M/F Strobe Drive Board

Removal and replacement steps are listed below. See Figures 6-8 and 6-32 for connector, screw, and index locations.

☐ Step 1: Place the instrument in the inverted position and remove the bottom panel.

☐ Step 2: Remove connectors J16, J27, J28, J33A, J33B, J35, J36, J37, J38, and J39 from the A1 M/F Strobe Drive board. Then remove connectors J10, J18, and J34 from the A1 M/F Strobe Drive board. Note the position of the connectors and index triangles to ensure that the connectors can be correctly replaced.

**NOTE**

Record the positions of the connectors to ensure that the connectors can be correctly replaced.

☐ Step 3: Remove the five Torx head screws and carefully lift the board, removing it from the J19 connector on the A1 M/F Strobe Drive board.

To replace the A1 M/F Strobe Drive board, perform the previous steps in reverse order.

---

**Figure 6-8: Removing/Replacing the A1 M/F Strobe Drive Board**
A3 M/F Power Connect Board

Removal and replacement steps are listed below. See Figures 6-2, 6-3, 6-9 and 6-19 for connector, screw, and index locations.

☐ Step 1: Remove the Power Supply module as described earlier in this section.

NOTE

The chassis ground (green-yellow) wire may be removed from the Power Supply module for this operation only.

Record the positions of all connectors to ensure that the connectors can be correctly replaced.

☐ Step 2: Remove the A1 M/F Strobe Drive board.

☐ Step 3: Remove the A5 Time Base/Controller board.

☐ Step 4: Remove the A4 Regulator board.

☐ Step 5: Remove J90 from the A14 Input/Output board.

To replace the A3 M/F Power Connect board, perform the previous steps in reverse order.

WARNING

To prevent electric shock or damage to the instrument, check that the chassis ground wire is replaced on the Power Supply module.
A4 Regulator Board

Removal and replacement steps are listed below. See Figures 6-2, 6-3, 6-9, and 6-32 procedures for removal for connector, screw, and index locations.

☐ **Step 1:** Remove the Power Supply module. (See Power Supply Module Removal in this section.)

☐ **Step 2:** Set the instrument upright (if not already in this position).

☐ **Step 3:** Remove connectors J57 and J60 from the A4 Regulator board. Note the position of the multi-pin connectors’ index triangles to ensure that the connectors can be correctly replaced.

☐ **Step 4:** Remove the two Torx head screws from the metal heat sink attached to the rear of this board).

**NOTE**

The A4 Regulator board is not attached to the chassis. However, it remains connected to the A3 M/I Power Connect board through interconnecting pins.

☐ **Step 5:** Carefully remove the J95 and J96 pins from the A4 Regulator board by pulling the A4 Regulator board toward the rear.

☐ **Step 6:** Remove the A4 Regulator board.

To replace the A4 Regulator board, perform the previous steps in reverse order.

**NOTE**

Match the index triangles on the multi-pin connectors with the corresponding square pads on the circuit board.
Figure 6-9: Removing/Replacing the A4 Regulator Board
A5 Time Base/Controller Board

Removal and replacement steps are listed below. See Figures 6-10 and 6-32 for connector, screw, and index locations.

☐ **Step 1:** Place the instrument in the inverted position.

☐ **Step 2:** Remove connectors J16, J29A, J30A, J32, J35, J91, Ext A, and Presc (if Prescaler is present) from the A5 Time Base/Controller board. Use extreme care to prevent damage to the cable center connector that was attached to Presc. Then remove connectors J18 and J83 from the A5 Time Base/Controller board. Note the position of the multi-pin connector’s index triangles to ensure that the connectors can be correctly replaced.

**NOTE**

*Record the positions of the connectors and the receptacles to ensure that these connectors and receptacles will be positioned correctly when reinstalled.*

☐ **Step 3:** Remove the six Torx head screws holding the board in place.

☐ **Step 4:** Remove the A5 Time Base/Controller board.

To replace the board, perform the previous steps in reverse order.
Figure 6-10: Removing/Replacing the A5 Time Base/Controller Board
A7 CRT Socket Board and A8 CRT Driver Board

See Figures 6-1, 6-4, 6-5, 6-7, 6-11, 6-12, 6-13, 6-15, and 6-32 for board, connector, screw, and index locations.

Remove and replace the A7 CRT Socket board and the A8 CRT Driver board as follows:

☐ **Step 1:** Remove the three Torx head screws that secure the CRT cover, and then remove the CRT cover.

☐ **Step 2:** Remove the two plastic circuit board guides on top of the card cage.

☐ **Step 3:** Remove the two Torx head screws that secure the A7 CRT Socket board cover, and then remove the A7 CRT Socket board cover.

☐ **Step 4:** Slowly pull the A7 CRT Socket board toward the rear of the instrument to remove the A7 CRT Socket board from the CRT.

☐ **Step 5:** Remove connectors J53 and J56 on the A7 CRT Socket board. Note the positions of the multi-pin connectors’ index triangles to ensure that you can correctly replace these connectors.

---

**WARNING**

_The CRT anode voltage is 16 kV. To avoid electric shock, ground the anode lead from the CRT to the chassis to short any stored charge remaining in the CRT. Wait approximately ten minutes, then ground the anode lead to the chassis again (refer to Step 6)._ 

☐ **Step 6:** Use a non-conducting tool to pry up the anode lead cap. This rubber cap is located on the upper part of the CRT, behind the front casting. Using a non-conducting tool, release the spring clip inside the cap and remove the anode. Insert one blade of a pair of needle-nose pliers against the anode, and touch the other blade to the top of the front casting to ground the anode to the chassis.

☐ **Step 7:** Remove the single Torx head screw that secures the A8 CRT Driver board to the instrument chassis. Use either of the following methods to remove the Torx head screw:

- Remove the Torx head screw with a very short handled T-15 Torx head screwdriver. Ensure that you do not strike the CRT while removing the screw.

- Remove the A10 Front Panel Control board. Then, use a Torx head screwdriver that has an extension length inserted in it to remove the Torx head screw. Access the screw from the hole in the left side of the instrument chassis. Ensure that you do not strike the CRT while removing the screw.
Corrective Maintenance

☐ **Step 8:** Remove the single Torx head screws that secure the transformer, on the A8 CRT Driver board, to the instrument chassis. This screw is located at the rear of the transformer. The A8 CRT Driver board is now not attached to the instrument chassis.

☐ **Step 9:** Remove connectors J52, J56, and J57 from the A8 CRT Driver board. Note the position of the multi-pin connectors’ index triangles to ensure that you can correctly replace these connectors.

☐ **Step 10:** Lift the A8 CRT Driver board partially out of the instrument chassis.

☐ **Step 11:** Remove connectors J54 and J55 from the A8 CRT Driver board. Note the position of the multi-pin connectors’ index triangles to ensure that you can correctly replace these connectors.

☐ **Step 12:** Remove the A8 CRT Driver board and the A7 CRT Socket board.

☐ **Step 13:** Unsolder the two wires that connect the A8 CRT Driver board to the A7 CRT Socket board (the two boards are now separated).

To replace the A8 CRT Driver board and the A7 CRT Socket board, perform the previous steps in reverse order.

![Solder Points](image_url)

**Figure 6-11:** Removing/Replacing the A7 CRT Socket Board
Figure 6-12: Removing/Replacing the A8 CRT Driver Board
A9 Touch Panel Assembly

Removal and replacement steps are listed below. See Figures 6-5, 6-15 and 6-32 for connector, screw, and index locations.

Remove and replace the A9 Touch Panel assembly as follows:

☐ **Step 1**: Set the instrument on its right side. (The CRT will now be at the top.)

☐ **Step 2**: Use a 1/16-inch Allen wrench to loosen the small Allen screws in each of the two control knobs.

☐ **Step 3**: Slowly remove the two control knobs so that you do not lose the small Allen screws inside the knobs.

☐ **Step 4**: Remove the two Torx head screws at the bottom of the A9 Touch Panel Assembly.

☐ **Step 5**: Lift up on the bottom of the A9 Touch Panel Assembly, and swing the assembly outward.

**NOTE**

*The top of the A9 Front Panel Assembly is held by two tabs. These tabs fit into two slots in the front-panel chassis.*

☐ **Step 6**: Remove the black ground wire from the quick-disconnect ground connector on the front panel casting.

☐ **Step 7**: Remove connector J73 from the A10 Front Panel Control board. Note the position of multi-pin connector’s index triangle to ensure that you can correctly replace this connector. Carefully remove the wire cable through the slot provided in the front casting.

Cover the A9 Touch Panel Assembly with protective material once it is removed, since the plastic exterior may scratch.

To replace the A9 Touch Panel Assembly board, perform the previous steps in reverse order.

**NOTE**

*Feed any slack cable from connector J73 to inside the chassis (near the A10 Front Panel Control board). Be careful not to pinch the interconnecting cable while replacing the front panel bezel.*
Figure 6-13: A9 Touch Panel Assembly Torx Head Screws

Figure 6-14: Removing/Replacing the A9 Touch Panel Assembly
A10 Front Panel Control Board

Removal and replacement steps are listed below. See Figures 6-5, 6-11, 6-15 and 6-32 for connector, screw, and index locations.

☐ **Step 1:** Remove the CRT shield. (Refer to Cathode Ray Tube Removal in this section, beginning at Step 4.)

☐ **Step 2:** Remove connectors J72, J73, J74, and J75 from the A10 Front Panel Button board. Note the position of the multi-pin connectors’ index triangles to ensure that the connectors can be correctly replaced.

☐ **Step 3:** Remove the two Torx head screws at the upper edge of the board.

☐ **Step 4:** Lift the board away from the guides at its bottom and remove it.

To replace the A10 Front Panel Control board, perform the previous steps in reverse order.
Figure 6-15: Removing/Replacing the A10 Front Panel Control Board
A11 Front Panel Button Board

Removal and replacement steps are listed below. See Figures 6-5, 6-11, 6-15, 6-16 and 6-32 for connector, screw, and index locations.

☐ **Step 1:** Remove the CRT shield. (Refer to the removal instructions under Cathode Ray Tube Removal/Replacement earlier in this section, beginning at Step 4.)

☐ **Step 2:** Remove connector J75 from the A10 Front Panel Control board. Note the position of connector’s index triangle for correct replacement.

☐ **Step 3:** Remove the two Torx head screws from the A11 Front Panel Button board, which is located at the top and near the inside center of the front casting.

☐ **Step 4:** Remove the A11 Front Panel Button board.

To replace the A11 Front Panel Button board, perform the previous steps in reverse order.

![Rear View of the A11 Front Panel Button Board](image)

**Figure 6-16:** Removing/Replacing the A11 Front Panel Button Board
A12 Rear Panel Assembly

Removal and replacement steps are listed below. See Figures 6-2, 6-17 and 6-32 for connector, screw, and index locations.

☐ **Step 1:** Remove the connectors from the RS-232-C, the GPIB, and the PRINTER connector holders.

☐ **Step 2:** Remove the eight Torx head screws from the outer edges of the rear panel connector plate.

☐ **Step 3:** Tilt the plate back from the instrument. Remove connector J78 from the top of the A12 Rear Panel assembly. Remove the grounding wire. Note the position of the connector’s index triangle to ensure that the connector can be correctly replaced.

☐ **Step 4:** Remove the rear panel connector plate and the attached A12 Rear Panel Assembly.

☐ **Step 5:** Remove the following items from the rear panel plate:

- two bail brackets, screws, and washers from the PRINTER connector
- two posts from the GPIB connector
- posts, lockwashers, and flat washers from the RS-232-C connector(s)
- Torx head screw and washer (at lower left, if present)

☐ **Step 6:** Remove the A12 Rear Panel Assembly from the rear panel connector plate.

![CAUTION]

The metal covers on the PRINTER and on the GPIB connectors are loose. If the board is inverted, these covers will fall off.

To replace the A12 Rear Panel assembly, perform the previous steps in reverse order.

**NOTE**

Replacement of connector J78 will be simplified if you replace the connector before reinstalling the rear panel connector plate on the rear of the chassis.
Corrective Maintenance

Figure 6-17: Removing/Replacing the A12 Rear Panel Assembly
A13 Mother Board

Removal and replacement steps are listed below. See Figures 6-7, 6-18 and 6-32 for connector, screw, and index locations.

- **Step 1**: Remove the three Torx head screws that secure the CRT cover, and then remove the CRT cover. Remove the card cage retainer from the top front of the card cage by removing the card cage’s two screws. Remove both circuit board guides from the top of the card cage. The other ends of the guides contain slots that attach to the edge of a metal bracket. Both ends of the guides can be pried loose.

- **Step 2**: Remove the A14 I/O, A15 MMU, A17 Executive Processor, and A18 Memory boards. Note the position of the multi-pin connectors’ index triangles to ensure that the connectors can be correctly replaced.

**NOTE**

*Tag the interconnecting plugs and mark the board locations to ensure that the plugs can be correctly replaced as well.*

- **Step 3**: Remove connector J63A from the A13 Mother board.
- **Step 4**: Remove the six Torx head screws.
- **Step 5**: Remove the A13 Mother board.

To replace the A13 Mother board, perform the previous steps in reverse order.

**CAUTION**

*To prevent damage to the interconnecting wires, be careful not to pinch the wires along the inside edge while replacing this board.*
Corrective Maintenance

Figure 6-18: Removing/Replacing the A13 Mother Board
A14 Input/Output (I/O) Board

See Figures 6-4, 6-7, 6-19, and 6-32 for board, connector, screw, and index locations.

Remove and replace the A14 I/O board as follows:

☐ **Step 1**: Remove the three Torx head screws that secure the CRT cover, and then remove the CRT cover.

☐ **Step 2**: Remove both of the plastic board guides from the top of the card cage. These guides are retained by two small catches located in two holes in the left bracket of the card cage. The other ends of the guides contain slots that attach to the edge of a metal bracket. Both ends of the guides can be pried loose.

☐ **Step 3**: Remove connectors J72, J77, J78, and J90 from the A14 I/O board. Note the position of multi-pin connector index triangles to ensure that you can be correctly replace these connectors.

☐ **Step 4**: Lift the white, hinged tab at the upper, front edge of the board. Pull the tab upward until the A14 I/O board separates from the A13 Mother board.

☐ **Step 5**: Remove the A14 I/O board.

To replace the A14 I/O board, perform the previous steps in reverse order.

**NOTE**

Insert the board edges into the plastic guides at each end of the card cage. Lower the board into position.

Ensure that connector P105 is seated on the A13 Mother board connector. Push down firmly on the A14 I/O board to seat this connector on the A13 Mother board.

**WARNING**

A lithium battery (BT130) is mounted on the A14 I/O board. Be careful when placing the A14 I/O board on metal surfaces. If some IC or battery leads are shorted, the battery may discharge or overheat and vent. (You can use plastic standoffs to prevent short circuits.) **This battery requires special handling for disposal.** Refer to the instructions on Lithium Battery Disposal and First Aid earlier in this section.
Figure 6-19: Removing/Replacing the A14 I/O Board
A15 Memory Management Unit (MMU) Board

See Figures 6-4, 6-7, 6-20, and 6-32 for board, connector, screw, and index locations.

Remove and replace the A15 MMU board as follows:

☐ **Step 1:** Remove the three Torx head screws that secure the CRT cover, and then remove the CRT cover.

☐ **Step 2:** Remove both of the plastic board guides from the top of the card cage. The guides are retained by two small catches located in two holes in the left bracket of the card cage. The other ends of the guides contain slots attach to the edge of a metal bracket. Both ends of the guides can be pried loose.

☐ **Step 3:** Remove connectors J52, J53, J57, and J83 from the A15 MMU board. Note the position of multi-pin connector index triangles to ensure that you can correctly replace these connectors.

☐ **Step 4:** Lift the white, hinged tabs at the front and rear edges of the A15 MMU board. Pull the tabs upward until the A15 MMU board separates from the A13 Mother board.

☐ **Step 5:** Remove the A15 MMU board.

To replace the A15 MMU board, perform the previous steps in the reverse order.

**NOTE**

*Insert the board edges into the plastic guides at each end of the card cage. Lower the board into position.*

*Ensure that connector P101 is seated on the A13 Mother board connector. Push down firmly on the A15 MMU board to seat this connector on the A13 Mother board.*
Figure 6-20: Removing/Replacing the A15 MMU Board
A17 Executive Processor (EXP) Board

See Figures 6-4, 6-7, 6-21, and 6-32 for board, connector, screw, and index locations.

Remove and replace the A17 Executive Processor board as follows:

- **Step 1:** Remove the three Torx head screws that secure the CRT cover, and then remove the CRT cover.

- **Step 2:** Remove both of the plastic board guides from the top of the card cage. The guides are retained by two small catches located in two holes in the left bracket of the card cage. The other ends of the guides contain slots that attach to the edge of a metal bracket. Both ends of the guides can be pried loose.

- **Step 3:** Remove connector J77 from the A17 Executive Processor board. Note the position of the multi-pin connector’s index triangle to ensure that you can correctly replace this connector.

- **Step 4:** Lift the white, hinged tabs at the front and rear edges of the board. Pull the tabs upward until the A17 Executive Processor board separates from the A13 Mother board.

- **Step 5:** Remove the A17 Executive Processor board.

To replace the A17 Executive Processor board, perform the previous steps in reverse order.

**NOTE**

Insert the board edges into the plastic guides at each end of the card cage. Lower the board into position.

Ensure that connector P104 on the A17 Executive Processor board is seated on the A13 Mother board connector. Push down firmly on the A17 Executive Processor board to seat this connector on the A13 Mother board.
Corrective Maintenance

Figure 6-21: Removing/Replacing the A17 Executive Processor Board
A18 Memory Board

See Figures 6-4, 6-7, 6-21, 6-22, and 6-32 for board, connector, screw, and index locations.

Remove and replace the A18 Memory board as follows:

☐ **Step 1**: Remove the three Torx head screws that secure the CRT cover, and then remove the CRT cover.

☐ **Step 2**: Remove both of the plastic board guides from the top of the card cage. The guides are retained by two small catches located in two holes in the left bracket of the card cage. The other ends of the guides contain slots that attach to the edge of a metal bracket. Both ends of the guides can be pried loose.

☐ **Step 3**: Remove connector J77 from the A17 Executive Processor board. Note the position of the multi-pin connector's index triangle to ensure that you can correctly replace this connector.

☐ **Step 4**: Lift the white, hinged tabs at the front and rear edges of the board. Pull the tabs upward until the A18 Memory board separates from the A13 Mother board.

☐ **Step 5**: Remove the A18 Memory board.

To replace the A18 Memory board, perform the previous steps in reverse order.

**NOTE**

Insert the edges of the board into the plastic guides at each end of the card cage. Lower the board into position.

Ensure that connector P106 is seated on the A13 Mother board connector. Push down firmly on the A18 Memory board to seat this connector on the A13 Mother board.

**WARNING**

A lithium battery (BT130) is mounted on the A18 Memory board. Be careful when placing the A18 Memory board on metal surfaces. If some IC or battery leads are shorted, the battery may discharge or overheat and vent. (You can use plastic standoffs to prevent short circuits.) **This battery requires special handling for disposal.** Refer to the instructions on Lithium Battery Disposal and First Aid earlier in this section.
Corrective Maintenance

Figure 6-22: Removing/Replacing the A18 Memory Board
A19 Strobe/TDR Buffer Board

Removal and replacement steps are listed below. See Figures 6-23, 6-26, and 6-32 for connector, screw, and index locations.

☐ **Step 1:** Remove the Acquisition unit and position the Acquisition unit in the upright position.

☐ **Step 2:** Remove the two Torx head screws on each black retaining brace located at the top of the Acquisition unit to remove these braces.

☐ **Step 3:** Remove connectors J3A, J4A, J1B, J2B, J3C, J4C, J29A, J30A, J32, J33A, J33B, and J34 from the A19 Strobe/TDR Buffer board.

**NOTE**

*Record the positions of the connectors and the receptacles to ensure that the connectors and receptacles can be correctly replaced.*

☐ **Step 4:** Remove J10 from the A26 M/F Acquisition Interconnect board.

☐ **Step 5:** Remove the two Torx head screws on the bottom of the A19 Strobe/TDR Buffer board, and gently pull out the board.

To replace the A19 Strobe/TDR board, perform the previous steps in reverse order.
Corrective Maintenance

Figure 6-23: Removing/Replacing the A19 Strobe/TDR Buffer Board
A20/A21 Head Interconnect (Power Only) and A22/A23 Head Interconnect Boards

Removal and replacement steps are listed below. See Figures 6-23, 6-24, 6-25, 6-26, 6-28, 6-29, and 6-32 for connector and screw locations.

☐ **Step 1:** Remove the Acquisition unit and position the Acquisition unit in the upright position.

☐ **Step 2:** Remove the two Torx head screws on each black retaining brace located at the top of the Acquisition unit.

☐ **Step 3:** Remove the A27 Acquisition Analog board, the A28 Acquisition MPU board and the A19 Strobe/TDR Buffer board.

☐ **Step 4:** Remove the four screws holding the top front subpanel of the Acquisition unit.

☐ **Step 5:** Remove the four screws on the gold-colored locking bar located on the top front of the Acquisition unit.

☐ **Step 6:** Turn the Acquisition unit in the inverted position and repeat Step 5 on the bottom of the Acquisition unit.

☐ **Step 7:** Remove the connectors from the A26 M/F Acquisition Interconnect board connector. Note the position of the multi-pin connector’s index triangle to ensure that the connector can be correctly replaced.

☐ **Step 8:** Remove the Front Subpanel assembly with the A20-A23 Head Interconnect boards intact.

☐ **Step 9:** Remove the bottom Torx head screw from within the sampling head compartment that contains the head interconnect board you are removing.

☐ **Step 10:** Turn the Front Subpanel assembly around so that the open compartments face away from you.

☐ **Step 11:** Remove the top nut that fastens the sampling head compartment to the head interconnect board you are removing.

☐ **Step 12:** Remove the Head Interconnect board by slightly prying up on the tabs that are keeping it in place, and slowly remove the board(s) from the J1/2/3/4 connector.

To replace the A20/A21 Head Interconnect (Power Only) or the A22/A23 Head Interconnect boards, perform the previous steps in reverse order. Be sure to replace the Power Only boards at J11 and J12 on the A26 M/F Acquisition Interconnect board.
Figure 6-24: Removing/Replacing the A20/A21 Head Interconnect (Power Only) and the A22/A23 Head Interconnect Boards
Figure 6-25: Removing/Replacing the Front Subpanel Assembly
Corrective Maintenance

A26 M/F Acquisition Interconnect Board

Removal and replacement Steps are listed below. See Figures 6-23, 6-25, 6-26, 6-27, 6-28, 6-29, and 6-32 for connector, screw, and index locations.

☐ **Step 1**: Remove the Acquisition unit and position the Acquisition unit in the upright position.

☐ **Step 2**: Remove the A27 Acquisition Analog board, the A28 Acquisition MPU board, and the A19 Strobe/TDR Buffer board.

☐ **Step 3**: Remove the four screws on the gold colored retaining brace holding the top of the Front Subpanel assembly of the Acquisition unit.

☐ **Step 4**: Remove the four screws on the gold colored locking bar located on the top front of the Acquisition unit.

☐ **Step 5**: Turn the Acquisition unit in the inverted position and repeat Steps 3 and 4 on the bottom of the Acquisition unit.

☐ **Step 6**: Remove connectors J11, J12, J13, and J14 on the A26 M/F Acquisition Interconnect board. Note the position of the multi-pin connectors’ index triangles to ensure that the connectors can be correctly replaced.

![Diagram](image-url)

*Figure 6-26: Removing/Replacing the A26 M/F Acquisition Interconnect Board*
Step 7: Remove the Front Subpanel assembly with the head interconnect boards intact.

Step 8: Remove the six Torx head screws to remove the A26 M/F Acquisition Interconnect board.

To replace the A26 M/F Acquisition Interconnect board, perform the previous steps in reverse order.

Figure 6-27: Top View of the A26 Mainframe Acquisition Interconnect Board
A27 Acquisition Analog Board

Removal and replacement steps are listed below. See Figures 6-23, 6-26, 6-28, and 6-32 for board guide, screw, and index locations.

☐ **Step 1**: Remove the Acquisition unit and position the Acquisition unit in the upright position.

☐ **Step 2**: Remove the two Torx head screws on each black retaining brace located at the top of the Acquisition unit to remove these braces.

☐ **Step 3**: Remove connectors J41, J42, J43 and J44 from the A27 Acquisition Analog board.

☐ **Step 4**: Pull up on the hinged white tabs until the board separates from connector P6.

To replace the A27 Acquisition Analog board, perform the previous steps in reverse order.

**NOTE**

*Insert the edges of the board into the plastic guides. Lower the board into position.*

*Check that connector is seated on the A26 M/F Acquisition Interconnect board connector. Push down firmly on the A27 Acquisition Analog board to seat this connector on the A26 M/F Acquisition Interconnect board.*

**Figure 6-28: Removing/Replacing the A27 Acquisition Analog Board**
A28 Acquisition MPU Board

Removal and replacement steps are listed below. See Figures 6-23, 6-26, 6-29, and 6-32 for board guide, screw, and index locations.

- **Step 1**: Remove the Acquisition unit and position it upright.
- **Step 2**: Remove the two Torx head screws on each black retaining brace located at the top of the Acquisition unit; remove these braces.
- **Step 3**: Pull up on the hinged white tabs until the board separates from connector P8 on the A26 M/F Acquisition Interconnect board.

To replace the A28 Acquisition MPU board, perform the previous steps in reverse order.

**NOTE**

*Insert the edges of the board into the plastic guides. Lower the board into position.*

*Check that the connector is seated on the A26 M/F Acquisition Interconnect board connector. Push down firmly on the A28 Acquisition MPU board to seat this connector on the A26 M/F Acquisition Interconnect board.*

![Diagram of A28 Acquisition MPU Board]

**Figure 6-29: Removing/Replacing the A28 Acquisition MPU Board**
FRU IC Removal

The procedures for removing and replacing the FRU ICs in the CSA 803A are outlined in this section.

Serial Data Interface Integrated Circuits ("Slam-Pack" ICs)

U330 is mounted on the A14 I/O board. See Figure 6-30 for the location of this IC. It has a raised, ridged, heat sink cover. The IC is oriented to its socket by a beveled corner. The other corners are notched to fit the edges of the socket. The beveled corner aligns with a spring (small metal tab) at one corner of the socket. An example of the IC is shown in Figure 6-32.

To remove the Serial Data Interface IC, proceed as follows:

- **Step 1**: Remove the A14 I/O board.
- **Step 2**: Hold the heat sink cover in place and unfasten the retaining clip by moving the retaining clip across the tabs while pushing down slightly on the cover.

  **CAUTION**

  To prevent static damage to the instrument or components, observe all the special precautions mentioned under Static-Sensitive Classification in this section.

- **Step 3**: Remove the cover slowly to prevent the IC from falling out. Before removing the IC, note the position of the IC index for later use.
- **Step 4**: Remove the IC with tweezers.

  **CAUTION**

  Finger oils can degrade reliability of components. Avoid touching the IC or its socket contacts with your fingers.
Replace the Serial Data Interface IC as follows:

- **Step 1**: Using tweezers, place the beveled corner of the replacement IC against the index spring (the original position of this index was noted earlier).

  
  **CAUTION**

  *Do not damage the spring by improperly seating the beveled corner because shorting of the two corner contacts could result.*

- **Step 2**: Arrange the other corners, with the tweezers, to fit evenly at the edges of the socket.

- **Step 3**: Set the cover flat on the IC with the cover’s end tabs properly aligned with, but not in, the mating recesses in the socket.

- **Step 4**: Push down on the cover, keeping it flat on the IC, and slide the cover end tabs into place. Hold it there while moving the retaining clip over the tabs at the other end of the cover.

- **Step 5**: Slightly pull on the cover to check that the cover is secure.

- **Step 6**: Replace the A14 I/O board.
Corrective Maintenance

Figure 6-30: FRU IC Detail
Firmware Integrated Circuits (“Dual In-Line Package” ICs)

The firmware ICs are located on four separate boards (see Figure 6-30 for the IC locations on each circuit board). The boards and their respective firmware (FW) are:

- **A5 Time Base/Controller board** — Time Base Processor FW (U300, U310, U400 and U410)
- **A15 MMU board** — Display Processor FW (U140 and U150)
- **A18 Memory board** — Main Processor FW (U800, U810, U820, U830, U900, U910, U920 and U930)
- **A28 Acquisition MPU board** — Acquisition Processor FW (U611)

All of the ICs listed above are ordered by a single Tektronix part number, as a single firmware kit. (**Each IC cannot be ordered separately**.) For the CSA 803A, the firmware kit number is 020-1717-XX.

To remove and replace the firmware ICs in your CSA 803A, follow these procedures:

**WARNING**

*Dangerous shock hazards may be exposed when the instrument covers are removed. Before proceeding, ensure that the CSA 803A PRINCIPAL POWER SWITCH is in the OFF position. Then, disconnect the instrument from the power source. Disassembly should only be attempted by qualified service personnel.*

**CAUTION**

*To prevent static damage to the instrument, observe all the special precautions mentioned under Static-Sensitive Classification in this section.*

Firmware Upgrade Procedure

To upgrade or replace your firmware ICs, complete the following steps:

☐ **Step 1:** Prepare the instrument for the firmware upgrade procedure as follows:

- Set the PRINCIPAL POWER SWITCH to OFF, and remove the power cord.
Corrective Maintenance

- Place the instrument on its right side (if not already in this position) to provide access to the boards upgraded in the firmware upgrade procedure that follows.

- **Step 2:** Access boards within the card cage as follows:
  - Ensure that the PRINCIPAL POWER SWITCH is set to OFF and the power cord is disconnected.
  - Remove the instrument’s top panel cover.
  - Remove the two plastic board guides from the top of the card cage (at the left rear of the instrument).
  - Remove the three Torx head screws that secure the CRT cover, and then remove the CRT cover (see Figure 6-4).

- **Step 3:** Upgrade the A15 MMU board firmware as follows:
  - Remove the A15 MMU board from the card cage. The A15 MMU board is typically located farthest from the outside (left side) of the instrument.
  - Locate the two firmware ICs, U140 and U150.

  **CAUTION**

  To prevent damage to the firmware ICs or the board, ensure pin 1 is positioned correctly when replacing components.

  **NOTE**

  Use the IC Insertion-Extraction Pliers shown in Figure 6-31 for removing and replacing the ICs. (Refer to Table 4-2, Test Equipment for the part number of these pliers.)

  Do not use the label on the IC for an index because it may be applied incorrectly. (See Figure 6-32 for the correct location of the index on the IC.)

  - Remove U140 and replace it with the upgraded IC. The last two-digit portion of the part number on the replacement IC should be the same as, or higher than, that on the removed IC. Ensure that pin 1 is oriented correctly.
  - Similarly replace U150 with the upgraded IC.
Step 4: Upgrade the A18 Memory board firmware as follows:

- Remove the A18 Memory board from the card cage. The A18 Memory board is typically located one slot from the outside (left side) of the instrument.
- On the A18 Memory board, replace the following ICs:
  
<table>
<thead>
<tr>
<th>Part Number</th>
<th>New Part Number</th>
</tr>
</thead>
<tbody>
<tr>
<td>U800</td>
<td>U900</td>
</tr>
<tr>
<td>U812</td>
<td>U910</td>
</tr>
<tr>
<td>U820</td>
<td>U920</td>
</tr>
<tr>
<td>U830</td>
<td>U930</td>
</tr>
</tbody>
</table>

  In each case, the last two-digits of the part number on the replacement IC should be the same as, or higher than, that on the removed IC. Again, ensure that pin 1 is oriented correctly.

- Return the A18 Memory board to its former location in the card cage.

Step 5: Upgrade the A5 Time Base/Controller board firmware as follows:

- Locate U300, U310, U400 and U410 on the A5 Time Base/Controller board (see Figure 6-30). These components are found near the bottom front of the instrument with the instrument positioned on its right side.
- Replace U300, U310, U400 and U410 on the A5 Time Base/Controller board.

  The last two-digit portion of the part number on the replacement IC should be the same as, or higher than, that on the removed IC. Again, ensure that pin 1 is oriented correctly.
Corrective Maintenance

☐ **Step 6:** Upgrade the A28 Acquisition MPU board firmware as follows:

- Remove the Acquisition unit from the instrument.
- Remove the A28 Acquisition MPU board from the Acquisition unit (see Figure 6-1 for the exact location of these boards in the Acquisition unit).
- Locate U611 on the A28 Acquisition MPU board (see Figure 6-28). This board is located in the card cage.
- Replace U611 on the A28 Acquisition MPU board.

The last two-digit portion of the part number on the replacement IC should be the same as, or higher than, that on the removed IC. Ensure that pin 1 is oriented correctly.

☐ **Step 7:** Verify the instrument serial number as follows:

- Locate the manufacturing jumper, J860, on the A5 Time Base/Controller board (see Figure 6-10), and install the terminal connector link.
- Connect a power cord to the instrument.
- Connect a terminal or controller to the CSA 803A. Refer to the CSA 803A User Manual for more information on this connection.
- Set the PRINCIPAL POWER SWITCH and ON/STANDBY switch to ON.
- Set necessary communication parameters; for example, baud rate.
- After the instrument is powered-on, to establish communication from the terminal or controller, enter the following commands (<CR> is the return key):
  ```
  e<CR>
  v<CR>
  ```
- Verify that the serial number on the instrument’s front panel matches the mainframe ID number in the Identify pop-up menu in the UTILITY major menu.
- If the numbers do not match, then enter the command:
  ```
  uid main:”BXXXXX”<CR>
  ```
  where XXXX corresponds to the serial number digits found on the front panel serial number marker.
- Verify that the proper ID is now displayed in the Identify pop-up menu, in the Utility major menu.
Step 8: Remove the procedure setup as follows:

- Set the PRINCIPAL POWER SWITCH to OFF.
- Remove the J860 manufacturing jumper on the A5 Time Base/Controller board.
- Replace the bottom instrument cover, and set the instrument upright.

Step 9: Perform the final power-on and verification as follows:

**NOTE**

You must now perform the power-on sequence again for the instrument to recognize the new manufacturing jumper configuration.

- Set the PRINCIPAL POWER SWITCH and ON/STANDBY switch to ON.
- Verify that the instrument powers-on and successfully completes the Self-Test diagnostics.

**NOTE**

If problems are encountered, then check for the following:

- all components are properly oriented in the sockets
- all component pins are properly seated
- components are installed in the correct location
Corrective Maintenance

Multi-Pin Connectors

Cover
End Tabs
Index Bevel
IC
Retaining Clip
Socket
Index Spring
Mating Recesses

Slam-Pack IC

Dual In-Line Package IC

Note: Match the index triangle on the multi-pin connectors with the corresponding square pad on the circuit board.

Figure 6-32: Multi-Pin Connector Orientation and Semiconductor Indexing Diagram
Cables and Connectors

A cabling diagram (see Figure 9-2) is provided to show the interconnecting cables between the various circuit boards, modules, and assemblies. Use this diagram as a reference when you are removing and/or replacing cables between these units.

Interconnecting Pins

Two methods of interconnection are used to electrically connect circuit boards with other boards and components. When the interconnection is made with a coaxial cable, a special end-lead connector plugs into a socket on the board. Other interconnections are made with a pin soldered into the board.

Two types of connectors are used for these interconnecting pins. If the connector is mounted on a plug-on board, a special socket is soldered into the board. If the connector is on the end of a lead, an end-lead pin connector that mates with the interconnecting pin is used. The following information provides the removal and replacement procedure for the various types of interconnecting methods.

Coaxial-Type End-Lead Connectors

Peltola and SMB connectors use color coding of wires, which may be helpful to correlate a Peltola connector to its socket on a circuit board. The wire insulation’s color, or its colored stripe, is the same as the color represented by the last digit of the JXX component number. (For example, a green wire would connect to a J05 socket.) Other Peltola connectors may have labels which designate their JXX component number.

Multi-Pin Connectors

These connectors are arranged so that the pin connectors used to connect the wires to the interconnecting pins are clamped to the ends of the associated leads.

Some of the pin connectors are grouped together and mounted in a plastic holder. The overall result is that these connectors are installed and removed as a multi-pin connector.

Pin 1 on multi-pin connectors is designated with a triangle (or arrowhead). A triangle, dot, or square printed on circuit boards denotes pin 1. When a connector is plugged onto a circuit board, the position or orientation of the
Corrective Maintenance

triangle on the multi-pin holder is determined by the index (triangle, dot or square) printed on the circuit board. Most board-mounted connectors have a square pad for pin 1. (See Figure 6-32.)

**NOTE**

*Match the index triangles on the multi-pin connectors with the corresponding square pads on the circuit board.*

*Some multi-pin connectors are keyed by a gap between the pin 1 and 3 positions in the holder. (A small plastic plug covers the pin 2 position on the end of the holder.) There is a corresponding gap between pins 1 and 3 on the circuit board.*

*Align the plug in the multi-pin holder with the gap between the circuit board pins. The connector is then ready to be installed.*

Many of the larger, multi-pin ribbon connectors have a red, blue, or other contrasting color line along one side of their attached wire cables. This line indicates the location of pins 1 and 2 and also the location of the corresponding triangle index mark on the connector.

Some of the gray-colored ribbon cables may have the number of their connectors stamped on them.

The ribbon connectors have the following two functions:

- to provide a strain relief for the wire connections. The wire ribbon is wrapped around a bar between the wire connections and the top of the connector. Strain is then felt between the wires and the top of the connector. This relieves most of the strain which would otherwise be felt on the wire connections.

- to provide a pull-tab to ease disconnection. The pull-tab is attached inside the connector. When the tab is pulled, even pressure is applied across the connector. The connector then separates from its holder easily.

**NOTE**

*To remove these ribbon connectors, grasp the pull-tab (fastened into the connector, if there) and pull it loose from the holder.*

*If there isn’t a pull-tab present in the connector, grasp the ends of the connector, instead, and pull it straight out from the connector socket.*
Checks After FRU Replacement

After any FRU has been replaced, that particular unit should be checked. Table 6-4 lists the required procedures to perform.

<table>
<thead>
<tr>
<th>FRU Replaced</th>
<th>Checks Required</th>
</tr>
</thead>
<tbody>
<tr>
<td>A1 Strobe Drive Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Internal Clock</td>
</tr>
<tr>
<td>A3 M/F Power Connect Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td>A4 Regulator Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Power Supply</td>
</tr>
<tr>
<td></td>
<td>Vertical Reference Voltage</td>
</tr>
<tr>
<td></td>
<td>Vertical Accuracy</td>
</tr>
<tr>
<td></td>
<td>System Vertical RMS Noise</td>
</tr>
<tr>
<td></td>
<td>Sweep Rate Accuracy</td>
</tr>
<tr>
<td></td>
<td>Triggering</td>
</tr>
<tr>
<td>A5 Time Base/Controller Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td>A8 CRT Driver Board</td>
<td>Display</td>
</tr>
<tr>
<td>A9 Touch Panel Assembly</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td>A10 Front Panel Control Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td>A11 Front Panel Button Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td>A12 Rear Panel Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td>A13 Mother Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td>A14 Input/Output Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Real Time Clock</td>
</tr>
<tr>
<td>A15 MMU Board</td>
<td>Power-On Diagnostics</td>
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<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td>A17 Executive Processor Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td>A18 Memory Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
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</table>
Table 6-4: Checks Required After FRU Replacement (Cont.)

<table>
<thead>
<tr>
<th>FRU Replaced</th>
<th>Checks Required</th>
</tr>
</thead>
<tbody>
<tr>
<td>A19 Strobe/TDR Buffer Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Sweep Rate Accuracy</td>
</tr>
<tr>
<td></td>
<td>Internal Clock</td>
</tr>
<tr>
<td>A20/A21 Head Interconnect (Power Only) Boards</td>
<td>Functional check of a power-only device such as an SD-42, SD-46, or SD-51 Sampling Head</td>
</tr>
<tr>
<td>A22/A23 Head Interconnect Boards</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Vertical Accuracy</td>
</tr>
<tr>
<td></td>
<td>System Vertical RMS Noise</td>
</tr>
<tr>
<td>A26 M/F Acquisition Interconnect Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Vertical Reference Voltage</td>
</tr>
<tr>
<td>A27 Acquisition Analog Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Vertical Accuracy</td>
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<tr>
<td></td>
<td>System Vertical RMS Noise</td>
</tr>
<tr>
<td>A28 Acquisition MPU Board</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td>Firmware ICs</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
<td></td>
<td>Extended Diagnostics</td>
</tr>
<tr>
<td>Cathode Ray Tube (CRT)</td>
<td>Display</td>
</tr>
<tr>
<td>Power Supply Module</td>
<td>Power-On Diagnostics</td>
</tr>
<tr>
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<td>Extended Diagnostics</td>
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<td></td>
<td>Power Supply</td>
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<td></td>
<td>System Vertical RMS Noise</td>
</tr>
<tr>
<td></td>
<td>Sweep Rate Accuracy</td>
</tr>
</tbody>
</table>
Diagnostic Troubleshooting

This section provides the information necessary to troubleshoot a faulty CSA 803A to the field replaceable unit (FRU) level. In most cases a FRU is a circuit board. The primary means for troubleshooting is to use the error index code output from the Kernel diagnostics and cross-reference it to the suspect circuit boards in the following tables, or to use the built-in FRU help function available in Extended Diagnostics. In addition, conventional troubleshooting techniques are described at the end of this section to help identify a faulty A4 Regulator board, CRT, Power Supply module, A13 Mother board, or A8 CRT Driver board.

Diagnostics Overview

Each subsystem processor (Executive, Display, Time Base, and Acquisition) executes a set of Kernel diagnostics prior to the Self-Test diagnostics. After the Acquisition processor has verified its support circuitry, it tries to establish communication with the Time Base processor. After the Time Base processor has verified its critical support circuitry, and after it has attempted to communicate with the Acquisition processor, the Time Base processor attempts to communicate with the Executive processor. Likewise, the Display processor attempts to communicate with the Executive processor after successfully executing its Kernel diagnostics.

After a processor has successfully completed its Kernel diagnostics and established communications with the next order processor (for example, Acquisition-to-Time Base and Time Base-to-Executive), then Self-Test diagnostics execute to verify the more global functionality of the processor’s hardware system. After all the Self-Test diagnostics are executed, any failures cause the CSA 803A to enter Extended Diagnostics and to display the error index codes in a diagnostic menu. Extended diagnostics contains tests which are a superset of the Self-Test.

The Kernel diagnostics (low-level Self-Test diagnostics) and Self-Test/Extended Diagnostics produce and format error index codes differently, so they are covered separately. Kernel diagnostics error index codes for each subsystem are produced and read quite differently from each other.

Note that some of these tests that may indicate faulty FRU(s) are not executed automatically during the Self-Test diagnostics (that is, some errors codes are only generated by manually selecting tests or Extended Diagnostics).
Kernel Diagnostics

Kernel diagnostics are executed each time the front panel ON/STANDBY switch is set to ON. The CSA 803A performs power-on diagnostics on its microprocessor subsystems and Self-Test diagnostics on all of its major circuits.

When Kernel diagnostics begin, the messages **Diagnostics in Progress** and **Comm Test in Progress** are displayed. If the CSA 803A is powered-on from a cold condition, then the diagnostics may complete before the CRT is warmed up and able to display these messages.

Diagnostic routines are performed in parallel on each of the instrument's processor subsystems: Display, Executive, Time Base, and Acquisition. Following successful execution of their Kernel diagnostics, the Acquisition processor attempts to communicate with the Time Base processor and the Time Base and Display processors attempt to communicate with the Executive processor.

The Executive processor will continue Self-Test diagnostics even if it is the only processor that has successfully completed its Kernel diagnostics.

In the case where the Display processor has not communicated successfully with the Executive processor, the message indicating that Self-Test diagnostics are beginning will not appear on the screen. Kernel diagnostic failures may be indicated by the message, **Dsy Kernel Failure**, or **Comm Test in Progress** on the screen and/or a single high-low beep and illuminated menu buttons.

If either the Display, Time Base, or Acquisition processors do not successfully pass their communications stage, then the CSA 803A automatically enters Extended Diagnostics at the end of the Self-Test diagnostics. If the Display processor is at fault, then the Extended Diagnostic menu will not appear on the screen.

The Kernel diagnostic tests execute concurrently in all three subsystem processor circuits at power-on. Hardware critical to diagnostic operation is verified, such as ROM, RAM, DMAs, timers, and interrupt control circuitry. For the Executive Processor, this requires checking basic operation for most boards in the card cage (that is, those boards plugged in to the A13 Mother board). The last step of Kernel diagnostics for the Display, Time Base, and Acquisition processors is to verify communication. Within each processor, all Kernel diagnostics must execute without failures before the Self-Test diagnostics can execute. However, the Executive processor continues with its Self-Test diagnostics despite a communication failure encountered with the Display and/or Time Base processors; additionally, the Time Base processor does not halt when it has a communication failure with the Acquisition processor.

Since the condition of the instrument is unknown at power-on, when a kernel failure occurs, Kernel diagnostics in the Executive, Time Base, and Acquisition processors do not attempt to display error index codes. Instead, these processors generate hexadecimal (hex) numbers that are read as a series of binary bits, such as XXX1 0101 (hex error code 15\text{hex}) for the Executive processor, 0100 (hex error code 4\text{hex}) for the Time Base processor, or
10 (hex error code $2_{\text{hex}}$) for the Acquisition processor, from either internal test points or LEDs. Refer to Tables 6-10, 6-15, and 6-16 for more information and examples of these hex error codes.

The Display kernel diagnostics display an error message on the screen giving the name of the test that failed. For example, the following message indicates that the DMA 0 test failed:

**Dsy Kernel Failure**

**DMA 0**

If the error message does not appear on the screen, the error index code can be obtained from the status LEDs and pins on the A15 Memory Management Unit board (see Figure 6-32).

---

**Self-Test/Extended Diagnostics**

Refer to the Power-On Diagnostics procedure for information about Self-Test/Extended Diagnostics.

**Extended Diagnostics Menu Structure**

The menu structure determines the format of the error index codes. The Extended Diagnostics menus are in a four-level hierarchy with the Subsys (that is, the Subsystem) menu at the highest level. This four-level Subsystem, Block, Area, and Routine menu hierarchy generates the error index codes. Each subsystem in the Subsystem menu can be selected and tested if there are functional processor(s) and communication paths. Each subsystem is broken into a number of parts, or circuit blocks, in the Block menu for the selected subsystem. In a similar manner, each block is broken into a number of circuit areas in the Area menu, the third level. The fourth and lowest menu level is the Routine menu, which contains the smallest test unit that can be selected and executed.

**Extended Diagnostics Error Index Codes**

The error index codes for the Extended Diagnostics are five-digit codes whose first character indicates the subsystem tested. The last four digits are hexadecimal ($_{\text{hex}}$) numbers that indicate the Block, Area, Routine, and specific failure mode. For example, E2321 is decoded as follows:

- **E** Subsystem — Executive
- **2** Block name — Front Panel
- **3** Area name — Soft Keys
- **2** Routine name — Column Open
- **1** Failure Identity — specific failure mode
Table 6-5 lists the subsystem characters of the Extended Diagnostic error index codes.

<table>
<thead>
<tr>
<th>Description</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>E</td>
<td>Executive</td>
</tr>
<tr>
<td>D</td>
<td>Display</td>
</tr>
<tr>
<td>T</td>
<td>Time Base</td>
</tr>
<tr>
<td>m</td>
<td>Mainframe Acquisition</td>
</tr>
</tbody>
</table>

Front panel controls are active during the Self-Test diagnostics sequence; any disturbance may cause a test failure, forcing the CSA 803A into the Extended Diagnostics mode. Touch the **(E)Exit** label twice in succession to remove the Extended Diagnostics menu and resume normal operation. In situations where the Display, Time Base, or Acquisition processors have failed their kernel diagnostics, exiting diagnostics to normal operation will not be possible.

After the Self-Test/Extended Diagnostic programs have executed, any resultant error index codes appear on the display next to the associated subsystem name in the Extended Diagnostics menu. Each subsystem that had a failure gives the first error encountered and the number of failures in the subsystem.

To get a more complete list of the error index codes in a subsystem, touch the selector of a failed subsystem (if the failed subsystem is not already selected) and then touch the Block selector. Touching the Area and then Routine selectors shows the lowest level test routines in the selected Block. The currently selected Subsystem, Block, Area, and Routine are shown below their labels at the bottom of the Extended Diagnostics menu. Several function and operating mode selectors are also available at the bottom of the screen. When certain test routines are selected, some of these operating modes are non-selectable. Additionally, when some of the operating modes are set to certain states, some of the test routines may become non-selectable.

The function and mode operators are the following:

- **(?)Help** — displays a list of FRUs for the currently selected routine. If the routine had a failure, then the error index code for that routine is also displayed. The FRUs are normally listed as the most-to-least probable cause for errors in the routine. In some cases, the FRUs are listed according to their ease-of-replaceability in order to minimize the time required to identify the faulty FRU.

Within this menu, you can scan forward to the next routine or to the next failure by touching the appropriate selectors in the lower portion of the screen (which functions like a simple keypad). Scanning continues in a circular fashion through all available subsystems.
Upon exiting this menu, the instrument returns to the same menu level (that is, Subsystem, Block, Area, or Routine) that it was at before the help function was invoked. However, the displayed menu may be different if any scanning was performed.

- **(--)Delete** — places an execution mark on the currently selected menu name (in the upper menu area) and all items beneath it, down to the Routine level. This inhibits the actual execution of these routines, when **(r)Run** is invoked.

  Visually, execution marks are displayed on the screen as an asterisk (*) immediately to the left of the menu name (in the upper menu area). If one, but not all, menu names in a menu are marked with an asterisk, then the name of the menu at the next highest level (that is, from Area to Block) is preceded by an execution mark of a minus (–).

- **(+)Add** — removes the execution mark, if present, on the currently selected menu name and all execution marks on items (that is, blocks, areas, or routines) below the currently selected menu name (down to the Routine level). The execution mark, if present, will change from an asterisk (*) or minus (–) to a space.

- **(D)Debugger** — normally cannot be selected and is used by qualified service personnel only.

- **E(Exit)** — terminates Extended Diagnostics and returns the instrument to normal operating mode, but only if this selector is touched twice in succession. The first touch causes a confirmation prompt to appear at the top of the screen; the second touch causes the actual termination of the Extended Diagnostics.

- **(p)Loop** — toggles On and Off. When On, the selected test(s) is executed continuously with the number of iterations displayed.

- **(t)Terse** — toggles On and Off. When On, tests in the loop mode execute at the fastest rate, but the iteration (i.e. Loop) readout is not updated until the test is stopped (by touching the screen or a button).

- **(x)All** — toggles On and Off. When On, all tests in the current menu are selected to execute when started.

- **(s)Stop on Err** — toggles On and Off. When On, testing stops after the first failed test completes.

- **(r)Run/(q)Quit** — starts or stops the currently selected tests.
Diagnostic Menus

The upper portion of the display screen is used to display diagnostic menus. Menus are comprised of menu items and menu fields. Menu items are rows of items that can be selected, while menu fields are columns of status information.

There are four tiers of menus which may appear in the menu area (only one is present at any given time): the Subsystem, Block, Area and Routine menus. Upon entry into any menu, there is always one menu item that is selected. And, only one menu item can be selected at any given time.

The following field descriptions apply for Subsystem, Block, Area and Routine menus.

Subsystem, Block and Area menus are divided into the following four fields: Execution Mark, Title, Error Index Code, and Failure Count. The Routine menu has these and three additional test result fields.

- **Execution Mark** — is a one character field preceding the Title field and succeeding the keystroke selector identification. The three values of this field and their meanings are as follows:
  - ‘ ’: All routines in this Subsystem, Block, or Area are available for execution
  - ‘*’: No routines in the Subsystem, Block, or Area are available for execution
  - ‘–’: One or more routines in the Subsystem, Block, or Area are available for execution

Refer to the Delete and Add descriptions for further information.

- **Title field** — contains the name of individual hardware Subsystems, Blocks, Areas, or Routines.

- **Error Index Code field** — contains an index code. The index field may contain one of five types of status (indicating one of four types of tests), providing the following information:
  - “pass”: An automatic test has executed and did not fail.
  - “Yxxx”: A test has failed and the failure encountered in subsystem Y is xxxx. This index code contains one digit each for Subsystem identification, Block identification, Area identification, Routine identification, and a Test identification that gives some specific information about the failure.
  - “****”: An automatic test has not yet been executed. When the test does execute, the test will provide pass or Yxxx failure status.
  - “– – – –”: The test requires you to perform some type of test setup using the RS-232-C loopback connector. When executed, this status provides pass or Yxxx failure status. To execute this test, you must select it.
“ ” (blank) This status indicates that the test requires action from
the user (such as the front panel verification tests), or
that the test is for stimulus only (such as the manual
calibration tests). This status does not provide failure
status. To execute this test, select it individually.

“????” This status indicates that an option was found that was
not present in the current instrument configuration or
that a subsystem was found that did not have a work-
ing communication path.

- **Failure Count field** — indicates the total number of routine failures (one
  per routine) currently encountered in the Subsystem, Block, or Area.
  Thus, the Failure Count will never be more than the total number of
  routines in the subsystem. If no tests have been executed or no failures
  have occurred, then this field is blank. Since the failure count field is an
  indication of all routines that have failures, it is possible to have a failure
  field count greater than the loop count (for example, there may be five
  routine failures after the first loop).

  A field display of **65535+** indicates that the Failure Count field has gone
  beyond 65534 and that an overflow condition has occurred.

The following field descriptions apply only to Routine menus.

- **Test Results fields** — contain information useful for troubleshooting.
  One of the following formats is used:

  - test address, expected data, and actual data
  - expected data lower bound (minimum), expected data upper bound
    (maximum) and actual data

**Diagnostic Menu Hardcopy**

Press the hardcopy button on the front panel to make hardcopy of a diag-
nostic menu. The hardcopy is sent to a printer attached to the PRINTER
port. Screen hardcopies can also be obtained from other menus (for exam-
ple, help menus, interactive test menus, and hardware debugger menus).

After a hardcopy is output, a Form Feed is issued to the printer. If no printer
is attached or the printer can not print (for example, if the printer is off line
or if the printer is out of paper,) then the following warning is shown in the
Input/Prompt area:

**Hardcopy absent or off line.**

The hardcopy function is unavailable for some tests requiring human inter-
action, such as touch panel interactive tests, various display tests, and
CRT/touch panel calibration patterns.

The knobs control the screen intensity during the four main diagnostics
menu levels. The TOUCH PANEL ON/OFF button enables/disables the touch
panel from responding to user touches.
Diagnostic Troubleshooting

Diagnostic Terminal Mode (RS-232-C)

The RS-232-C port drives a terminal which conforms to the ANSI 3.64 standard. In this mode, the terminal provides a screen-driven, interactive human interface.

This mode is useful when either the display or touch panel is not functioning properly, or when it is desired to remotely use the diagnostics with a modem and phone link.

There are several single terminal keystroke commands which are equivalent to front panel buttons or are terminal-only commands, all of which do not appear on any of the display screens. The following terminal keystrokes do appear on the screen and are shown in quotes:

- `'B< baud rate>< cr>'` — this keystroke, followed by the baud rate and carriage return, allows you to change the default baud rate to any one of the allowable product baud rates (300, 1200, 9600, 19200). The default power-up baud rate is determined from the position of two internal jumpers located on the A14 I/O board. (The Default setting is for 9600 baud.)

- `'T'` — this keystroke toggles the screen output between the current screen display and an ANSI compatible terminal. The terminal should initially be set in its ANSI mode.

- `'K'` — this keystroke toggles the screen output between the current screen display and a Tektronix 4x05 terminal (4105, 4205).

- `'L'` — this keystroke toggles the screen output between the current screen display and a Tektronix 4x07 terminal (4107, 4207).

- `'H'` — this keystroke produces a hardcopy of the current diagnostic menu as described earlier.

- `'O'` — this keystroke disables/enables the touch panel from responding to the user's touches. It is equivalent to the TOUCH PANEL ON/OFF button.

- `'Q'` — this keystroke, when used in interactive test menus, stops and starts the display information in the keypad prompt area. This keystroke is equivalent to the ACQUISITION RUN/STOP button in those menus.

To gain access to the terminal mode diagnostics, the instrument must be in the Extended Diagnostic mode.

To exit the terminal mode, either recycle the power, enter the (Exit) keystroke twice to begin normal operation, or enter the appropriate 'L', 'T', or 'K' keystroke to transfer the screen output back to the instrument display.
**System Mode (GPIB & RS-232-C)**

The Self-Test diagnostics and Extended Diagnostics are accessible using the two commands listed in Table 6-6.

<table>
<thead>
<tr>
<th>Table 6-6: System Mode Commands</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Header</strong></td>
</tr>
<tr>
<td>TEST</td>
</tr>
<tr>
<td>TEST</td>
</tr>
<tr>
<td>TEST</td>
</tr>
<tr>
<td>DIAG?</td>
</tr>
</tbody>
</table>

The **TEST** command invokes Self-Test diagnostics or Extended Diagnostic execution. The **TEST** command without arguments initiates Self-Test diagnostics. The **TEST** command with argument **XTND** initiates Extended Diagnostics.

Refer to the CSA 803A and 11801B Programmer Manual for more information on TEST and DIAG command syntax and usage.

The return of one of two event codes listed in Table 6-7 to the GPIB and RS-232-C ports signals that diagnostic testing is complete.

<table>
<thead>
<tr>
<th>Table 6-7: Event Code Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Event Code</strong></td>
</tr>
<tr>
<td>460</td>
</tr>
<tr>
<td>394</td>
</tr>
</tbody>
</table>

In either case, a GPIB/RS-232-C controller may obtain pass/fail information through the **DIAG?** query.

The **TEST** command with argument **MAN** initiates the Extended Diagnostics similarly to entering Extended Diagnostics through the front panel UTILITY menu. The primary use of this command is to provide the remote operator a convenient way of accessing the diagnostics through the normal RS-232-C interface so that the operator can use the Diagnostic Terminal Mode to do remote testing.

---

**CAUTION**

The **TEST** command with argument **MAN** violates normal GPIB protocols in that, when used, the instrument becomes non-responsive to further GPIB commands until normal operation is resumed.
The **DIAG?** query returns pass/fail information from the most recent invocation of Self-Test diagnostics or Extended Diagnostics. Examples of possible responses and explanations, are as follows:

**DIAG PASSED: NONE**

This response indicates that the Self-Test diagnostics or Extended Diagnostic operation did not detect any test faults.

**DIAG FAILED: E1311, E1711, E1721, E1731**

This response indicates that the Extended Diagnostic operation detected test faults.

**DIAG FAILED: E1311, D1211, T1431**

This response indicates that the Self-Test diagnostics or Extended Diagnostic operation detected test faults.

**DIAG BYPASSED**

This response indicates that a power-on has occurred and that Self-Test diagnostics were bypassed through a jumper on the A14 I/O board.
Battery Testing

The CSA 803A holds four lithium batteries to provide power when the instrument is turned off. The following discussions provide criteria for determining if a battery has exceeded its lifetime, and is thus causing incorrect instrument operation. (A battery’s lifetime will typically exceed five years.) If the battery voltage measures (at 20°C) equal to or greater than the voltages listed in this section, then the circuit should operate correctly from 0°C to 50°C. (These voltage measurements are taken with the instrument power off.)

Battery BT130 provides power for the real time clock on the A14 I/O board. If the clock begins to lose time rapidly when the instrument is turned off or the diagnostics report that the Real Time Clock (E42XX) has failed, the battery should be tested. If the battery voltage measures less than 2.7 V, then the most likely source of the problem is the battery and you should follow the instructions for battery disposal earlier in this section.

Battery BT150 provides power for the nonvolatile RAM (NVRAM) on the A18 Memory board. If the diagnostics consistently reports an NVRAM Battery (E141X) failure over multiple power-ons, then the battery should be tested. If the battery voltage measures less than 2.7 V, then the most likely source of the problem is the battery and you should follow the instructions for battery disposal earlier in this section.

Sockets for devices U500 and U511 provide power for the NVRAM on the A5 Time Base/Controller board. If the diagnostics consistently report a Static RAM Battery (T1331) failure over multiple power-ons, then the batteries should be tested. If either one of the battery voltages measures less than 2.1 V, as measured on pin 28 (Vcc), follow the instructions for battery disposal earlier in this section. (It is recommended that both batteries be replaced at the same time.)

NOTE

Turning the instrument off while Extended Diagnostics is executing one of the NVRAM memory tests may cause failure of the NVRAM battery test. If the diagnostics report an NVRAM battery failure, then exit the diagnostics. This will rewrite the confidence words into the NVRAM. Turn off the instrument for at least one hour. Then, turn the instrument back on. If the diagnostics still indicate an NVRAM battery failure, then the battery should be tested.
Clearing NVRAM

Before a power-up Self-Test begins — but just after the Executive processor has run its Kernel Diagnostics — the front panel buttons are scanned by the Executive processor. If the Executive processor senses that the WAVEFORM and TRIGGER buttons, and only these two buttons, are pressed in (i.e., closed) during this time, then the Executive processor resets its NVRAM to a default state, the Teksecure Erase Memory function. This essentially destroys all stored settings and stored traces in NVRAM. When this occurs, the NVRAM is initialized by filling all but a few locations with a default value. The following items are left intact after the NVRAM is reset:

- Number of instrument power-ons (POWERON?)
- Instrument power on time (UPTIME?)
- Mainframe serial number (UID? MAIN)

Field Replaceable Unit (FRU) Guide

This section correlates Kernel Diagnostic error index codes with the components or boards suspected of causing each error. The suspect FRU(s) for Self-Test/Extended Diagnostics error index codes are identified by using the built-in FRU help function (?Help, described under Self-Test/Extended Diagnostics.

The FRU(s) in the Suspect board category in the following error index tables are listed in most-to-least probable cause order. If any diagnostic errors occur, inspect the suspect FRU for loose connections and components. Then, repeat the Diagnostic test. If any diagnostic errors occur again, replace the suspect FRU(s) with a known good FRU or FRUs. Check that the new FRU is configured exactly like the old one and that any installed firmware matches the version in the old FRU.

The error index codes and tests are divided into four groups based on the four processor subsystems: Executive, Display, Time Base, and Acquisition. Each subsystem group has a table of kernel diagnostic error index codes. In addition, the Executive has a table of manual test error index codes, which help extend the confidence level of instrument functionality.

If necessary, kernel error index codes for the Executive and Display can be read as TTL logic levels on circuit board pins using a logic probe.
FRU Name Abbreviations

Abbreviations of FRU names are listed in Table 6-8.

<table>
<thead>
<tr>
<th>FRU</th>
<th>Board</th>
<th>Board No</th>
</tr>
</thead>
<tbody>
<tr>
<td>STROBEDR</td>
<td>M/F Strobe Drive board</td>
<td>(A1)</td>
</tr>
<tr>
<td>MFPOWER</td>
<td>M/F Power Connect board</td>
<td>(A3)</td>
</tr>
<tr>
<td>REG</td>
<td>Regulator board</td>
<td>(A4)</td>
</tr>
<tr>
<td>TBC</td>
<td>Time Base/Controller board</td>
<td>(A5)</td>
</tr>
<tr>
<td>CRTSOC</td>
<td>CRT Socket board</td>
<td>(A7)</td>
</tr>
<tr>
<td>CRTDR</td>
<td>CRT Driver board</td>
<td>(A8)</td>
</tr>
<tr>
<td>TOUCH</td>
<td>Touch Panel assembly</td>
<td>(A9)</td>
</tr>
<tr>
<td>FPCTRL</td>
<td>Front Panel Control board</td>
<td>(A10)</td>
</tr>
<tr>
<td>FPBUT</td>
<td>Front Panel Button board</td>
<td>(A11)</td>
</tr>
<tr>
<td>REAR</td>
<td>Rear Panel assembly</td>
<td>(A12)</td>
</tr>
<tr>
<td>MOTHER</td>
<td>Mother board</td>
<td>(A13)</td>
</tr>
<tr>
<td>IO</td>
<td>Input/Output board</td>
<td>(A14)</td>
</tr>
<tr>
<td>MMU</td>
<td>Memory Management Unit board</td>
<td>(A15)</td>
</tr>
<tr>
<td>EXP</td>
<td>Executive Processor board</td>
<td>(A17)</td>
</tr>
<tr>
<td>MEM</td>
<td>Memory board</td>
<td>(A18)</td>
</tr>
<tr>
<td>STROBEBUF</td>
<td>Strobe/TDR Buffer board</td>
<td>(A19)</td>
</tr>
<tr>
<td>HEAD</td>
<td>Head Interconnect (Power Only) bo</td>
<td>(A20/A21)</td>
</tr>
<tr>
<td>HEAD</td>
<td>Head Interconnect board</td>
<td>(A22/A23)</td>
</tr>
<tr>
<td>ACQANALOG</td>
<td>Acquisition Analog board</td>
<td>(A27)</td>
</tr>
<tr>
<td>ACQMPU</td>
<td>Acquisition MPU board</td>
<td>(A28)</td>
</tr>
<tr>
<td>MFACQCON</td>
<td>M/F Acquisition Interconnect board</td>
<td>(A26)</td>
</tr>
</tbody>
</table>
Component and Module Name Abbreviations

Abbreviations of component and modules names are listed in Table 6-9.

<table>
<thead>
<tr>
<th>FRU</th>
<th>Board</th>
</tr>
</thead>
<tbody>
<tr>
<td>CRT</td>
<td>Cathode Ray Tube</td>
</tr>
<tr>
<td>FW</td>
<td>Executive, Display, Time Base, or Acquisition Firmware</td>
</tr>
<tr>
<td>SDI</td>
<td>Serial Data Interface IC</td>
</tr>
<tr>
<td>BATTERY</td>
<td>Lithium Battery</td>
</tr>
<tr>
<td>PS</td>
<td>Power Supply Module</td>
</tr>
</tbody>
</table>

**NOTE**

*The Executive, Display, Time Base, and Acquisition firmware is packaged in a single firmware (FW) kit; the individual parts are not available as separate components.*
Executive Subsystem Error Codes

Error index codes for the Executive subsystem are listed in Table 6-10 along with the suspected FRUs.

Table 6-10: Executive Processor Kernel Error Index Codes

<table>
<thead>
<tr>
<th>Error Index_{hex}</th>
<th>Hybrid/IC FRUs</th>
<th>Suspect Board FRUs</th>
</tr>
</thead>
<tbody>
<tr>
<td>1F – 1D</td>
<td>MEM, EXP</td>
<td></td>
</tr>
<tr>
<td>1C – 19</td>
<td>FW</td>
<td>MEM</td>
</tr>
<tr>
<td>18 – 16</td>
<td>IO, EXP</td>
<td></td>
</tr>
<tr>
<td>15</td>
<td>EXP</td>
<td></td>
</tr>
<tr>
<td>14</td>
<td>EXP, MEM</td>
<td></td>
</tr>
<tr>
<td>13</td>
<td>FPCTRL, IO, MPU</td>
<td></td>
</tr>
<tr>
<td>12</td>
<td>IO, EXP</td>
<td></td>
</tr>
<tr>
<td>11</td>
<td>IO, EXP</td>
<td></td>
</tr>
<tr>
<td>10 – 0E</td>
<td>REAR, IO, MPU</td>
<td></td>
</tr>
<tr>
<td>0D</td>
<td>MMU, EXP</td>
<td></td>
</tr>
<tr>
<td>0C</td>
<td>EXP, MEM</td>
<td></td>
</tr>
<tr>
<td>0B</td>
<td>REAR, IO, EXP</td>
<td></td>
</tr>
</tbody>
</table>

Bit patterns for the hexadecimal error index codes listed in Table 6-10 are displayed with the front panel MENUS LEDs in bottom-to-top bit order. The STORE/RECALL label represents the MSB (most significant bit) and the WAVEFORM label represents the LSB (least significant bit). When lit, the LEDs represent a one.

For example, error index code $12_{hex}$ causes the STORE/RECALL and TRIGGER LEDs to light.

The status LEDs (DS306 and DS307) on the A17 Executive Processor board will flash while the Kernel diagnostic tests are executing. If a kernel failure is detected, then one or both LEDs will remain on. Table 6-11 lists the various LED configurations and their significance.

Reading the Executive processor subsystem error bits from the A17 Executive Processor board test points TP201 (MSB) to TP205 (LSB) is also possible. See Figure 6-33 for the location of these test points and status LEDs. The bits are high (+5 V) true.
Table 6-11: Executive Processor Status LED Configuration

<table>
<thead>
<tr>
<th></th>
<th>DS307</th>
<th>DS306</th>
<th>Significance</th>
</tr>
</thead>
<tbody>
<tr>
<td>ON</td>
<td>ON</td>
<td></td>
<td>Power-On</td>
</tr>
<tr>
<td>ON</td>
<td>OFF</td>
<td></td>
<td>Kernel Tests Executing</td>
</tr>
<tr>
<td>OFF</td>
<td>ON</td>
<td></td>
<td>Kernel Tests Failed</td>
</tr>
<tr>
<td>OFF</td>
<td>OFF</td>
<td></td>
<td>Kernel Tests Finished</td>
</tr>
</tbody>
</table>

Figure 6-33: A17 Executive Processor Board Test Point and Status LED Locations

Table 6-12 lists the Executive processor manual tests and verification procedures. If the conditions specified in the verification procedure listed are not met, then the suspect FRUs can be found using the (?) Help function.

These tests are performed manually and produce no error index code displays. They are included to help you locate faulty boards that the Kernel or Self-Test diagnostics possibly did not locate. Interconnections such as the A13 Mother boards cables and the power supply boards are not listed; however, these interconnections are considered as possible problem sources.
### Table 6-12: Executive Processor Manual Tests

<table>
<thead>
<tr>
<th>Test</th>
<th>Verification Procedure</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Front Panel</strong></td>
<td></td>
</tr>
<tr>
<td>Verify</td>
<td>This test allows you to interactively press the hard keys to verify their operation. This test verifies the operation of a key with both visual and audio feedback.</td>
</tr>
<tr>
<td>Hard Keys</td>
<td>This test requires operator interaction and can be executed only in the <strong>Routine</strong> pop-up menu with the <strong>All</strong> and <strong>Loop</strong> modes set to <strong>Off</strong>. Once this test is invoked, you can press any of the hard keys on the instrument and verify that the corresponding image of the key on the screen is highlighted, that the associated LED is turned on, and that an audio click is generated.</td>
</tr>
<tr>
<td><strong>Soft Keys</strong></td>
<td>This test allows you to interactively touch any of the soft keys and verify their operation. This test verifies the operation of a key with both visual and audio feedback.</td>
</tr>
<tr>
<td></td>
<td>This test requires operator interaction and can be executed only in the <strong>Routine</strong> pop-up menu with the <strong>All</strong> and <strong>Loop</strong> modes set to <strong>Off</strong>. Once this test is invoked, you can touch any of the soft keys in the instrument and verify that a touch box is drawn around the soft key on the screen and that an audio click is generated.</td>
</tr>
<tr>
<td><strong>Knobs</strong></td>
<td>This test allows you to turn either of the knobs and verify their operation. This test verifies knob movement with visual feedback.</td>
</tr>
<tr>
<td></td>
<td>This test requires operator interaction and can be executed only in the <strong>Routine</strong> pop-up menu with the <strong>All</strong> and <strong>Loop</strong> modes set to <strong>Off</strong>. Once this test is invoked, you can turn either of the knobs on the instrument and verify that the corresponding knob pointer on the screen rotates and that the associated counter value changes.</td>
</tr>
<tr>
<td><strong>Test Pattern</strong></td>
<td></td>
</tr>
<tr>
<td>Gray Scale</td>
<td>These tests allow you to examine and adjust the CRT color.</td>
</tr>
<tr>
<td>Green Grid</td>
<td>These tests require operator interaction and are only executable in the <strong>Routine</strong> pop-up menu with the <strong>All</strong> and <strong>Loop</strong> modes set to <strong>Off</strong>. Once one of the tests is invoked, you can examine/adjust the CRT by following the procedure outlined in the <strong>Adjustments</strong> section.</td>
</tr>
<tr>
<td>White Grid</td>
<td></td>
</tr>
<tr>
<td>Red Display</td>
<td></td>
</tr>
<tr>
<td>Green Display</td>
<td></td>
</tr>
<tr>
<td>Blue Display</td>
<td></td>
</tr>
<tr>
<td>HV Reg Display</td>
<td></td>
</tr>
</tbody>
</table>
### Table 6-12: Executive Processor Manual Tests (Cont.)

<table>
<thead>
<tr>
<th>Test</th>
<th>Verification Procedure</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Internal I/O</strong></td>
<td></td>
</tr>
<tr>
<td>Tone Gen</td>
<td></td>
</tr>
<tr>
<td>Ramp Tone</td>
<td>This test verifies the capability of the instrument to generate tones through its internal speaker. This test requires operator interaction and can be executed only in the <strong>Routine</strong> pop-up menu with the <strong>Loop</strong> mode set to <strong>On</strong> and the <strong>Terse</strong> and <strong>All</strong> mode set to <strong>Off</strong>. After invoking this test, you should verify that a high-speed clicking sound occurs.</td>
</tr>
<tr>
<td><strong>Real Time Clk</strong></td>
<td></td>
</tr>
<tr>
<td>Calibrate</td>
<td>This test allows you to check and adjust the Real Time Clock period. This test requires operator interaction and can be executed only in the <strong>Routine</strong> pop-up menu with the <strong>All</strong> and <strong>Loop</strong> modes set to <strong>Off</strong>. Once this test is invoked, you can examine/adjust the real time clock period following the procedure outlined in the Real Time Clock procedure in the <strong>Adjustments</strong> section.</td>
</tr>
<tr>
<td><strong>External I/O</strong></td>
<td></td>
</tr>
<tr>
<td>Printer</td>
<td></td>
</tr>
<tr>
<td>Pattern</td>
<td>This test prints a set of patterns (all printable ASCII characters) to help you verify the external printer interface. This test requires operator interaction and can be executed only in the <strong>Routine</strong> pop-up menu with the <strong>All</strong> mode set to <strong>Off</strong>. Before executing this test, you should connect a Centronics-compatible printer to the PRINT-ER connector on the rear panel of the instrument.</td>
</tr>
<tr>
<td><strong>RS-232</strong></td>
<td></td>
</tr>
<tr>
<td>Extern Loop</td>
<td>This test verifies parts of the external RS-232-C interface. This test requires operator interaction and can be executed only in the <strong>Routine</strong> pop-up menu with the <strong>All</strong> mode set to <strong>Off</strong>. Before executing this test, you should plug an external loopback connector on the RS-232-C connector on the rear panel of the instrument.</td>
</tr>
</tbody>
</table>
Table 6-12: Executive Processor Manual Tests (Cont.)

<table>
<thead>
<tr>
<th>Test</th>
<th>Verification Procedure</th>
</tr>
</thead>
<tbody>
<tr>
<td>GPIB</td>
<td>These tests verify the Executive processor interface to the internal GPIB circuitry. The major external GPIB functions are not tested.</td>
</tr>
<tr>
<td>Inrpt Reset</td>
<td>This test requires operator interaction and can be executed only in the Routine pop-up menu with the All and Loop modes set to Off. Before executing this test, you should disconnect the GPIB connector from the instrument.</td>
</tr>
</tbody>
</table>

Display Subsystem Error Index Codes

The Display subsystem error index codes and suspect FRUs are listed in Table 6-13.

Table 6-13: Display Processor Kernel Error Index Codes

<table>
<thead>
<tr>
<th>Error Index&lt;sub&gt;hex&lt;/sub&gt;</th>
<th>Suspect Hybrid/IC FRUs</th>
<th>Suspect Board FRUs</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 – 4</td>
<td>FW</td>
<td>MMU</td>
</tr>
<tr>
<td>5 – 7</td>
<td></td>
<td>MMU</td>
</tr>
</tbody>
</table>

The name of the first Display kernel test that fails is displayed on the screen. The Display processor error index code is read from the A15 MMU board test points DIAG0 (LSB) to DIAG2 (MSB). The bits are high (+5 V) true.

The status LEDs (DS201 and DS200) on the A15 MMU board will flash while the Kernel diagnostic tests are executing. If a kernel failure is detected, then one or both LEDs will remain on. Table 6-14 lists the various LED configurations and their significance. See Figure 6-34 for the location of these test points and status LEDs.

Table 6-14: Display Processor Status LED Configuration

<table>
<thead>
<tr>
<th>DS200</th>
<th>DS201</th>
<th>Significance</th>
</tr>
</thead>
<tbody>
<tr>
<td>ON</td>
<td>ON</td>
<td>Power-On</td>
</tr>
<tr>
<td>ON</td>
<td>OFF</td>
<td>Kernel Tests Executing</td>
</tr>
<tr>
<td>OFF</td>
<td>ON</td>
<td>Kernel Tests Failed</td>
</tr>
<tr>
<td>OFF</td>
<td>OFF</td>
<td>Kernel Tests Finished</td>
</tr>
</tbody>
</table>
Figure 6-34: A15 MMU Board Test Point and Status LED Locations

**Time Base Processor Error Index Codes**

Error index codes for the Time Base processor are listed in Table 6-15.

<table>
<thead>
<tr>
<th>Error Index(_{\text{hex}})</th>
<th>Suspect Hybrid/IC FRUs</th>
<th>Suspect Board FRUs</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>TBC</td>
<td></td>
</tr>
<tr>
<td>2 – 3</td>
<td>FW</td>
<td>TBC</td>
</tr>
<tr>
<td>4 – 7</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>8 – A</td>
<td></td>
<td>TBC, MMU</td>
</tr>
<tr>
<td>B</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>C</td>
<td></td>
<td>TBC, MMU</td>
</tr>
</tbody>
</table>

The error index code bits of the first Time Base kernel test that fails are read from the A5 Time Base/Controller board status LEDs ST4 (MSB), ST3, ST2 and ST1 (LSB). The bits are true (one) when the LED is on. Also, status LEDs ST5 and ST6 indicate when the test is executing and when the test has failed, respectively. See Figure 6-35 for the location of these status LEDs.

The patterns from the status LEDs are applicable only when the Time Base is executing or stopped in Kernel diagnostics.
Figure 6-35: A5 Time Base/Controller Board Status LEDs
Acquisition Processor Error Index Codes

Error index codes for the Acquisition processor are listed in Table 6-16.

**Table 6-16: Acquisition Processor Kernel Error Index Codes**

<table>
<thead>
<tr>
<th>Error Index₇hex</th>
<th>Suspect Hybrid/IC FRUs</th>
<th>Suspect Board FRUs</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>FW</td>
<td>ACQMPU</td>
</tr>
<tr>
<td>2</td>
<td></td>
<td>ACQMPU</td>
</tr>
<tr>
<td>3</td>
<td></td>
<td>ACQMPU, TBC, STROBEDR, MFACQCON</td>
</tr>
</tbody>
</table>

The error index code bits of the first Acquisition kernel test that fails are read from the A28 Acquisition MPU board status LEDs, DS101 (MSB) and DS100 (LSB). See Figure 6-36 for the location of these status LEDs.

The patterns from the status LEDs are applicable only when the Acquisition is executing or stopped in Kernel diagnostics.

![Figure 6-36: A28 Acquisition MPU Board Status LEDs](image)
Other Troubleshooting

This section provides additional information and procedures for troubleshooting a faulty CSA 803A to the FRU level.

---

**Power Supply Module**

This procedure requires an Extended Diagnostics power supplies troubleshooting fixture. Refer to Table 4-2 for a complete description of the equipment required.

**Module Troubleshooting**

If any Power Supply module problems are present, they appear when the ON/STANDBY switch is set to ON. If the green light beside the ON label fails to light, then check for the following conditions:

- The PRINCIPAL POWER SWITCH located on the back panel is in the ON position.
- The line cord is connected to a functional power source with the same output voltage set as the LINE VOLTAGE SELECTOR on the back panel.
- The fuse is good. If the fuse is blown, then replace the fuse.
- The fan is exhausting air from the instrument when the ON/STANDBY switch is ON. A defective fan causes an over-temperature shutdown in the power supply.

If these checks fail to correct the problem, connect the Extended Diagnostics 11000-Series Power Supplies Test Fixture to the Power Supply module (refer to the documentation accompanying the test fixture for troubleshooting techniques). The test fixture indicates which power supply voltage source is at fault. To help isolate the source of the problem, set the instruments ON/STANDBY switch to STANDBY, and disconnect the suspected faulty power supply voltage source from the Power Supply module. Set the ON/STANDBY switch to ON. If the test fixture does not record a fault, then you have verified the suspected faulty power source. This procedure is only effective for externally shorted power supplies. Once again, refer to the documentation accompanying the test fixture for more troubleshooting information.

---

**A4 Regulator Board**

This board is implicitly verified; that is, if all the other FRUs pass diagnostic testing, then you can assume that the A4 Regulator board is operating correctly as well.
Other Troubleshooting

CRT, A7 CRT Socket Board, or A8 CRT Driver Board

This procedure requires a test terminal and a compatible RS-232-C serial interface cable. Refer to Table 4-2 for a complete description of the equipment required.

Module Troubleshooting

If the CSA 803A powers-on (the ON/STANDBY light is on), but the display gives scrambled information or none at all, then the CRT and A8 CRT Driver board are suspect. The following two procedures help you determine whether the A15 MMU board or one of the CRT units, (either the CRT, the A7 CRT Socket board or the A8 CRT Driver board) is at fault.

- With the power off (ON/STANDBY switch to STANDBY), remove the top cover, then turn the power on. Observe the two LEDs on the A15 MMU board and those on the A17 Executive Processor board in the card cage. These LEDs should flicker on and off until the diagnostic tests are complete and then all turn off. If any of these LEDs remain lit, it indicates a problem with the board on which the LED resides. If all LEDs turn off, then the CRT, A7 CRT Socket board, or the A8 CRT Driver board is suspect.

- With the power off, connect a test terminal (ANSI 3.64-compatible) to the CSA 803A using an RS-232-C cable. Touch the screen through the full power-on cycle to force a diagnostic error so the instrument enters Extended Diagnostics. On the test terminal, type T to display the EXTENDED DIAGNOSTICS menu on the terminal display. If the displayed errors are only for the front panel touch screen, then the CRT, the A7 CRT Socket board, or the A8 CRT Driver board is at fault. Note any other errors and use Table 6-5, earlier in this section, to identify the suspect subsystem.

A13 Mother Board

This board is implicitly verified; that is, if all the other FRUs pass diagnostic testing, then you can assume that the A13 Mother board is operating correctly as well.
Fuse Testing

The A14 I/O board has four fuses (see Figure 6-37). F200 supplies +5 V to the A12 Rear Panel board. F800 supplies +5 V to the A10 Front Panel Control board and the A9 Touch Panel board. F600 supplies +15 V to the A14 I/O board, card cage, A10 Front Panel Control board, A9 Touch Panel board, A11 Front Panel Button board, and A12 Rear Panel board (reduced to +12 V). F602 supplies −15 V to the A14 I/O board, card cage, A10 Front Panel Control board (reduced to −5 V), and A12 Rear Panel board (reduced to −12 V).

- F200 supplies +5 V to the A12 Rear Panel board. If diagnostics report failure of all three ports (RS-232-C, GPIB, and PRINTER), then this fuse is the probable suspect (assuming that the ribbon cable to the A12 Rear Panel board is connected). When tested with a multimeter, this fuse should measure less than 1.5 V.

- F800 supplies +5 V to the A10 Front Panel Control board and the A11 Front Panel board. If the diagnostics report both an A9 Touch Panel board failure and knob failures, then this fuse is one possible source of this problem. When tested with a multimeter, this fuse should measure less than 1 Ω.

- F600 supplies +15 V to the A14 I/O board temperature sensor and tone generator, the lights of the A11 Front Panel Button board, the A9 Touch Panel board, the A12 Rear Panel board’s RS-232-C output line drivers, the card cage, and the A17 Executive Processor board’s NVRAM. If the NVRAM battery test and the RS-232-C External Loop Back test fail (but the Internal Loop Back test passes), and the A11 Front Panel Button board’s lights, temperature sensor, and tone generator are all off, then this fuse is the probable suspect. When tested with an multimeter, this fuse should measure less than 1 Ω.

- F602 supplies −15 V to the A14 I/O board temperature sensor and tone generator, A12 Rear Panel board’s RS-232-C output line drivers, the A9 Touch Panel board, and the card cage. If the temperature sensor, tone generator, and RS-232-C External Loop Back test fail (but the Internal Loop Back test passes), then this fuse is the probable suspect. When tested with an multimeter, this fuse should measure less than 1 Ω.

The A14 I/O board uses the +15 V and −15 V supplies on board to operate the temperature sensor and the tone generator. Of the other card cage boards, the A18 Memory board uses the +15 V supply to operate the NVRAM circuitry. The information above and Table 6-17 will help you to identify a failure of one of these fuses. If a test fails, then check the fuses.

**WARNING**

Using a replacement fuse with an incorrect current rating may cause the ribbon cables to melt and create fire danger during a component fault.
Other Troubleshooting

See Figures 6-2 and 6-37 for the location of the line fuse and the A14 I/O board fuses, respectively.

When a fuse must be replaced, unsolder the fuse from the board. Be careful not to damage the solder pads on the board. (It may be helpful to straighten the fuse leads on the rear of the board before removing the leads from their holes in the circuit board.) Refer to the Parts List section for the correct value and part number of each fuse.

Table 6-17: A14 I/O Board Fuse Failures

<table>
<thead>
<tr>
<th>Fuse</th>
<th>Executive Kernel Test Failure (refer to Table 6-10, Executive Subsystem Error Index Codes)</th>
<th>Self-Test/Extended Test Failure</th>
</tr>
</thead>
<tbody>
<tr>
<td>F200 open</td>
<td>10hex (GPIO Interrupt)</td>
<td>E1411 3</td>
</tr>
<tr>
<td>F800 open</td>
<td>13hex (Front Panel Inter) <strong>NOTE:</strong> The front panel lights do not work so the code must be read from the error status test points (TP200-TP205) on the A17 Executive Processor board.</td>
<td>Exec Control NVRAM Battery *Data Lines *Addr/Data Internal I/O Temp Sensor Comparator E3111 1 *Tone Gen *Ramp Tone (works)</td>
</tr>
<tr>
<td>F600 open</td>
<td>Passes the Kernel diagnostic tests, but the front panel lights are not lit.</td>
<td>E1411 3 E1411 1 E1421 1 E1431 1 E3111 1</td>
</tr>
<tr>
<td>F602 open</td>
<td>13hex (Front Panel Inter) <strong>NOTE:</strong> The tone generator has a very different tone.</td>
<td></td>
</tr>
</tbody>
</table>

*Indicates a Manual Test forced by the operator. The test is not automatically executed by Self-Test diagnostics.
Figure 6-37: A14 I/O Board Fuse Locator Diagram
Time Base Calibration Errors

Table 6-18 lists the time base calibration errors that can appear on the CSA 803A screen and the suspected faulty FRUs that cause the error. The FRUs are listed in the order of most to least likely source of the error.

Time base calibration errors whose error codes are greater than 100 have two different forms, depending on when the error occurs. If the error occurs during power-on then the message will say:

**Time base calibration failed at power up: 2XX**

where 2XX is the error code.

If the error occurs at any other time, then the message will say:

**Time base calibration failed: 1XX**

where 1XX is the error code.

Calibration data to enhance the time interpolator linearity is stored in NVRAM on the Time Base/Controller board. If this NVRAM fails, a T1331 error occurs during power-on diagnostics. The values are written at the factory with the GPIB command **CALC**CORRECTION.

**CALC**CORRECTION<ui>: N

where <ui> = 0..32 and N = −128..+127

---

**CAUTION**

The calibration enhancement values are set at time of manufacture. There is no query form of this command. Do NOT reset these values. If a T1331 failure occurs during extended power-on diagnostics or you suspect a time interpolator error, contact Tektronix factory service.

A T1331 failure causes all N values in the 33 ui locations to be reset to zero. The oscilloscope will still run, but with decreased accuracy in the time interpolator linearity. Resetting NVRAM with the Teksecure feature does not affect the Time Base/Controller board NVRAM.
### Table 6-18: Time Base Calibration Errors

<table>
<thead>
<tr>
<th>Error Message</th>
<th>Error Code</th>
<th>Suspect FRU</th>
</tr>
</thead>
<tbody>
<tr>
<td>Minor time base calibration problem:</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>12</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>14</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>16</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>18</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>24</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>33</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>Time base calibration failed (at power-on):</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>101 (201)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>102 (202)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>103 (203)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>111 (211)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>113 (213)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>115 (215)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>117 (217)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>121 (221)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>122 (222)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>123 (223)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>125 (225)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>126 (226)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>131 (231)</td>
<td></td>
<td>STROBEBUF, STROBEDR</td>
</tr>
<tr>
<td>132 (232)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>134 (234)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>135 (235)</td>
<td></td>
<td>STROBEBUF, STROBEDR</td>
</tr>
<tr>
<td>136 (236)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>137 (237)</td>
<td></td>
<td>TBC</td>
</tr>
<tr>
<td>138 (238)</td>
<td></td>
<td>STROBEBUF, STROBEDR, or Sampling Head</td>
</tr>
</tbody>
</table>

All errors are generated by C0049, which is the main control chip.
Acquisition Calibration Errors

When acquisition calibration errors occur, a message will appear on the CSA 803A screen followed by a number that indicates in which Acquisition system the error was detected. Following this number, there will be a string of eight, four-digit error codes that are used to identify possible faulty FRUs. The following example shows the form that the error message will appear:

**Error detected in acquisition system AA: BBBB, CCCC, DDDD, EEEE, FFFF, GGGG, HHHH, IIII**

where the A digits represent the number of the Acquisition system, and the B, C, D, E, F, G, H, and I digits represent the four-digit error codes.

The B and I digits can be ignored. If any of the C or D digits are non-zero, then the possible faulty FRUs, from most to least likely, are:

```
ACQMPU
MFACQCON
ACQANALOG
TBC
```

If any of the E, F, G, or H digits are non-zero, then the possible fault FRUs, from most to least likely, are:

```
ACQANALOG
ACQMPU
MFACQCON
```
Options

This section contains information on instrument and power cord options available for your CSA 803A.

Instrument Options

Your instrument may be equipped with one or more options. A brief description of each available option is given in the following discussion. Option information is incorporated into the appropriate sections of the manual set. Refer to the Table of Contents for the location of option information. For further information and prices of instrument options, see your Tektronix Products Catalog or contact your local Tektronix service center.

Option 1R — adds slide rails and rackmounting hardware to convert the benchtop instrument to a standard 19-inch rackmount version. This option can be added at any time.

Option 1T — adds the Predefined Telecommunications Mask firmware. This feature is standard after serial number B020000, though it still appears as Option 1T in the Identify (System Identification) pop-up menu.

Option 10 — deletes the Prescaler. The Prescaler circuitry extends the trigger bandwidth to 10 GHz. The Prescaler may be added at any time with an option kit.

Option A1 — replaces the standard power cord with the Universal European 220 V type power cord.

Option A2 — replaces the standard power cord with the United Kingdom 240 V type power cord.

Option A3 — replaces the standard power cord with the Australian 240 V type power cord.

Option A4 — replaces the standard power cord with the North American 250 V type power cord.

Option A5 — replaces the standard power cord with the Switzerland 240 V type power cord.
Power Cord Information

A power cord with appropriate plug configuration is supplied with each instrument. Table 7-1, Power-Cord Conductor Identification, gives the color-coding of the conductors in the power cord. If you require a power cord other than the one supplied, refer to Figure 7-1, Power-Cord Plug Identification.

<table>
<thead>
<tr>
<th>Conductor</th>
<th>Color</th>
<th>Alternate Color</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ungrounded (Line)</td>
<td>Brown</td>
<td>Black</td>
</tr>
<tr>
<td>Grounded (Neutral)</td>
<td>Light Blue</td>
<td>White</td>
</tr>
<tr>
<td>Grounded (Earth)</td>
<td>Green/Yellow</td>
<td>Green</td>
</tr>
</tbody>
</table>

*Canadian Standards Association certification includes these power plugs for use in the North American power network*

Figure 7-1: Power-Cord Plug Identification
Electrical Parts

The modules that make up this instrument are often a combination of mechanical and electrical subparts. Therefore, all replaceable modules are listed in the Parts List section. Refer to that section for part numbers when using this manual.
Block Diagrams

This section contains the system block diagram, interconnection diagram, and the board level block diagrams. Detailed discussion of these diagrams is located in the *Theory of Operation* section.
Figure 9-3: A1 M/F Strobe Drive Board Block Diagram
Figure 9-4: A4 Regulator Board Block Diagram
Figure 9-5: A5 Time Base/Controller Board Block Diagram

Figure 9-6: A7 CRT Socket Board Block Diagram
Figure 9-7: A8 CRT Driver Board Block Diagram
Figure 9-8: A12 Rear Panel Assembly Block Diagram
Figure 9-9: A14 I/O Board Block Diagram

Figure 9-10: A15 MMU Board Block Diagram
Figure 9-11: A17 Executive Processor Board Block Diagram
Figure 9-12: A18 Memory Board Block Diagram
Figure 9-13: A19 Strobe/TDR Buffer Board Block Diagram

Figure 9-14: A26 M/F Acquisition Interconnect Board Block Diagram
Block Diagrams

Figure 9-15: A27 Acquisition Analog Board Block Diagram

Figure 9-16: A28 Acquisition MPU Board Block Diagram
Replaceable Parts

This section contains a list of the replaceable components for the CSA 803A. As described below, use this list to identify and order replacement parts.

Parts Ordering Information

Replacement parts are available from or through your local Tektronix, Inc. service center or representative.

Changes to Tektronix instruments are sometimes made to accommodate improved components as they become available and to give you the benefit of the latest circuit improvements. Therefore, when ordering parts, it is important to include the following information in your order:

- part number
- instrument type or model number
- instrument serial number
- instrument modification number, if applicable

If a part you order has been replaced with a different or improved part, your local Tektronix service center or representative will contact you concerning any change in the part number.

Change information, if any, is located at the back of this manual.

Module Replacement

The CSA 803A is serviced by module replacement, so there are three options you should consider:

- **Module Exchange.** In some cases you may exchange your module for a remanufactured module. These modules cost significantly less than new modules and meet the same factory specifications. For more information about the module exchange program, call 1–800–TEKWIDE, ext. BV 5799.

- **Module Repair.** You may ship your module to us for repair, after which we will return it to you.

- **New Modules.** You may purchase new replacement modules in the same way as other replacement parts.
Using the Replaceable Parts List

The tabular information in the Replaceable Parts List is arranged for quick retrieval. Understanding the structure and features of the list will help you find the all the information you need for ordering replacement parts.

Item Names

In the Replaceable Parts List, an Item Name is separated from the description by a colon (:). Because of space limitations, an Item Name may sometimes appear as incomplete. For further Item Name identification, U.S. Federal Cataloging Handbook H6-1 can be used where possible.

Indentation System

This parts list is indented to show the relationship between items. The following example is of the indentation system used in the Description column:

```
1 2 3 4 5       Name & Description
Assembly and/or Component
Attaching parts for Assembly and/or Component
(END ATTACHING PARTS)
Detail Part of Assembly and/or Component
Attaching parts for Detail Part
(END ATTACHING PARTS)
Parts of Detail Part
Attaching parts for Parts of Detail Part
(END ATTACHING PARTS)
```

Attaching parts always appear at the same indentation as the item they mount, while the detail parts are indented to the right. Indented items are part of, and included with, the next higher indentation. Attaching parts must be purchased separately, unless otherwise specified.

Abbreviations

Abbreviations conform to American National Standards Institute (ANSI) standard Y1.1
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<th>Description</th>
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## Replaceable Parts

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Figure 10-1: Cabinet
### Replaceable Parts

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**10-8 Mechanical Parts List**
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**Figure 10-2: Front Panel**
### Replaceable Parts

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10-10 Mechanical Parts List
## Replaceable Parts

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Figure 10-4: Circuit Boards
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(SEE MAINT SECTION FOR CABLE DIAGRAM)
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Replaceable Parts

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Figure 10-5: Acquisition Module
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**WIRE ASSEMBLIES**
(SEE MAINT SECTION FOR CABLE DIAGRAM)
### POWER SUPPLY

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<td>FUSE, WIRE LEAD:3A,125V,FASST (F740, PART OF CONTROL RECTIFIER BOARD)</td>
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<td>031 1673</td>
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**Figure 10-6: Power Supply**
### Replaceable Parts

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**STANDARD ACCESSORIES**

**OPTIONAL ACCESSORIES**

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Figure 10-7: Accessories
Replaceable Parts